# Theory Assignment 1 (Practice Version)

COMP 451 - Fundamentals of Machine Learning

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## Question 1 [6 points]

Recall that the k-NN model is defined by the prediction function

$$f_{k-NN}(\mathbf{x}) = \mathsf{MAJ}\left(\{y_i : (\mathbf{x}_i, y_i) \in \mathcal{D}_{\mathrm{trn}} \land \exists_{\langle k}(y_j, \mathbf{x}_j) \in \mathcal{D}_{\mathrm{trn}} : d(\mathbf{x}, \mathbf{x}_i) > d(\mathbf{x}, \mathbf{x}_j)\}\right),\tag{1}$$

where MAJ is the majority vote function. Assume that we are using the Euclidean distance function, considering a binary 0-1 classification task with two-dimensional features, and that we are evaluating accuracy using the 0-1 loss:

$$L(y, \hat{y}) = \begin{cases} 0 & \text{if } y = \hat{y} \\ 1 & \text{otherwise.} \end{cases}$$
(2)

Lastly, assume that ties in the majority vote function are broken randomly with a 50/50 probability (i.e., if we have equal positive and negative classes in the nearest neighbor set, then we flip a coin to make the prediction), and assume that we are evaluating the expected accuracy in light of this randomness.

**Prove or provide a counter-example to the following claim:** if we assume that our dataset is linearly separable with geometric margin  $\gamma$ , then the expected training error of a k-NN monotonically increases as a function of k for  $k \ge 1$ .

*Hint:* Remember that the nearest neighbor of a training point is always itself!

**Solution.** The claim is false. For example, suppose we have the following training dataset:

point 1:	$\left([0,1],1 ight)$
point 2:	([0, 2.1], 1)
point 3:	([0, 2.1], 1)
point 4:	$\left( [0,0],0 ight)$
point 5:	([0, -0.2], 0)
point 6:	([0, -0.2], 0)

Now, for k = 2 we will have that point 1 is misclassified with 50% probability, since its two nearest neighbors are itself and point 4. All other points will be correctly classified: points 2/3 and points 5/6 are identical and from the same class, guaranteeing correct classification; point 4 is correctly classified because its nearest neighbors are points 5/6. Moving up to k = 3, point 1 is now correctly classified, since points 2/3 are included in its set of nearest neighbors. All the other points remain correctly classified, since the points added to their nearest neighbor set are from the same class.

# Question 2 [6 points]

For this question, you should refer to the details and notation for the perceptron algorithm (i.e., Algorithm 1) in Chapter 3 of the notes. Provide a proof for the following lemma, which we used to prove the perceptron convergence theorem:

**Lemma 1.** Assume that there exists some  $\gamma > 0$  and some set of optimal parameters  $\mathbf{w}^*$  such that  $y_i(\mathbf{w}^*)^\top \mathbf{x}_i \geq \gamma$  for all  $(\mathbf{x}_i, y_i) \in \mathcal{D}_{trn}$ . The norm of the weight vector  $\|\mathbf{w}^{(k)}\|$  increases at most linearly with each update in Algorithm 1. In particular, if assume that  $\|\mathbf{x}_i\| < R, \forall i \in \mathcal{D}_{trn}$ , then  $\|\mathbf{w}^{(k)}\|^2 \leq R^2 k$ , where k denotes the number of updates in Algorithm 1.

**Solution.** By the definition of the perceptron update on a point  $(\mathbf{x}, y)$  we have that

$$\|\mathbf{w}^{(k)}\|^2 = (\mathbf{w}^{(k)})^\top \mathbf{w}^{(k)}$$
(3)

$$= \left(\mathbf{w}^{(k-1)} + y\mathbf{x}\right)^{\top} \left(\mathbf{w}^{(k-1)} + y\mathbf{x}\right)$$
(4)

$$= (\mathbf{w}^{(k-1)})^{\top} \mathbf{w}^{(k-1)} + 2y \mathbf{x}^{\top} \mathbf{w}^{(k-1)} + y^2 \mathbf{x}^{\top} \mathbf{x}$$
(5)

$$\leq (\mathbf{w}^{(k-1)})^{\mathsf{T}} \mathbf{w}^{(k-1)} + \mathbf{x}^{\mathsf{T}} \mathbf{x}$$
(6)

$$\leq \|\mathbf{w}^{(k-1)}\|^2 + R^2 \tag{7}$$

Note that we only make updates when we make mistakes, so we can safely assume that  $2y\mathbf{x}^{\top}\mathbf{w}^{(k-1)} < 0$ , since y and  $\mathbf{x}^{\top}\mathbf{w}^{(k-1)}$  must have opposite signs. The proof is completed by simple induction on k. The inductive step is given by Equation 7 and the base case for k = 0 is given by  $\|\mathbf{w}^{(0)}\|^2 = \|\mathbf{0}\|^2 = 0 = 0R^2$ .

### Question 3 [6 points]

In class, we were introduced to Bernoulli Naive Bayes and the Gaussian Naive Bayes models. In this question, you will derive that maximum likelihood parameters for a Poisson Naive Bayes model. In a Poisson Naive Bayes model, the feature likelihoods are defined following distribution:

$$p(\mathbf{x}[j] \mid y = k) = \frac{\theta_{j,k}^{\mathbf{x}[j]} e^{-\theta_{j,k}}}{\mathbf{x}[j]!}.$$
(8)

As in the Bernoulli Naive Bayes model, the  $\theta_{j,k}$  parameter determines the likelihood for the *j*th feature, assuming the point belongs to class k.

#### Part 1 [2 points]

Assume we are in a binary classification setting. Write an expression for the log-odds ratio of the Poisson Naive Bayes model. Use the notation from Equation 8 above and use  $\theta_k = P(y = k)$  to denote the estimated class likelihoods.

#### Part 2 [4 points]

Derive the maximum likelihood estimates for the Poisson Naive Bayes parameters, i.e., give maximum likelihood estimates for the  $\theta_{j,k}$  parameters.

#### Solution.

#### Part 1

The log-odds ratio is given by

$$\frac{\log(p(y=1 \mid \mathbf{x}))}{\log(p(y=0 \mid \mathbf{x}))} = \log(\theta_1) - \log(\theta_0) + \sum_{j=1}^m \mathbf{x}[j] \left(\log(\theta_{j,1}) - \log(\theta_{j,0})\right) - \theta_{j,1} + \theta_{j,0}$$

#### Part 2

To derive the maximum likelihood estimates for the  $\theta_{j,k}$  parameters, we only need to consider the parts of the log-likelihood that depend on the  $\theta_{j,k}$  term. All other terms will be zero. Moreover, without loss of generality we assume that k = 1. Given these simplifications we have that

$$\frac{\partial}{\partial \theta_{j,1}} \log \mathcal{L}(\mathcal{D}; \Theta) = \frac{\partial}{\partial \theta_{j,1}} \sum_{(\mathbf{x}, y) \in \mathcal{D}} y(\mathbf{x}[j] \log(\theta_{j,1}) - \theta_{j,1})$$
$$= \sum_{(\mathbf{x}, y) \in \mathcal{D}} y\left(\frac{\mathbf{x}[j]}{\theta_{j,1}} - 1\right),$$

and setting this to zero and solving we get

$$\sum_{(\mathbf{x},y)\in\mathcal{D}} y\left(\frac{\mathbf{x}[j]}{\theta_{j,1}} - 1\right) = 0$$
$$\sum_{(\mathbf{x},y)\in\mathcal{D}} y\left(\frac{\mathbf{x}[j]}{\theta_{j,1}}\right) = \sum_{(\mathbf{x},y)\in\mathcal{D}} y$$
$$\theta_{j,1} = \frac{\sum_{(\mathbf{x},y)\in\mathcal{D}} y\mathbf{x}}{\sum_{(\mathbf{x},y)\in\mathcal{D}} y}$$

And in general we get that

$$\theta_{j,k} = \frac{\sum_{(\mathbf{x},y)\in\mathcal{D}:y=k} \mathbf{x}[j]}{|(\mathbf{x},y)\in\mathcal{D}:y=k|}.$$
(9)

In other words, we just take the average value of the feature for points belonging to class k.

# Question 4 [short answers; 2 points each]

Answer each question with 1-3 sentences for justification, potentially with equations/examples for support.

a) True or false: Bernoulli Naive Bayes always correctly classifies all training points if the dataset is linearly separable.

**b)** Consider the following dataset:

point 1:	([0, 1], 1)
point 2:	([1, 0], 1)
point 3:	([0,0],-1)
point 4:	([1,1],-1)

Is the perceptron algorithm guaranteed to converge on this dataset?

c) Consider the following dataset:

point 1:	([0.5, 1], 1)
point 2:	([0.2, 0.5], 1)
point 3:	([0.9, 0.9], 0)
point 4:	([1.5, 1.5], 0)

What class will a Gaussian Naive Bayes model predict for point [1.1, 1.1]?

#### Solution.

a) This is false. If there are many more points from one class then the class priors can lead to a misclassification even if the data is separable. For example, suppose we have a dataset consisting of 5 identical points ([1,0],1), 5 identical points ([0,1],1), and one point ([1,1],0). This dataset is linearly separable, but the model will predict class 1 for the training point ([1,1],0), since  $0.5 \times 0.5 \times \frac{10}{11} > 1 \times 1 \times \frac{1}{11}$ .

**b**) The data is not linearly separable. (It is the exclusive-or function). Thus, the perceptron is not guaranteed to converge.

c) The GNB model will predict class 0, since the input point is closer to the mean of the points from class 0.