

Applied Machine Learning

Bootstrap, Bagging and Boosting

Siamak Ravanbakhsh

Learning objectives

bootstrap for uncertainty estimation

bagging for variance reduction

- random forests

boosting

- AdaBoost
- gradient boosting
- relationship to L1 regularization

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- for predictions

Bootstrap

a simple approach to estimate the uncertainty in prediction

non-parametric bootstrap

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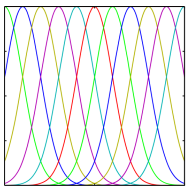
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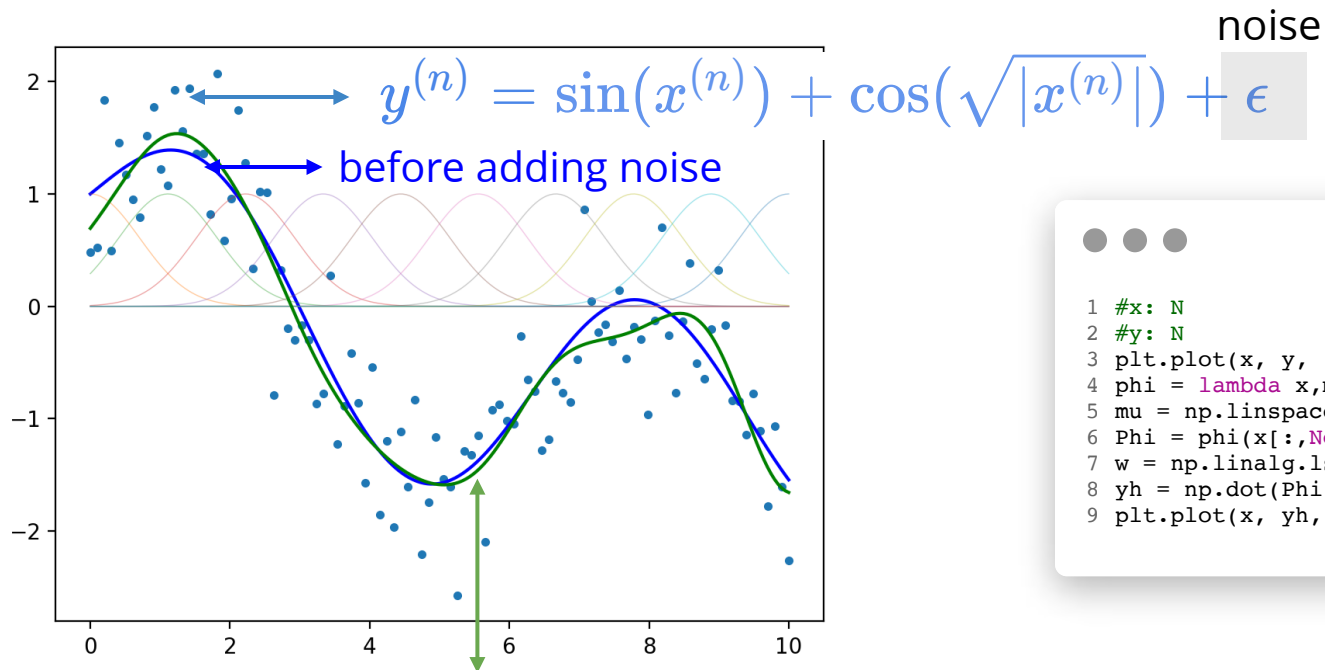
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Bootstrap: example

Recall: linear model with nonlinear Gaussian bases (N=100)



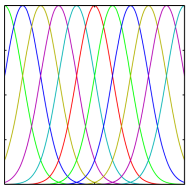
noise

```

1 #x: N
2 #y: N
3 plt.plot(x, y, 'b.')
4 phi = lambda x, mu: np.exp(-(x-mu)**2)
5 mu = np.linspace(0,10,10) #10 Gaussians bases
6 Phi = phi(x[:,None], mu[None,:]) #N x 10
7 w = np.linalg.lstsq(Phi, y)[0]
8 yh = np.dot(Phi,w)
9 plt.plot(x, yh, 'g-')

```

our fit to data using 10 Gaussian bases



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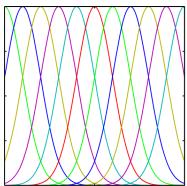
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Recall: linear model with nonlinear Gaussian bases (N=100)

using B=500 bootstrap samples

gives a measure of uncertainty of the parameters

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2 #y: N
3 B = 500
4 ws = np.zeros((B,D))
5 for b in range(B):
6     inds = np.random.randint(N, size=(N))
7     Phi_b = Phi[inds,:] #N x D
8     y_b = y[inds] #N
9     #fit the subsampled data
10    ws[b,:] = np.linalg.lstsq(Phi_b, y_b[:,b])[0]
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12 plt.hist(ws, bins=50)
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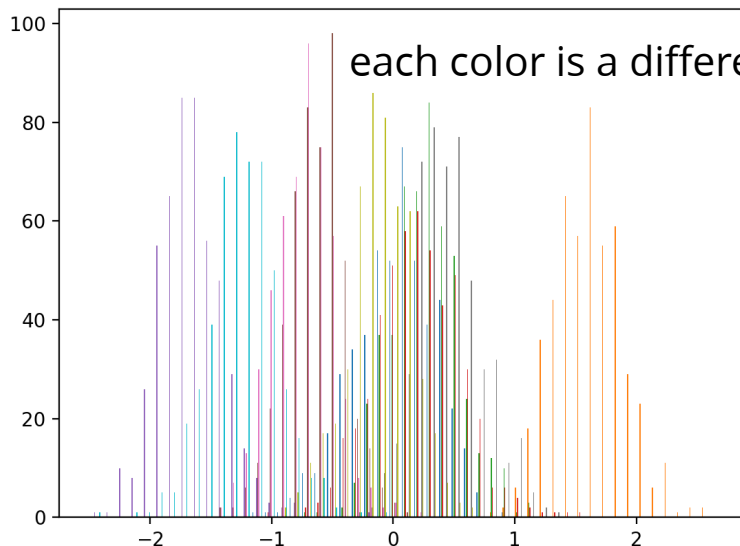
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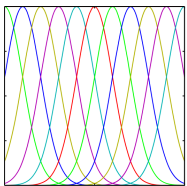
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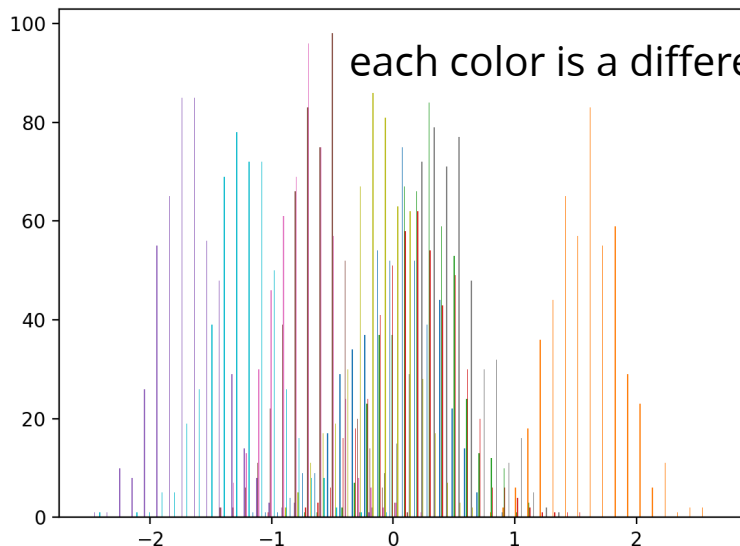
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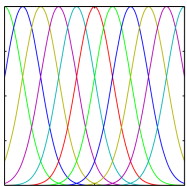
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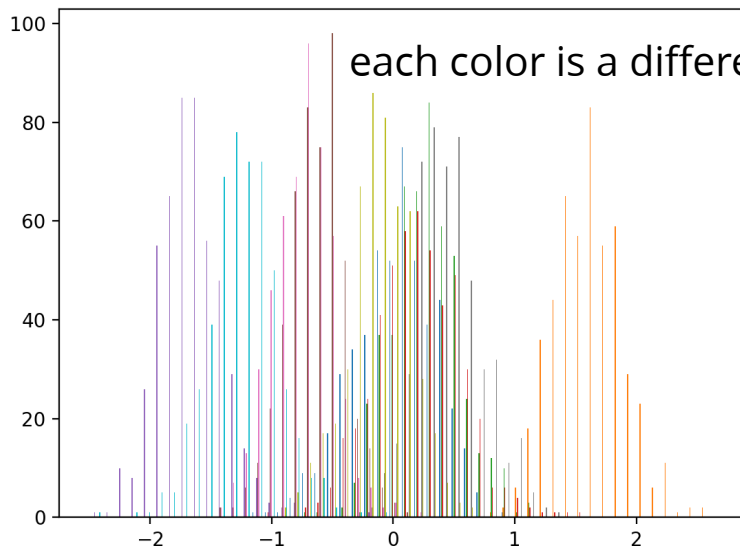
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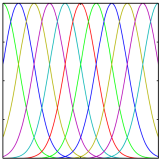
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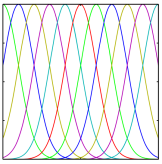
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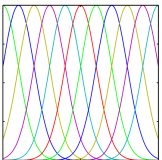
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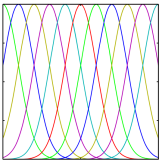


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2 #Phi_test: Nt x D
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4 #ws: B x D from previous code
5 y_hats = np.zeros((B, Nt))
6 for b in range(B):
7     wb = ws[b,:]
8     y_hats[b,:] = np.dot(Phi_test, wb)
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10 # get 95% quantiles
11 y_5 = np.quantile(y_hats, .05, axis=0)
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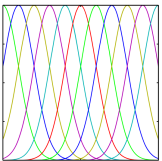
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the **red lines** are 5% and 95% quantiles
(for each point we can get these across bootstrap model predictions)

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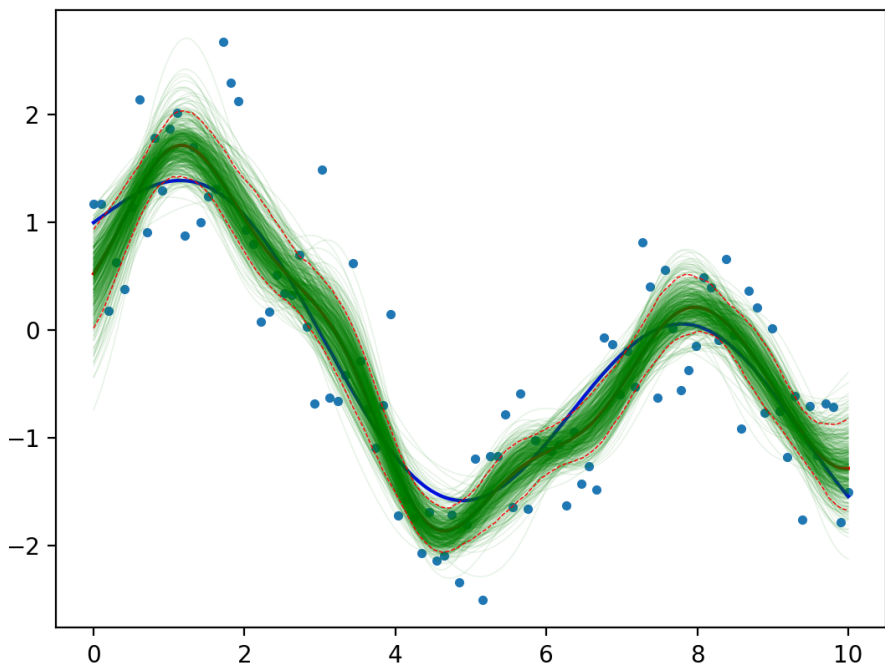




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Bagging

use bootstrap for **more accurate prediction** (not just uncertainty)

variance of sum of random variables

$$\text{Var}(z_1 + z_2) = \mathbb{E}[(z_1 + z_2)^2] - \mathbb{E}[z_1 + z_2]^2$$

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issue: model predictions are not uncorrelated (trained using the same data)

bagging (bootstrap aggregation) use **bootstrap samples** to reduce correlation

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averaging makes sense for regression, how about classification?

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Bagging decision trees

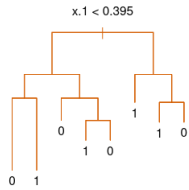
setup

- *synthetic dataset*
- *5 correlated features*
- *1st feature is a noisy predictor of the label*

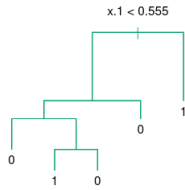
example

Bagging decision trees

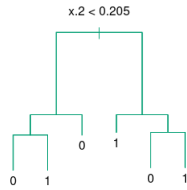
Original Tree



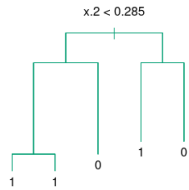
$b = 1$



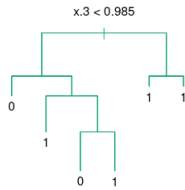
$b = 2$



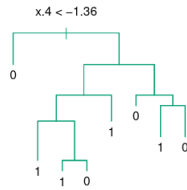
$b = 3$



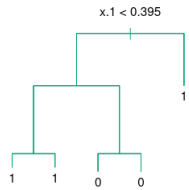
$b = 4$



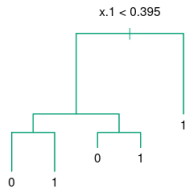
$b = 5$



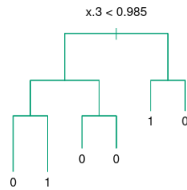
$b = 6$



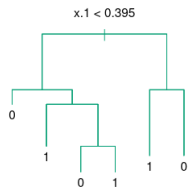
$b = 7$



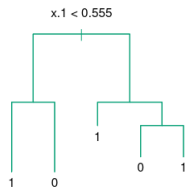
$b = 8$



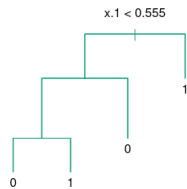
$b = 9$



$b = 10$



$b = 11$



setup

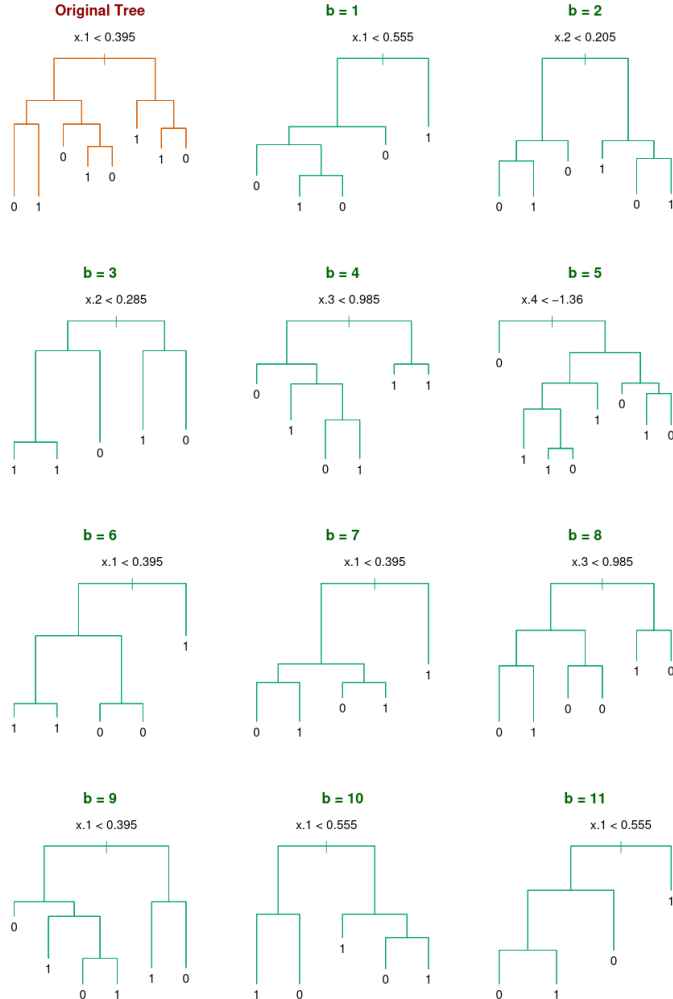
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Bootstrap samples create different decision trees (due to high variance)

compared to decision trees, no longer **interpretable!**

example

Bagging decision trees

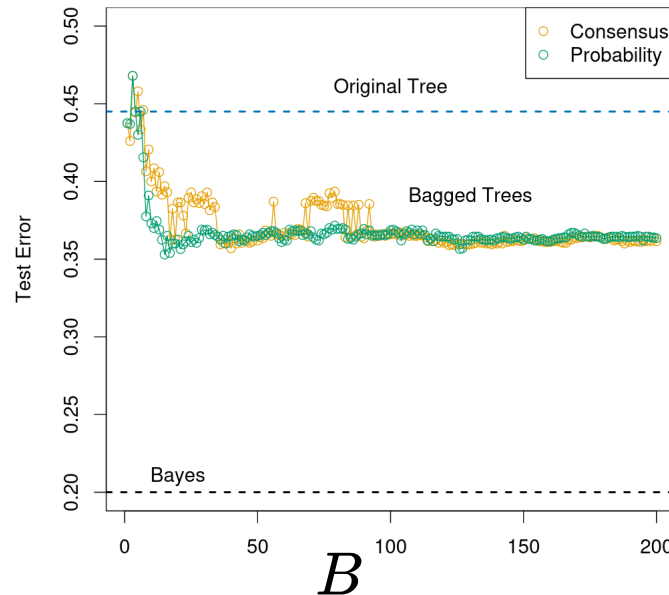


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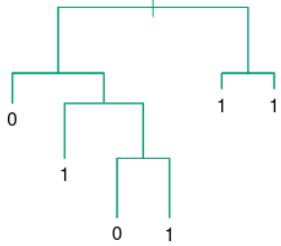
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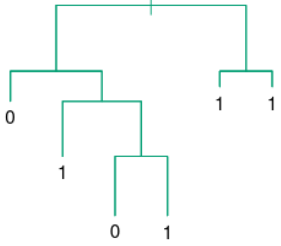
— voting for the most probably class
— averaging probabilities

Random forests



further reduce the correlation between decision trees

Random forests



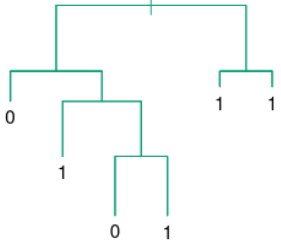
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feature sub-sampling

only a random subset of features are available for split at each step

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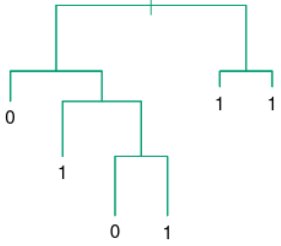
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further reduce the dependence between decision trees

magic number? \sqrt{D}

this is a hyper-parameter, can be optimized using CV

Random forests



further reduce the correlation between decision trees

feature sub-sampling

only a **random subset** of features are available for split at each step

further reduce the dependence between decision trees

magic number? \sqrt{D}

this is a hyper-parameter, can be optimized using CV

Out Of Bag (OOB) samples:

- the instances not included in a bootstrap dataset can be used for validation
- simultaneous validation of decision trees in a forest
- no need to set aside data for **cross validation**

Example: spam detection

Dataset

N=4601 emails

binary classification task: *spam - not spam*

D=57 features:

- **48** words: percentage of words in the email that match these words
 - e.g., *business,address,internet, free, George* (customized per user)
- **6** characters: again percentage of characters that match these
 - *ch; , ch(,ch[,ch! ,ch\$, ch#*
- average, max, sum of length of uninterrupted sequences of capital letters:
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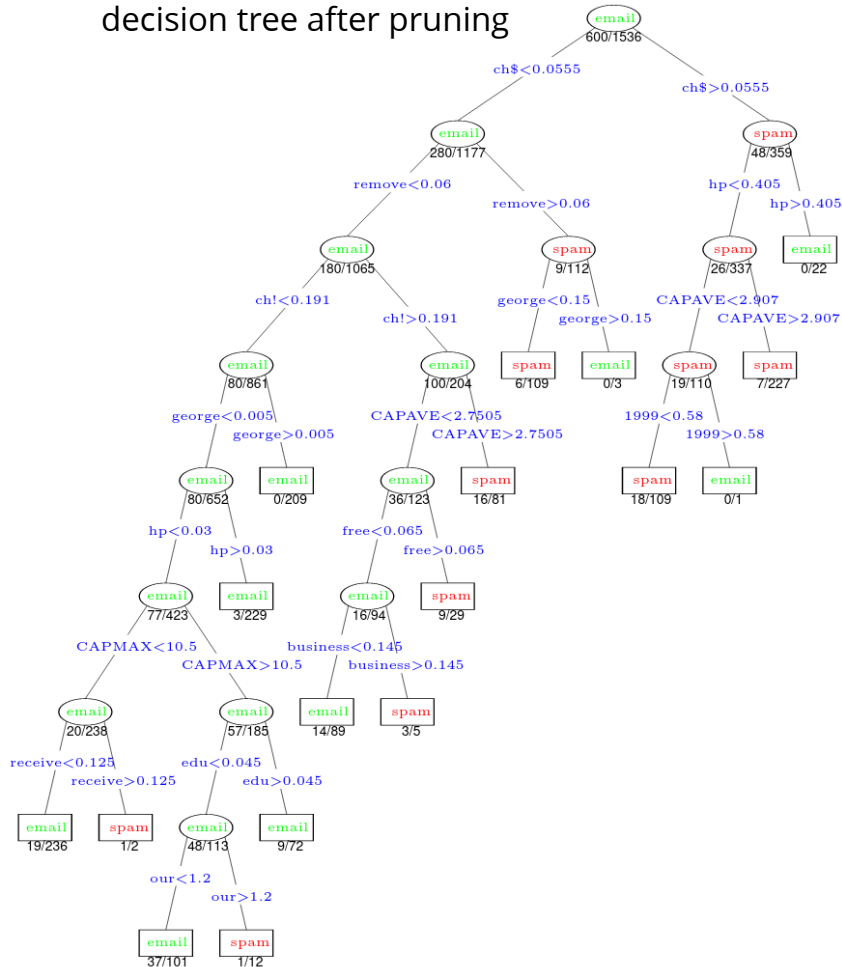
an example of
feature engineering

average value of these features in the spam and non-spam emails

	george	you	your	hp	free	hpl	!	our	re	edu	remove
spam	0.00	2.26	1.38	0.02	0.52	0.01	0.51	0.51	0.13	0.01	0.28
email	1.27	1.27	0.44	0.90	0.07	0.43	0.11	0.18	0.42	0.29	0.01

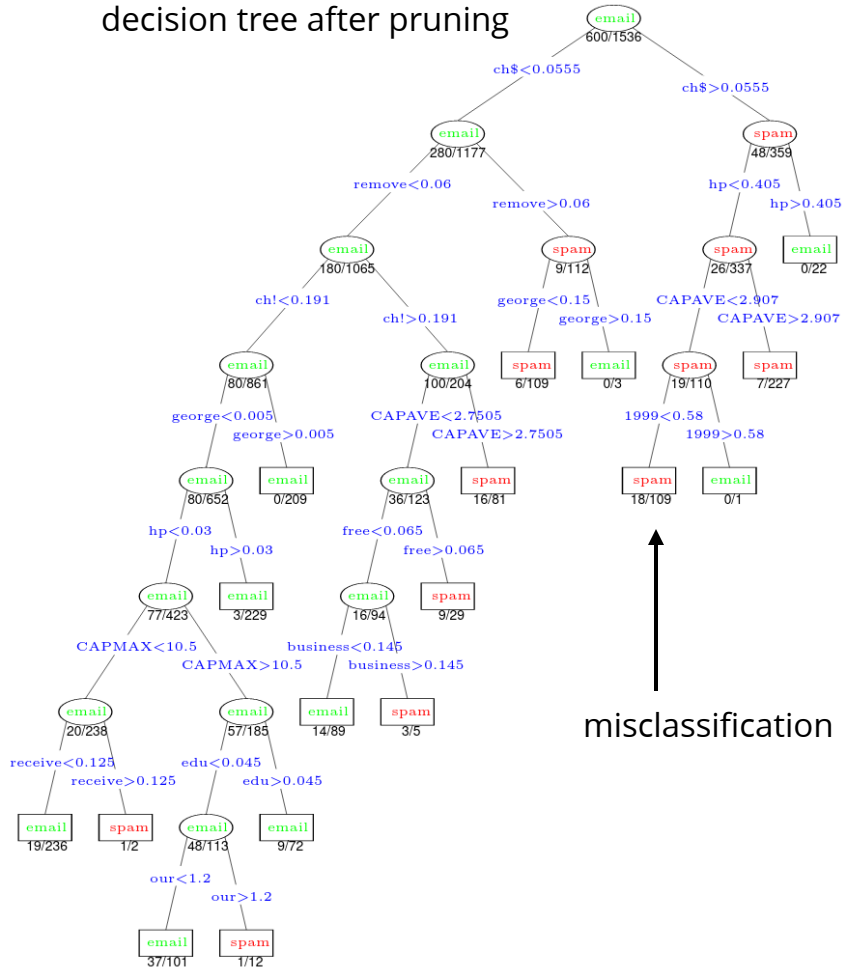
Example: spam detection

decision tree after pruning



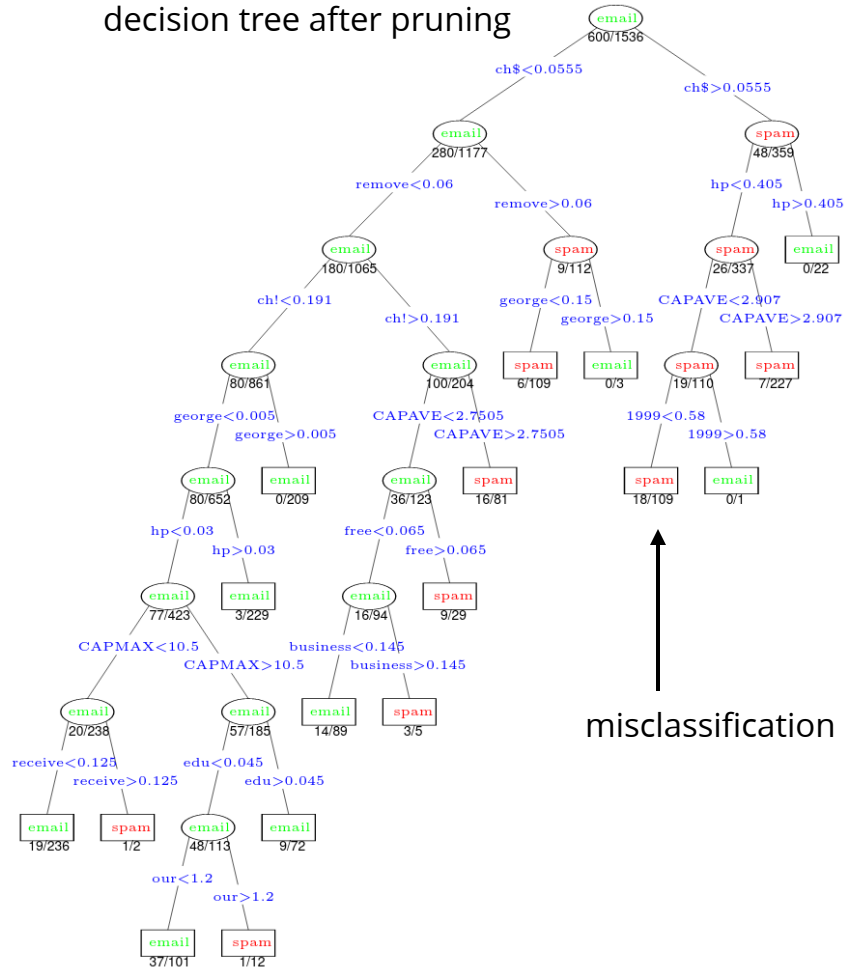
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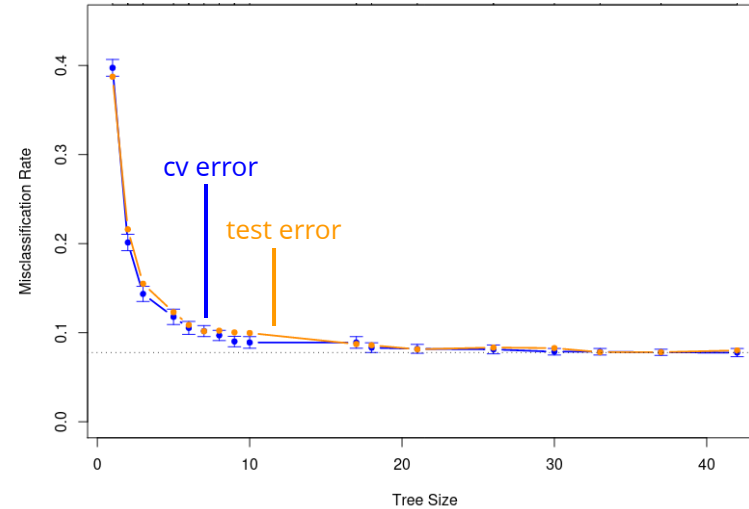


Example: spam detection

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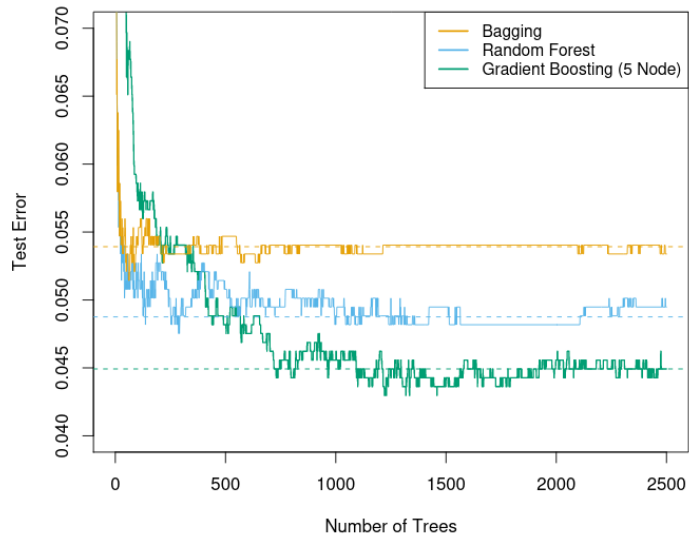
number of leaves (17) in optimal pruning
decided based on cross-validation error



misclassification rate on test data

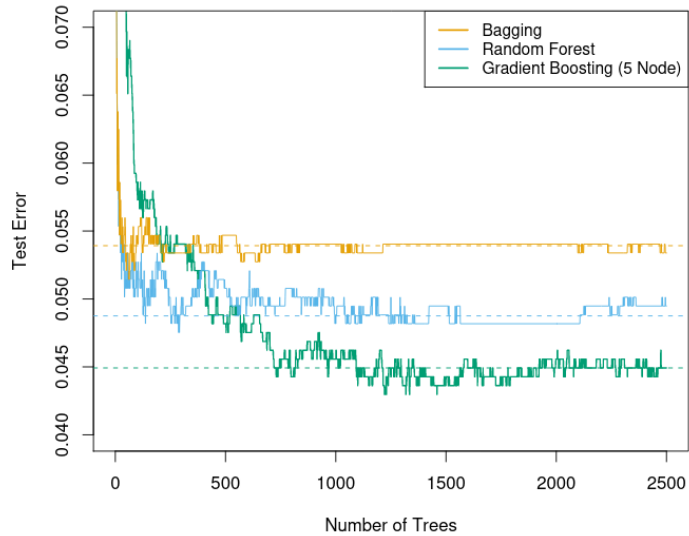
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Bagging and Random Forests do much better than a single decision tree!

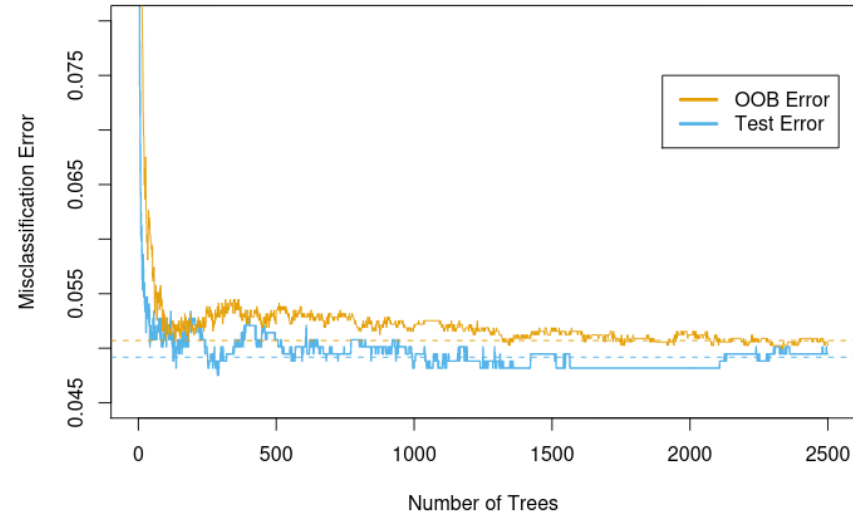


Example: spam detection

Bagging and Random Forests do much better than a single decision tree!



Out Of Bag (OOB) error can be used for parameter tuning (*e.g.*, size of the forest)



Summary so far...

- Bootstrap is a powerful technique to get uncertainty estimates
- Bootstrap aggregation (Bagging) can reduce the variance of unstable models

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- Bootstrap is a powerful technique to get uncertainty estimates
- Bootstrap aggregation (Bagging) can reduce the variance of unstable models
- Random forests:
 - Bagging + further de-correlation of features at each split
 - OOB validation instead of CV
 - destroy interpretability of decision trees
 - perform well in practice
 - can fail if only few relevant features exist (due to feature-sampling)

Adaptive bases

several methods can be classified as *learning these bases adaptively*

- decision trees
- generalized additive models
- **boosting**
- neural networks



$$f(x) = \sum_d w_d \phi_d(x; v_d)$$



in boosting each basis is a classifier or regression function (**weak learner, or base learner**)
create a *strong learner* by sequentially combining *weak learners*

Forward stagewise additive modelling

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optimization idea add one weak-learner in each stage t , to reduce the error of previous stage

1. find the best weak learner

$$v^{\{t\}}, w^{\{t\}} = \arg \min_{v, w} \sum_{n=1}^N L(y^{(n)}, f^{\{t-1\}}(x^{(n)}) + w \phi(x^{(n)}; v))$$

2. add it to the current model

$$f^{\{t\}}(x) = f^{\{t-1\}}(x^{(n)}) + w^{\{t\}} \phi(x^{(n)}; v^{\{t\}})$$

L_2 loss & forward stagewise **linear** model

model

consider **weak learners** that are individual features $\phi^{\{t\}}(x) = w^{\{t\}} x_{d^{\{t\}}}$

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using L2 loss for regression

$$\text{at stage } t \quad \arg \min_{d, w_d} \frac{1}{2} \sum_{n=1}^N \left(y^{(n)} - (f^{\{t-1\}}(x^{(n)}) + w_d x_d^{(n)}) \right)^2$$

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optimization

recall: optimal weight for each d is $w_d = \frac{\sum_n x_d^{(n)} r_d^{(n)}}{\sum_n x_d^{(n)2}}$

pick the feature that most significantly reduces the residual

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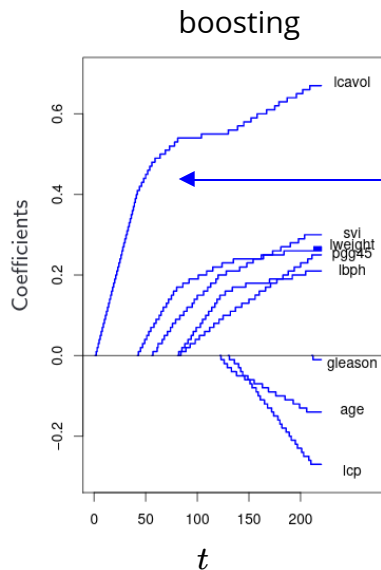
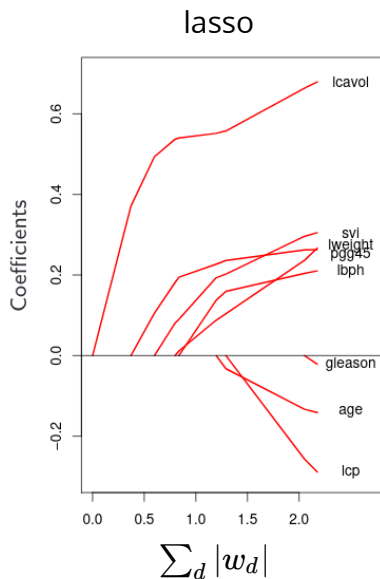
the model at time-step t : $f^{\{t\}}(x) = \sum_t \alpha w_{d^{\{t\}}} x_{d^{\{t\}}}$

using a small α helps with test error

is this related to L1-regularized linear regression?

L_2 loss & forward stagewise **linear** model

using small learning rate $\alpha = .01$ L2 Boosting has a similar regularization path to lasso

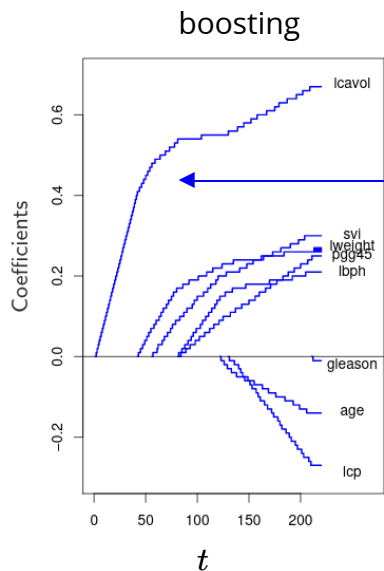
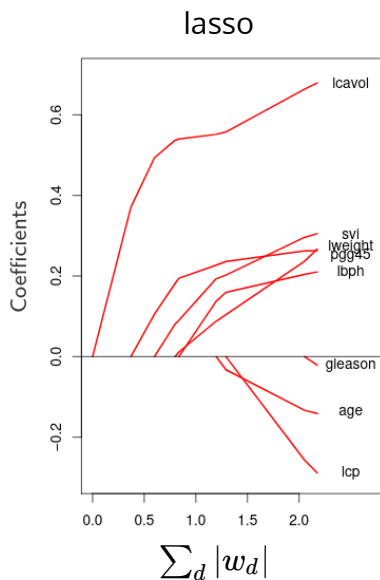


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$$w_d^{\{t\}}$$

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we can view boosting as doing feature (base learner) selection in exponentially large spaces (*e.g.*, all trees of size K)
the number of steps t plays a similar role to (the inverse of) regularization hyper-parameter

Exponential loss & AdaBoost

loss functions for **binary classification** $y \in \{-1, +1\}$

predicted label is $\hat{y} = \text{sign}(f(x))$

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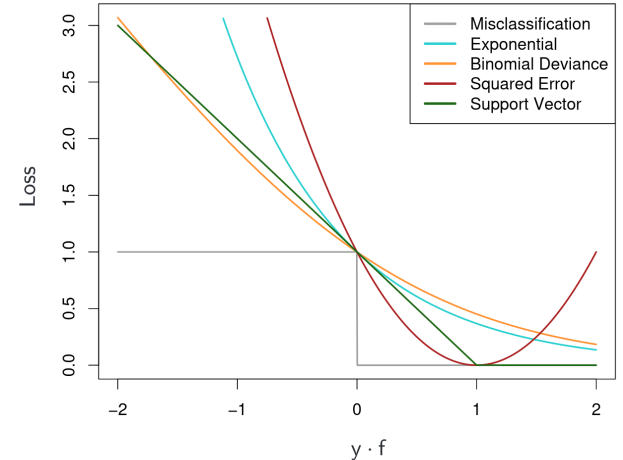
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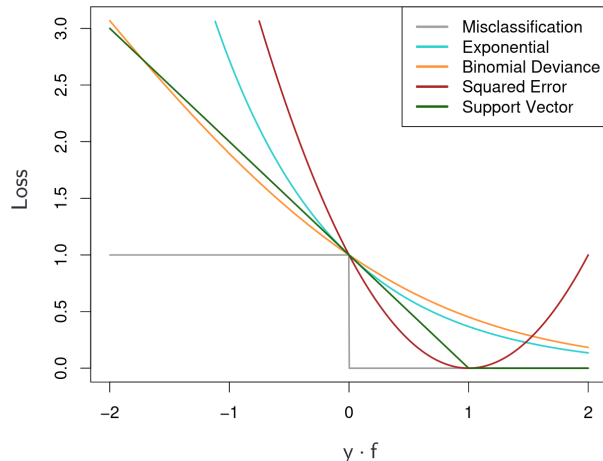
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useful property when working with additive models:

$$L(y, f^{\{t-1\}}(x) + w^{\{t\}} \phi(x, v^{\{t\}})) = L(y, f^{\{t-1\}}(x)) \cdot L(y, w^{\{t\}} \phi(x, v^{\{t\}}))$$

treat this as a weight q for an instance

instances that are not properly classified before receive a higher weight



Exponential loss & AdaBoost

cost using exponential loss

$$J(\{w^{t\}}, v^{t\})_t = \sum_{n=1}^N L(y^{(n)}, f^{t-1}(x^{(n)} + w^{t\} \phi(x^{(n)}, v^{t\}))) = \sum_n q^{(n)} L(y^{(n)}, w^{t\} \phi(x^{(n)}, v^{t\})))$$

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does not depend on
the weak learner

assuming $w^{\{t\}} \geq 0$ the weak learner should minimize this cost
this is classification with weighted instances

Exponential loss & AdaBoost

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we can now update instance weights q for next iteration $q^{(n), \{t+1\}} = q^{(n), \{t\}} e^{-w^{\{t\}} y^{(n)} \phi(x^{(n)}; v^{\{t\}})}$

(multiply by the new loss)

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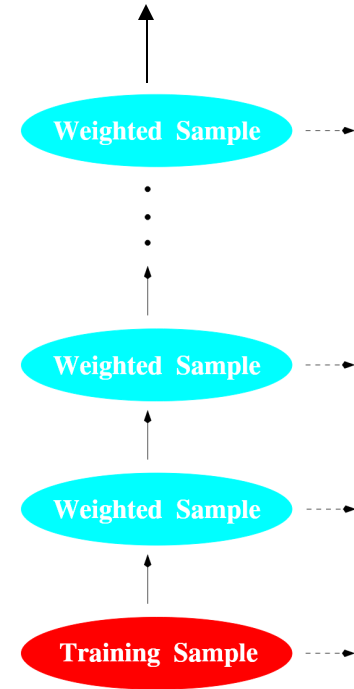
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since $w > 0$, the weight q of misclassified points increase and the rest decrease

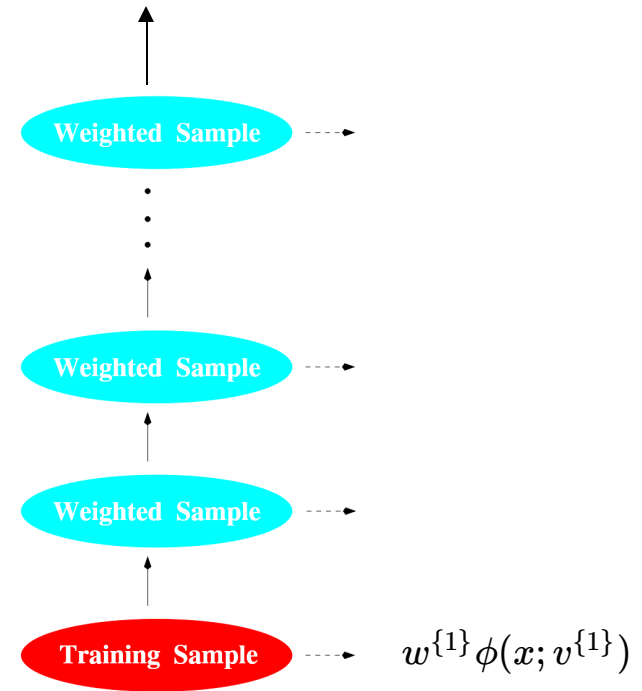
Exponential loss & AdaBoost

overall algorithm for discrete AdaBoost



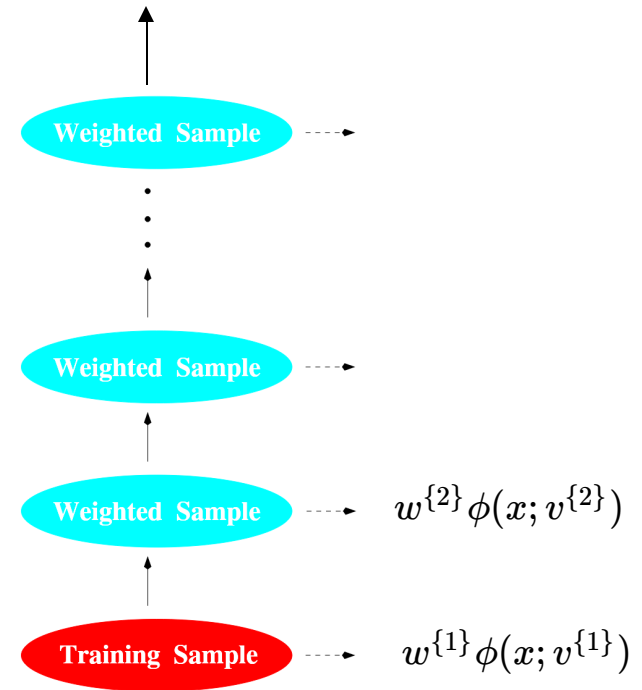
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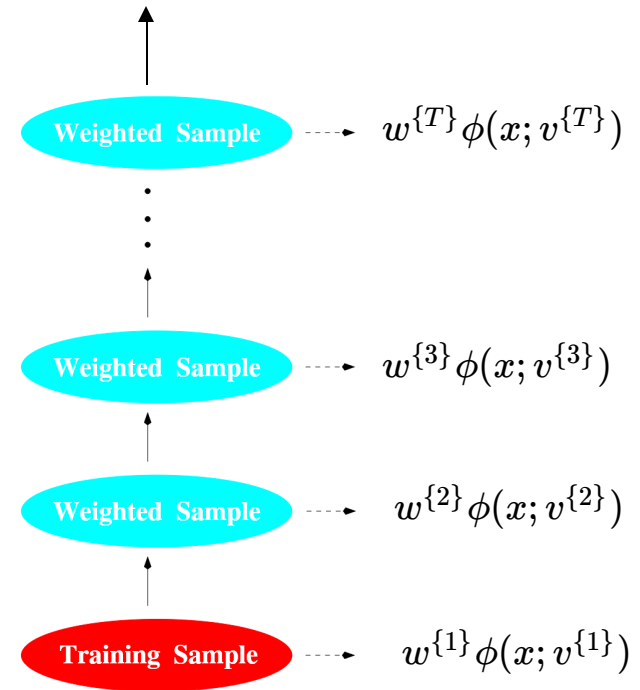
Exponential loss & AdaBoost

overall algorithm for discrete AdaBoost



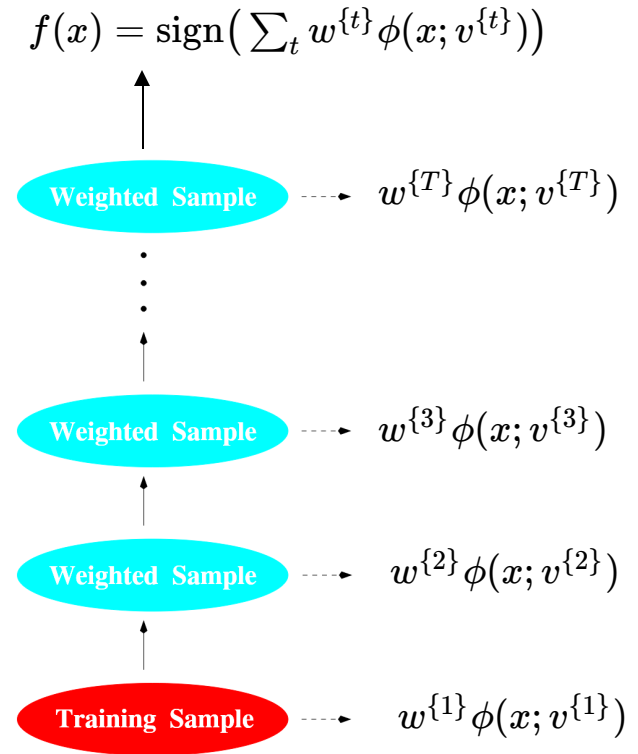
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```
initialize  $q^{(n)} := \frac{1}{N} \quad \forall n$ 
```

```
for t=1:T
```

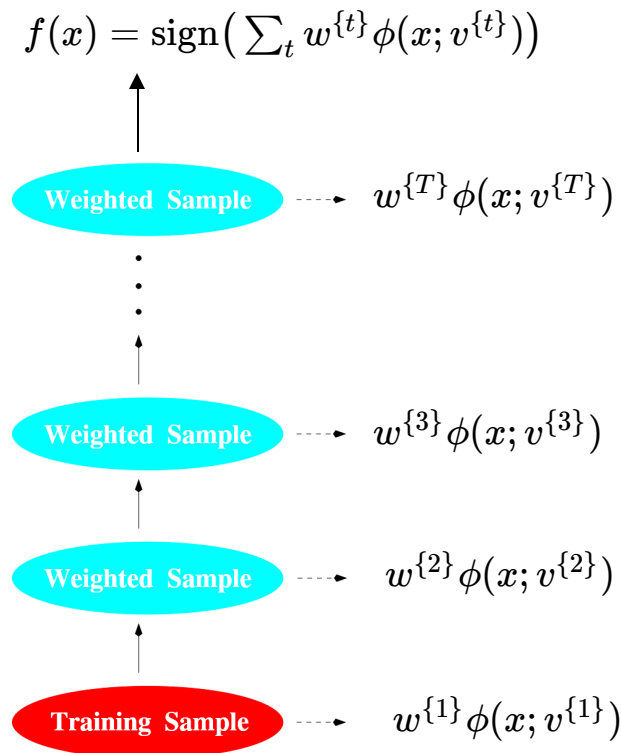
```
    fit the simple classifier  $\phi(x, v^{(t)})$  to the weighted dataset
```

$$\ell^{(t)} := \frac{\sum_n q^{(n)} \mathbb{I}(\phi(x^{(n)}; v^{(t)}) \neq y^{(n)})}{\sum_n q^{(n)}}$$

$$w^{(t)} := \frac{1}{2} \log \frac{1 - \ell^{(t)}}{\ell^{(t)}}$$

$$q^{(n)} := q^{(n)} e^{-w^{(t)} y^{(n)} \phi(x^{(n)}; v^{(t)})} \quad \forall n$$

```
return  $f(x) = \text{sign}(\sum_t w^{(t)} \phi(x; v^{(t)}))$ 
```



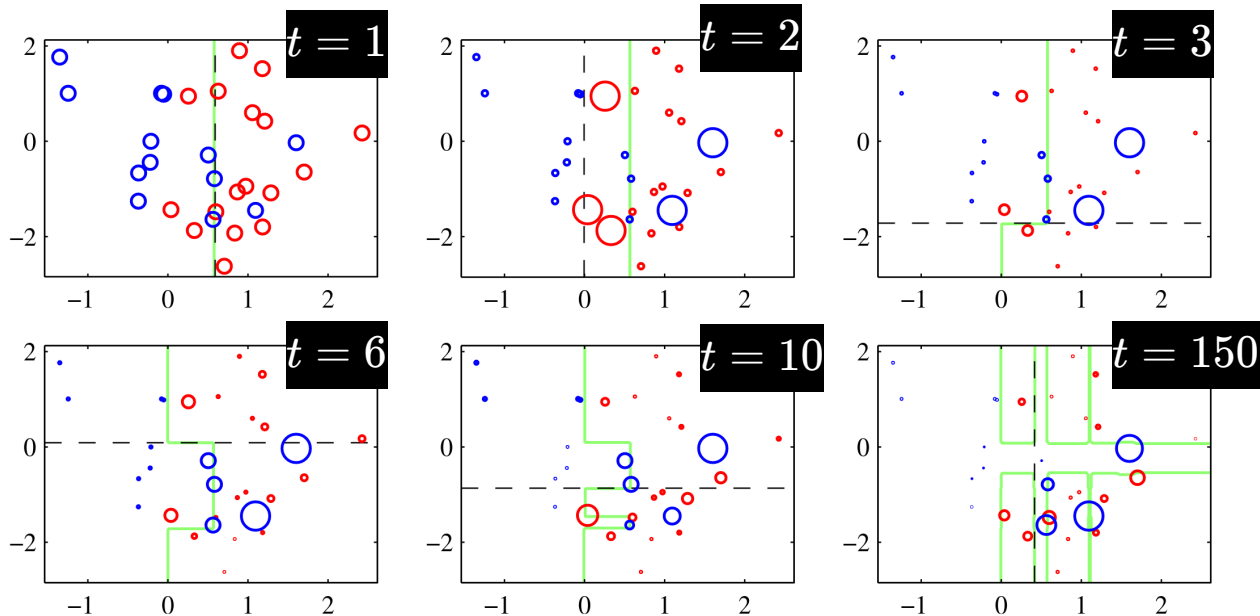
example

AdaBoost

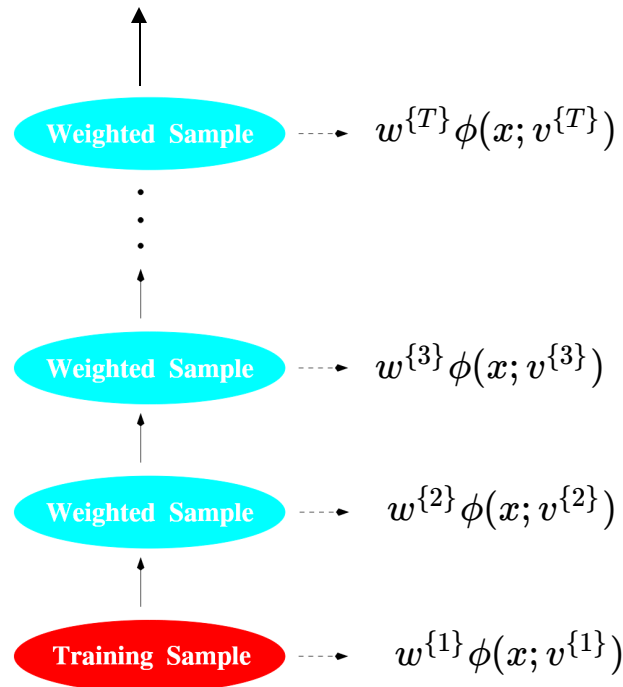
each weak learner is a decision stump (dashed line)

circle size is proportional to $q^{n,\{t\}}$

green is the decision boundary of $f^{\{t\}}$



$$\hat{y} = \text{sign}\left(\sum_t w^{\{t\}} \phi(x; v^{\{t\}})\right)$$



example AdaBoost

features $x_1^{(n)}, \dots, x_{10}^{(n)}$ are samples from standard Gaussian

example

AdaBoost

features $x_1^{(n)}, \dots, x_{10}^{(n)}$ are samples from standard Gaussian

label $y^{(n)} = \mathbb{I}(\sum_d x_d^{(n)2} > 9.34)$

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N=2000 training examples

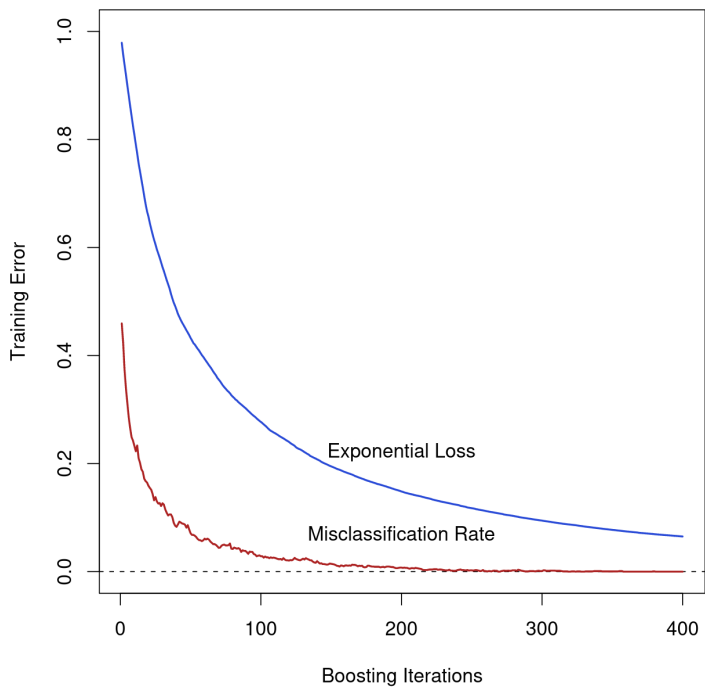
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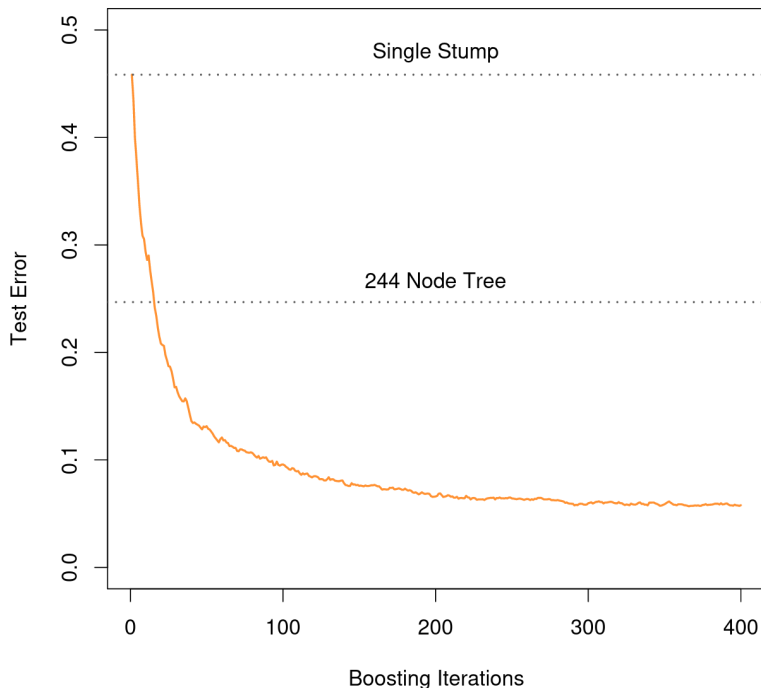
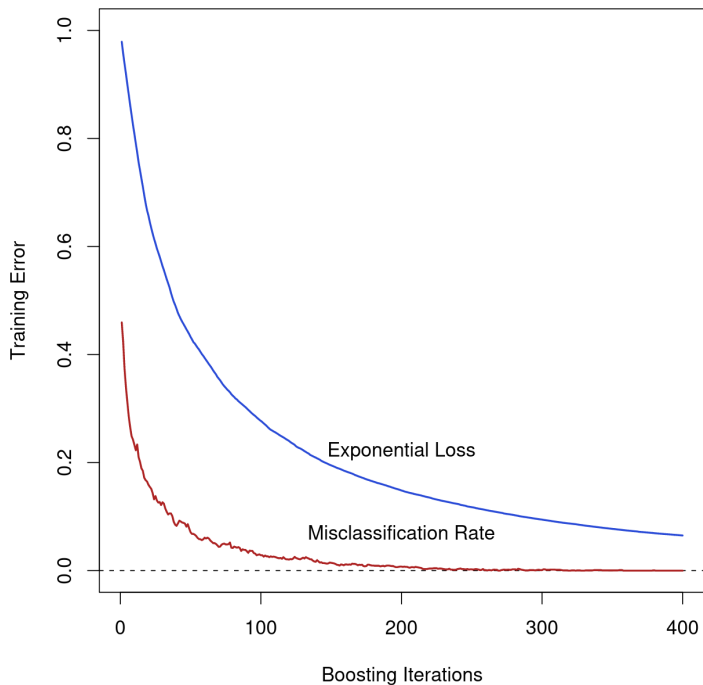
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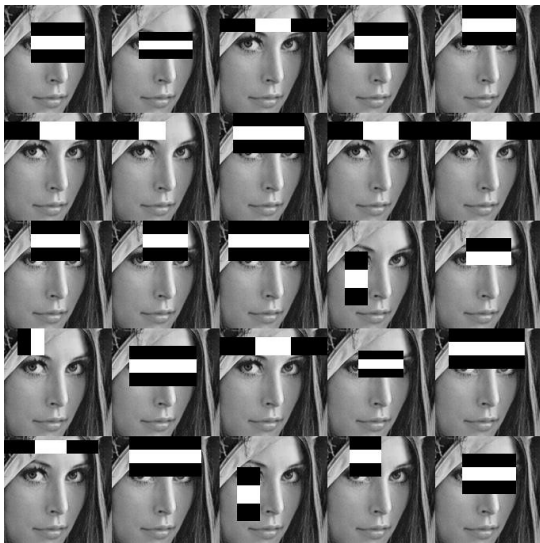
N=2000 training examples

notice that test error does not increase

AdaBoost is very slow to overfit



application: Viola-Jones face detection



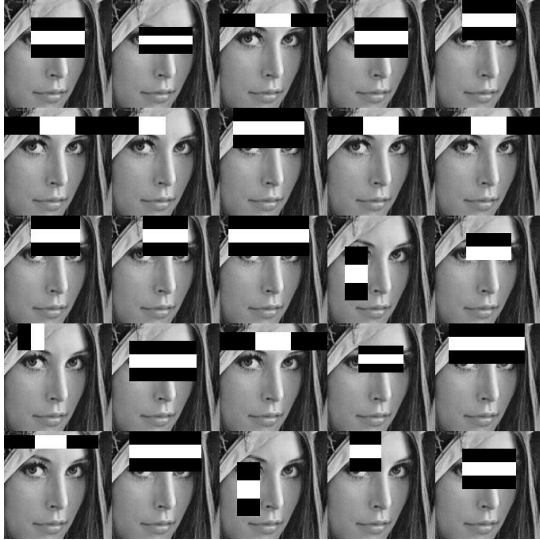
Haar features are computationally efficient
each feature is a weak learner

AdaBoost picks one feature at a time (label: face/no-face)

Still can be inefficient:

- use the fact that faces are rare (.01% of subwindows are faces)
- cascade of classifiers due to small rate

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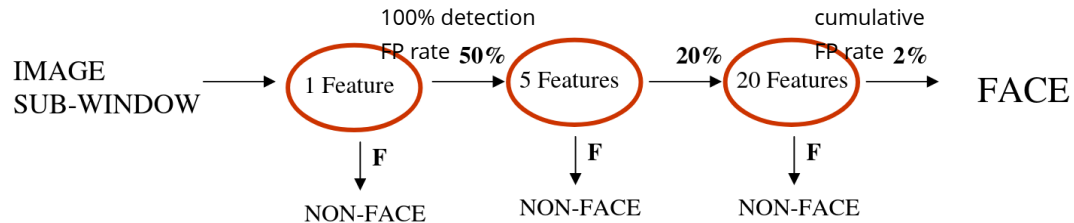


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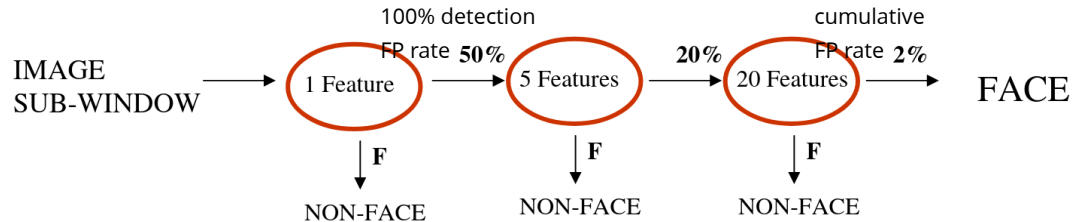


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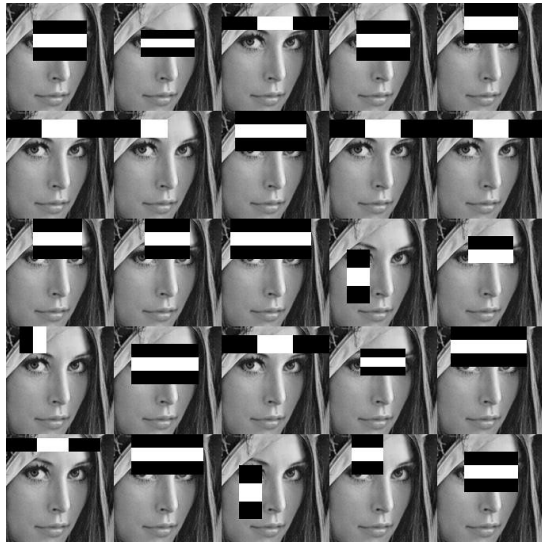
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cascade is applied over all image subwindows

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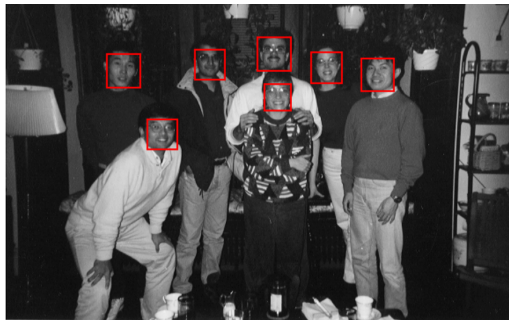
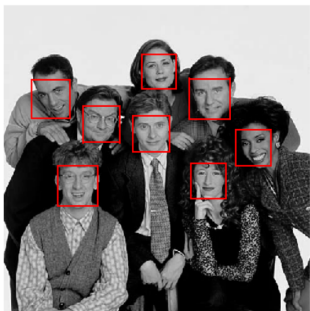
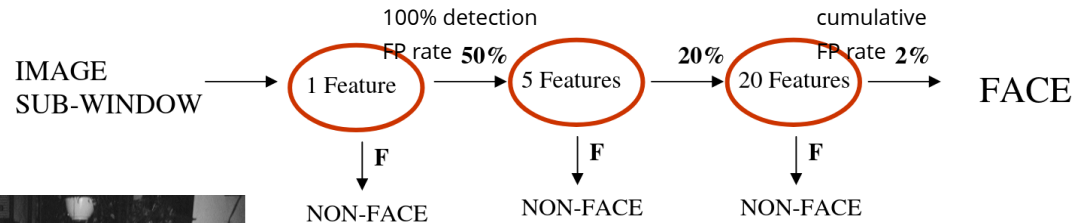


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cascade is applied over all image subwindows
fast enough for real-time (object) detection

Gradient boosting

idea fit the weak learner to the gradient of the cost

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let $\mathbf{f}^{\{t\}} = [f^{\{t\}}(\mathbf{x}^{(1)}), \dots, f^{\{t\}}(\mathbf{x}^{(N)})]^\top$ and true labels $\mathbf{y} = [y^{(1)}, \dots, y^{(N)}]^\top$

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ignoring the structure of \mathbf{f}

if we use gradient descent to minimize the loss $\hat{\mathbf{f}} = \arg \min_{\mathbf{f}} L(\mathbf{f}, \mathbf{y})$

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write $\hat{\mathbf{f}}$ as a sum of steps

$$\hat{\mathbf{f}} = \mathbf{f}^{\{T\}} = \mathbf{f}^{\{0\}} - \sum_{t=1}^T w^{\{t\}} \mathbf{g}^{\{t\}}$$

|
 $\frac{\partial}{\partial \mathbf{f}} L(\mathbf{f}^{\{t-1\}}, \mathbf{y})$
gradient vector
its role is similar to residual

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$w^{\{t\}} = \arg \min_w L(\mathbf{f}^{\{t-1\}} - w \mathbf{g}^{\{t\}})$ we can look for the optimal step size

$\mathbf{g}^{\{t\}} = \frac{\partial}{\partial \mathbf{f}} L(\mathbf{f}^{\{t-1\}}, \mathbf{y})$ gradient vector
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fit the weak-learner to negative of the gradient $v^{\{t\}} = \arg \min_v \frac{1}{2} \|\phi_v - (-\mathbf{g})\|_2^2$

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we can look for the optimal step size gradient vector
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we are fitting the gradient using L2 loss regardless of the original loss function

$$\phi_v = [\phi(x^{(1)}; v), \dots, \phi(x^{(N)}; v)]^\top$$

Gradient tree boosting

apply gradient boosting to CART (classification and regression trees)

```
initialize  $\mathbf{f}^{\{0\}}$  to predict a constant
```

```
for t=1:T
```

```
  calculate the negative of the gradient  $\mathbf{r} = -\frac{\partial}{\partial \mathbf{f}} L(\mathbf{f}^{\{t-1\}}, \mathbf{y})$ 
```

```
  fit a regression tree to  $\mathbf{X}, \mathbf{r}$  and produce regions  $\mathbb{R}_1, \dots, \mathbb{R}_K$ 
```

```
  re-adjust predictions per region  $w_k = \arg \min_w \sum_{x^{(n)} \in \mathbb{R}_k} L(y^{(n)}, f^{\{t-1\}}(x^{(n)}) + w_k)$ 
```

```
  update  $f^{\{t\}}(x) = f^{\{t-1\}}(x) + \alpha \sum_{k=1}^K w_k \mathbb{I}(x \in \mathbb{R}_k)$ 
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```
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 $N \times D$ N

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stochastic gradient boosting

- combines bootstrap and boosting
- use a subsample at each iteration above
- similar to stochastic gradient descent

example

Gradient tree boosting

recall the synthetic example:

features $x_1^{(n)}, \dots, x_{10}^{(n)}$ are samples from standard Gaussian

label $y^{(n)} = \mathbb{I}(\sum_d x_d^{(n)} > 9.34)$

N=2000 training examples

example

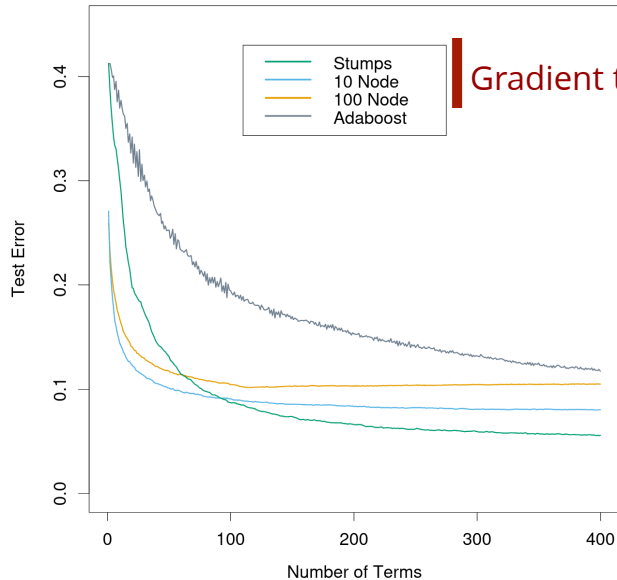
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Gradient tree boosting (using log-loss) works better than Adaboost

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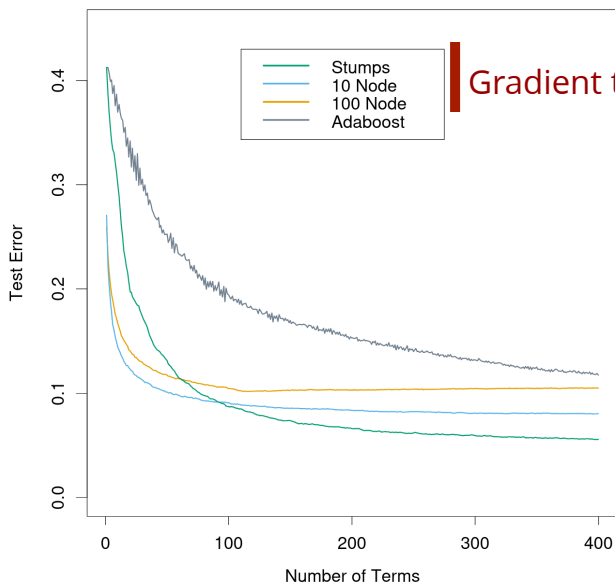
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since sum of features are used in prediction using stumps work best

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$$\alpha = .2$$

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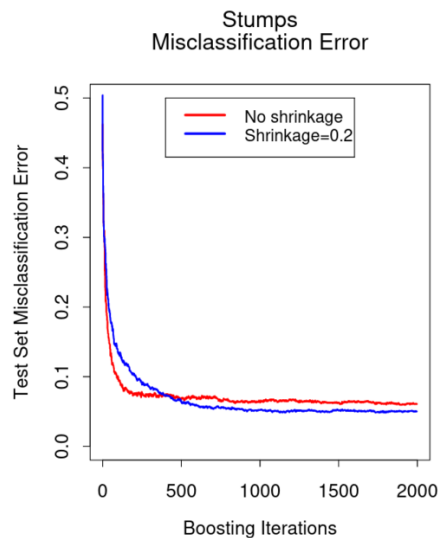
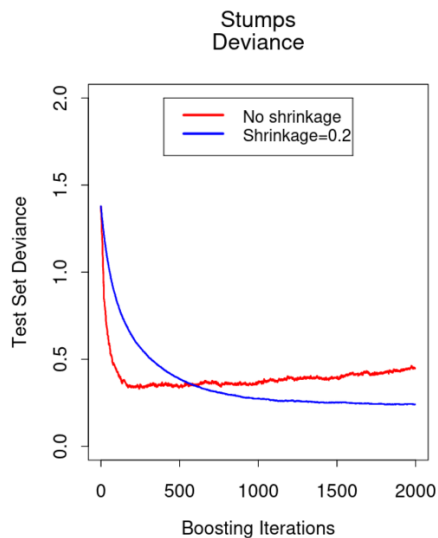
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N=2000 training examples

deviance = cross entropy = log-loss

(K=2) stump



$\alpha = .2$

example

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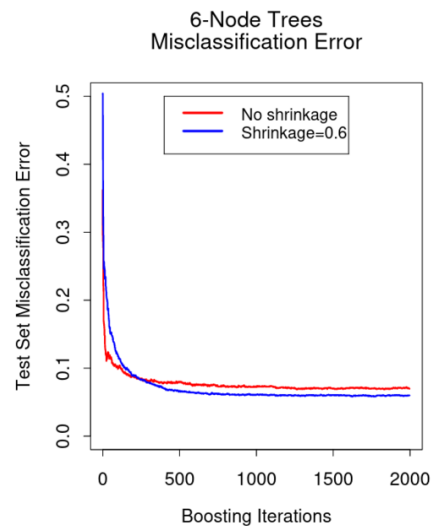
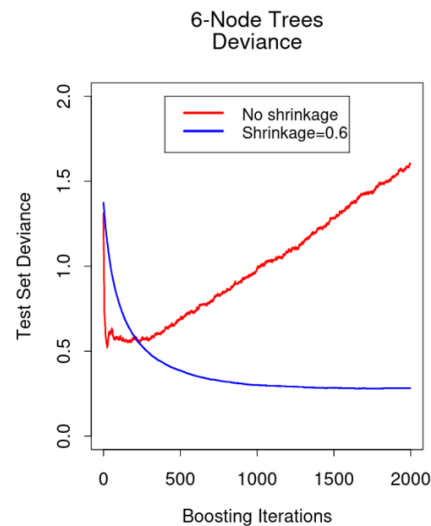
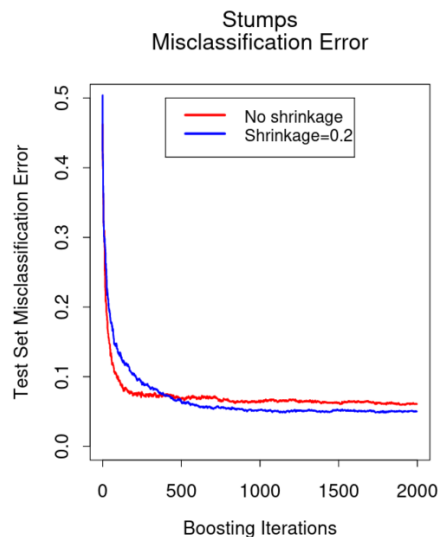
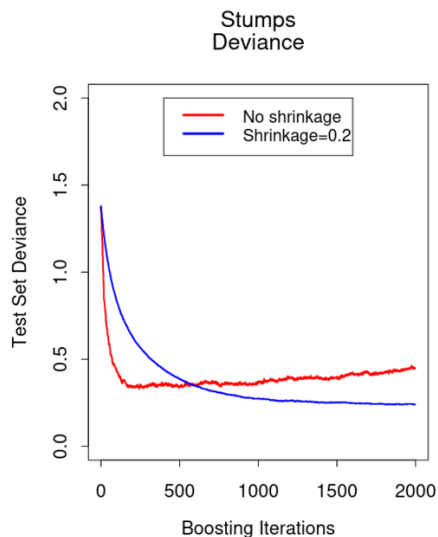
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(K=2) stump

K=6



$\alpha = .2$

example

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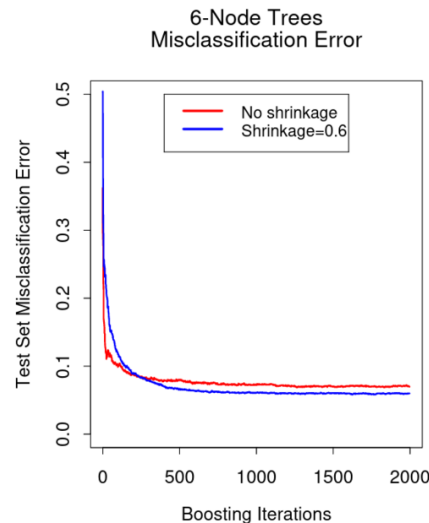
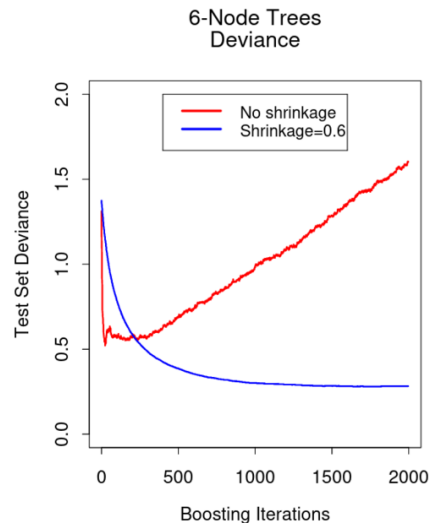
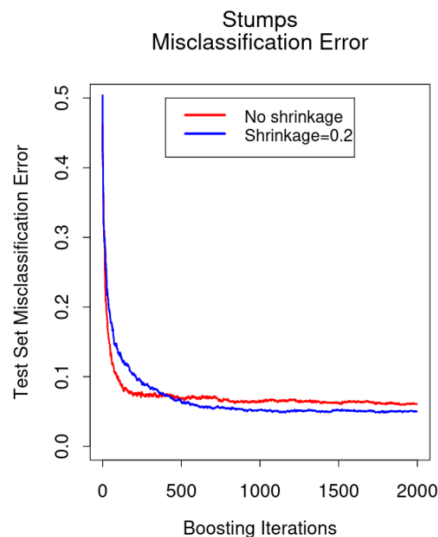
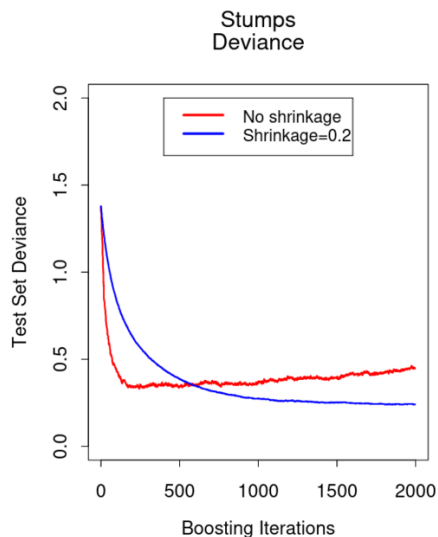
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N=2000 training examples

deviance = cross entropy = log-loss

(K=2) stump K=6



in both cases using shrinkage $\alpha = .2$ helps

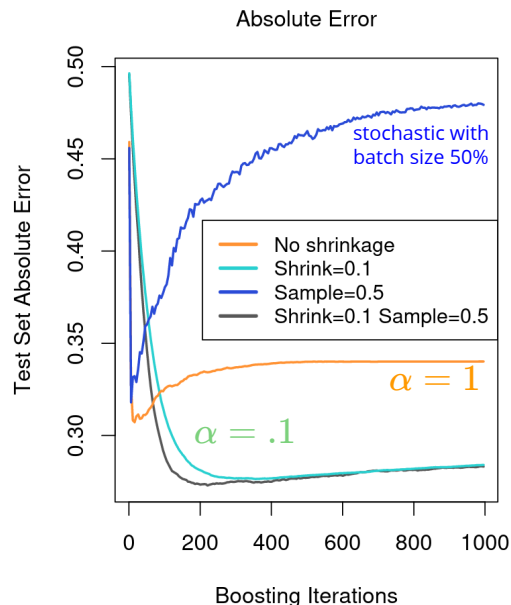
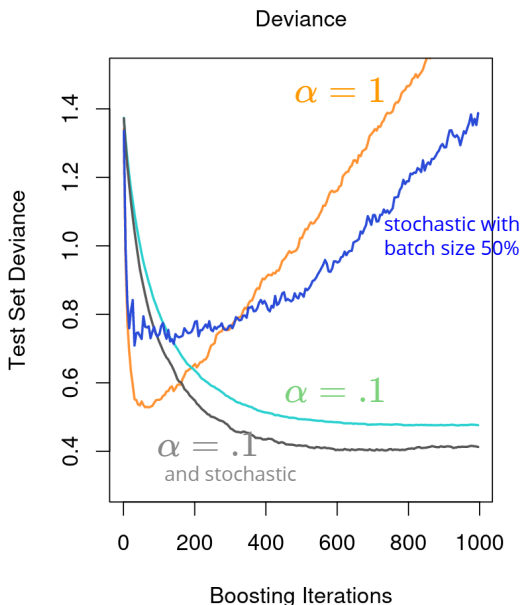
while test loss may increase, test misclassification error does not

Gradient tree boosting

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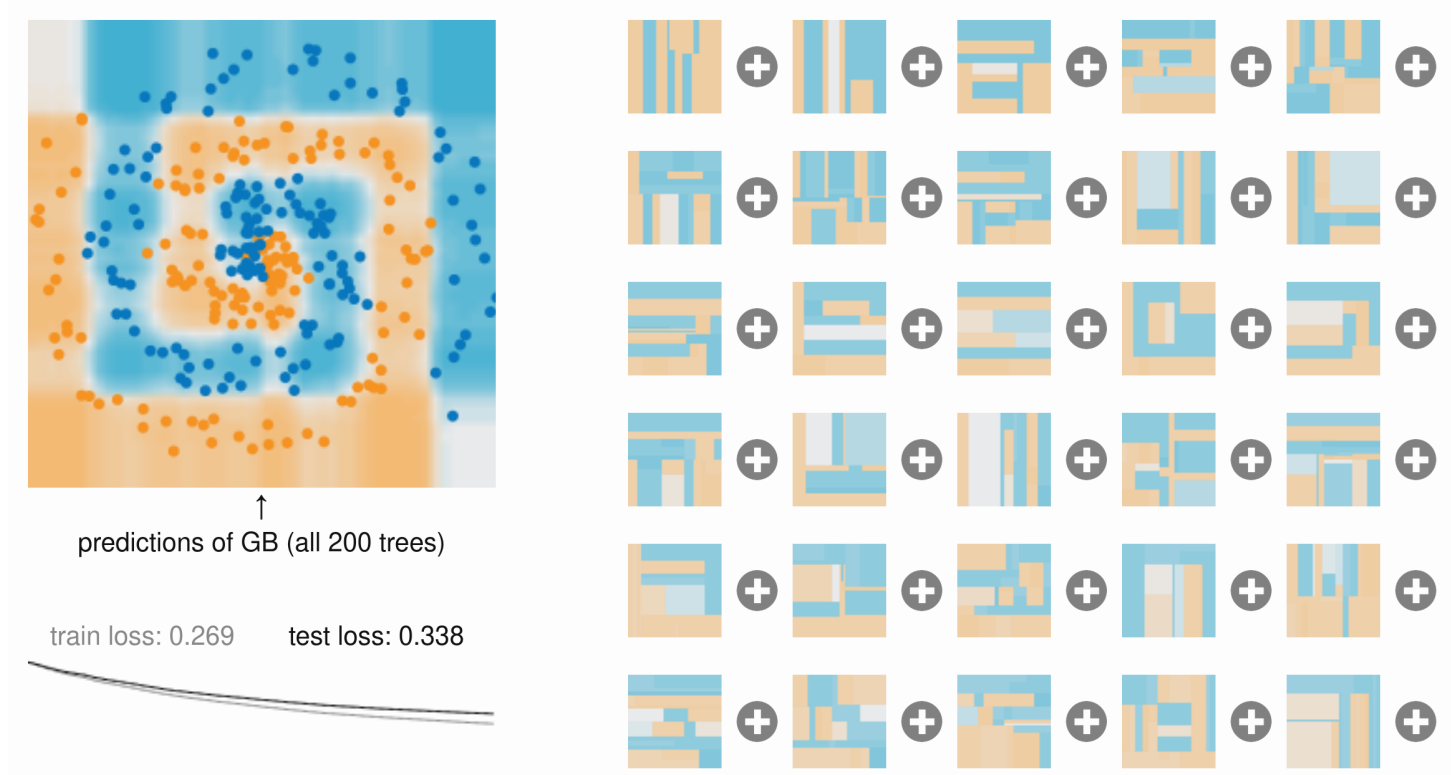
4-Node Trees



both shrinkage and **subsampling** can help
 more hyper-parameters to tune

example

Gradient tree boosting



see the interactive demo: https://arogozhnikov.github.io/2016/07/05/gradient_boosting_playground.html

Summary

two **ensemble methods**

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- bagging & random forests (reduce variance)
 - produce models with minimal correlation
 - use their average prediction

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- bagging & random forests (reduce variance)
 - produce models with minimal correlation
 - use their average prediction
- boosting (reduces the bias of the weak learner)
 - models are added in steps
 - a single cost function is minimized
 - for exponential loss: interpret as re-weighting the instance (AdaBoost)
 - gradient boosting: fit the weak learner to the negative of the gradient
 - interpretation as L1 regularization for "weak learner"-selection
 - also related to max-margin classification (for large number of steps T)

Summary

two **ensemble methods**

- bagging & random forests (reduce variance)
 - produce models with minimal correlation
 - use their average prediction
- boosting (reduces the bias of the weak learner)
 - models are added in steps
 - a single cost function is minimized
 - for exponential loss: interpret as re-weighting the instance (AdaBoost)
 - gradient boosting: fit the weak learner to the negative of the gradient
 - interpretation as L1 regularization for "weak learner"-selection
 - also related to max-margin classification (for large number of steps T)
- random forests and (gradient) boosting generally perform very well

Gradient boosting

Gradient for some loss functions $\hat{\mathbf{f}} = \mathbf{f}^{\{T\}} = \mathbf{f}^{\{0\}} - \sum_{t=1}^T w^{\{t\}} \frac{\partial}{\partial \mathbf{f}} L(\mathbf{f}^{\{t-1\}}, \mathbf{y})$

setting	loss function	$-\frac{\partial}{\partial \mathbf{f}} L(\mathbf{f}^{\{t-1\}}, \mathbf{y})$
regression	$\frac{1}{2} \ \mathbf{y} - \mathbf{f}\ _2^2$	$\mathbf{y} - \mathbf{f}$
regression	$\ \mathbf{y} - \mathbf{f}\ _1$	$\text{sign}(\mathbf{y} - \mathbf{f})$
binary classification	$\exp(-\mathbf{y}\mathbf{f})$ exponential loss	$-\mathbf{y} \exp(-\mathbf{y}\mathbf{f})$
multiclass classification	multi-class cross-entropy	$\mathbf{Y} - \mathbf{P}$ $N \times C \quad N \times C$ <i>one-hot coding for C-class classification</i> <i>predicted class probabilities</i> $\mathbf{P}_{c,:} = \text{softmax}(f_{[c]})$