

Markov Processes as Function Transformers

Part II: Functorial View of Expectation Values

Prakash Panangaden¹

¹School of Computer Science
McGill University

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Outline

- 1 Introduction
- 2 Some background
- 3 The Arena: Two Categories
- 4 The expectations value functors
- 5 Labelled abstract Markov processes

Approximation via Averaging

- 1 Approximation of Markov processes should be based on “averaging”.
- 2 Averages are computed by expectation values.
- 3 Beautiful functorial presentation of expectation values d’après Vincent Danos.
- 4 Make bisimulation and approximation live in the same universe

Duality is the Key

$$\begin{array}{ccccc} \mathcal{M}^{\ll p}(X) & \xleftrightarrow{\sim} & L_1^+(X, p) & \xleftrightarrow{\sim} & L_{\infty}^{+,*}(X, p) & (1) \\ \uparrow \text{---} \downarrow & & \uparrow \text{---} \downarrow & & \uparrow \text{---} \downarrow & \\ \mathcal{M}_{\text{UB}}^p & \xleftrightarrow{\sim} & L_{\infty}^+(X, p) & \xleftrightarrow{\sim} & L_1^{+,*}(X, p) & \end{array}$$

where the vertical arrows represent dualities and the horizontal arrows represent isomorphisms.

Pairing function

There is a map from the product of the cones $L_{\infty}^+(X, p)$ and $L_1^+(X, p)$ to \mathbb{R}^+ defined as follows:

$$\forall f \in L_{\infty}^+(X, p), g \in L_1^+(X, p) \quad \langle f, g \rangle = \int fgdp.$$

- 1 Given (X, Σ, p) and (Y, Λ) and a measurable function $f : X \rightarrow Y$ we obtain a measure q on Y by $q(B) = p(f^{-1}(B))$. This is written $M_f(p)$ and is called the *image measure* of p under f .
- 2 We say that a measure ν is **absolutely continuous** with respect to another measure μ if for any measurable set A , $\mu(A) = 0$ implies that $\nu(A) = 0$. We write $\nu \ll \mu$.

The Radon-Nikodym Theorem

The Radon-Nikodym theorem is a central result in measure theory allowing one to define a “derivative” of a measure with respect to another measure.

Radon-Nikodym

If $\nu \ll \mu$, where ν, μ are finite measures on a measurable space (X, Σ) there is a positive measurable function h on X such that for every measurable set B

$$\nu(B) = \int_B h \, d\mu.$$

The function h is defined uniquely up to a set of μ -measure 0. The function h is called the Radon-Nikodym derivative of ν with respect to μ ; we denote it by $\frac{d\nu}{d\mu}$. Since ν is finite, $\frac{d\nu}{d\mu} \in L_1^+(X, \mu)$.

Notation for Radon-Nikodym

- 1 Given an (almost-everywhere) positive function $f \in L_1(X, p)$, we let $f \cdot p$ be the measure which has density f with respect to p .
- 2 Two identities that we get from the Radon-Nikodym theorem are:
 - given $q \ll p$, we have $\frac{dq}{dp} \cdot p = q$.
 - given $f \in L_1^+(X, p)$, $\frac{df \cdot p}{dp} = f$
- 3 These two identities just say that the operations $(-) \cdot p$ and $\frac{d(-)}{dp}$ are inverses of each other as maps between $L_1^+(X, p)$ and $\mathcal{M}^{\ll p}(X)$ the space of finite measures on X that are absolutely continuous with respect to p .

Expectation and conditional expectation

- 1 The expectation $\mathbb{E}_p(f)$ of a measurable function f is the average computed by $\int f dp$ and therefore it is just a number.
- 2 The *conditional* expectation is not a mere number but a random variable.
- 3 It is meant to measure the expected value in the presence of additional information.
- 4 The additional information takes the form of a sub- σ algebra, say Λ , of Σ . The experimenter knows, for every $B \in \Lambda$, whether the outcome is in B or not.
- 5 Now she can recompute the expectation values given this information.

Formalizing conditional expectation

- It is an immediate consequence of the Radon-Nikodym theorem that such conditional expectations exist.

Kolmogorov

Let (X, Σ, p) be a measure space with p a finite measure, f be in $L_1(X, \Sigma, p)$ and Λ be a sub- σ -algebra of Σ , then there exists a $g \in L_1(X, \Lambda, p)$ such that for all $B \in \Lambda$

$$\int_B f dp = \int_B g dp.$$

- This function g is usually denoted by $\mathbb{E}(f|\Lambda)$.
- We clearly have $f \cdot p \ll p$ so the required g is simply $\frac{df \cdot p}{dp|_\Lambda}$, where $p|_\Lambda$ is the restriction of p to the sub- σ -algebra Λ .

Properties of conditional expectation

- 1 The point of requiring Λ -measurability is that it “smooths out” variations that are too rapid to show up in Λ .
- 2 The conditional expectation is *linear*, *increasing* with respect to the pointwise order.
- 4 It is defined uniquely p -almost everywhere.

Where the action happens

- We define two categories \mathbf{Rad}_∞ and \mathbf{Rad}_1 that will be needed for the functorial definition of conditional expectation.
- This will allow for L_∞ and L_1 versions of the theory.
- Going between these versions by duality will be very useful.

The “infinity” category

\mathbf{Rad}_∞

The category \mathbf{Rad}_∞ has as objects probability spaces, and as arrows $\alpha : (X, p) \rightarrow (Y, q)$, measurable maps such that $M_\alpha(p) \leq Kq$ for some real number K .

The reason for choosing the name \mathbf{Rad}_∞ is that $\alpha \in \mathbf{Rad}_\infty$ maps to $d/dq M_\alpha(p) \in L_\infty^+(Y, q)$.

The “one” category

Rad₁

The category **Rad**₁ has as objects probability spaces and as arrows $\alpha : (X, p) \rightarrow (Y, q)$, measurable maps such that $M_\alpha(p) \ll q$.

- 1 The reason for choosing the name **Rad**₁ is that $\alpha \in \mathbf{Rad}_1$ maps to $d/dq M_\alpha(p) \in L_1^+(Y, q)$.
- 2 The fact that the category **Rad**_∞ embeds in **Rad**₁ reflects the fact that L_∞^+ embeds in L_1^+ .

Recall the isomorphism between $L_\infty^+(X, p)$ and $L_1^{+,*}(X, p)$ mediated by the pairing function:

$$f \in L_\infty^+(X, p) \mapsto \lambda g : L_1^+(X, p). \langle f, g \rangle = \int fg d p.$$

Precomposition

- 1 Now, precomposition with α in \mathbf{Rad}_∞ gives a map $P_1(\alpha)$ from $L_1^+(Y, q)$ to $L_1^+(X, p)$.
- 2 Dually, given $\alpha \in \mathbf{Rad}_1 : (X, p) \rightarrow (Y, q)$ and $g \in L_\infty^+(Y, q)$ we have that $P_\infty(\alpha)(g) \in L_\infty^+(X, p)$.
- 3 Thus the subscripts on the two precomposition functors describe the *target* categories.
- 4 Using the $*$ -functor we get a map $(P_1(\alpha))^*$ from $L_1^{+,*}(X, p)$ to $L_1^{+,*}(Y, q)$ in the first case and
- 5 dually we get $(P_\infty(\alpha))^*$ from $L_\infty^{+,*}(X, p)$ to $L_\infty^{+,*}(Y, q)$.

Expectation value functor

- The **functor** $\mathbb{E}_\infty(\cdot)$ is a functor from \mathbf{Rad}_∞ to $\omega\mathbf{CC}$ which, on objects, maps (X, p) to $L_\infty^+(X, p)$ and on maps is given as follows:
- Given $\alpha : (X, p) \rightarrow (Y, q)$ in \mathbf{Rad}_∞ the action of the functor is to produce the map $\mathbb{E}_\infty(\alpha) : L_\infty^+(X, p) \rightarrow L_\infty^+(Y, q)$ obtained by composing $(P_1(\alpha))^*$ with the isomorphisms between $L_1^{+,*}$ and L_∞^+

$$\begin{array}{ccc} L_1^{+,*}(X, p) & \leftarrow \dots\dots\dots & L_\infty^+(X, p) \\ (P_1(\alpha))^* \downarrow & & \downarrow \mathbb{E}_\infty(\alpha) \\ L_1^{+,*}(Y, q) & \dots\dots\dots > & L_\infty^+(Y, q) \end{array}$$

Consequences

- 1 It is an immediate consequence of the definitions that for any $f \in L_\infty^+(X, p)$ and $g \in L_1(Y, q)$

$$\langle \mathbb{E}_\infty(\alpha)(f), g \rangle_Y = \langle f, P_1(\alpha)(g) \rangle_X.$$

$$\begin{array}{ccc} \lambda h : L_1^+(X, p) \cdot \langle f, h \rangle & \longleftarrow & f \\ \downarrow & & \vdots \\ \lambda g : L_1^+(Y, q) \cdot \langle f, g \circ \alpha \rangle & \longmapsto & \mathbb{E}_\infty(\alpha)(f) \end{array}$$

- 2 One can informally view this functor as a “left adjoint” in view of this proposition.
- 3 Note that since we started with α in \mathbf{Rad}_∞ we get the expectation value as a map between the L_∞^+ cones.

The other expectation value functor

The **functor** $\mathbb{E}_1(\cdot)$ is a functor from \mathbf{Rad}_1 to $\omega\mathbf{CC}$ which maps the object (X, p) to $L_1^+(X, p)$ and on maps is given as follows:

Given $\alpha : (X, p) \rightarrow (Y, q)$ in \mathbf{Rad}_1 the action of the functor is to produce the map $\mathbb{E}_1(\alpha) : L_1^+(X, p) \rightarrow L_1^+(Y, q)$ obtained by composing $(P_\infty(\alpha))^*$ with the isomorphisms between $L_\infty^{+,*}$ and L_1^+ as shown in the diagram below

$$\begin{array}{ccc} L_\infty^{+,*}(X, p) & \leftarrow \cdots & L_1^+(X, p) \\ (P_\infty(\alpha))^* \downarrow & & \downarrow \mathbb{E}_1(\alpha) \\ L_\infty^{+,*}(Y, q) & \cdots \rightarrow & L_1^+(Y, q) \end{array}$$

Another “adjoint”

Once again we have an “adjointness” statement; this time it is a right adjoint.

Right adjoint

Given $f \in L_{\infty}^{+}(Y, q)$ and $g \in L_1^{+}(X, p)$ we have

$$\langle f, \mathbb{E}_1(\alpha)(g) \rangle_Y = \langle P_{\infty}(\alpha)(f), g \rangle_X.$$

Relating the two expectation value functors

Given $\alpha \in \mathbf{Rad}_\infty[(X, p), (Y, q)]$ we have

$$(a) \quad \mathbb{E}_1(\alpha)(f \circ \alpha) = \mathbb{E}_\infty(\alpha)(\mathbf{1}_X)f,$$

$$(b) \quad \mathbb{E}_\infty(\alpha)(f \circ \alpha) = \mathbb{E}_1(\alpha)(\mathbf{1}_X)f,$$

for $f \in L_1^+(Y, q)$ and

for $f \in L_\infty^+(Y, q)$.

- 1 Given τ a Markov kernel from (X, Σ) to (Y, Λ) , we define $T_\tau : \mathcal{L}^+(Y) \rightarrow \mathcal{L}^+(X)$, for $f \in \mathcal{L}^+(Y)$, $x \in X$, as
$$T_\tau(f)(x) = \int_Y f(z) \tau(x, dz).$$
- 2 This map is well-defined, linear and ω -continuous.
- 3 If we write $\mathbf{1}_B$ for the indicator function of the measurable set B we have that $T_\tau(\mathbf{1}_B)(x) = \tau(x, B)$.
- 4 It encodes all the transition probability information

- 1 Conversely, any ω -continuous morphism L with $L(\mathbf{1}_Y) \leq \mathbf{1}_X$ can be cast as a Markov kernel by reversing the process on the last slide.
- 2 The interpretation of L is that $L(\mathbf{1}_B)$ is a measurable function on X such that $L(\mathbf{1}_B)(x)$ is the probability of jumping from x to B .

- 1 We can also define an operator on $\mathcal{M}(X)$ by using τ the other way.
- 2 We define $\bar{T}_\tau : \mathcal{M}(X) \rightarrow \mathcal{M}(Y)$, for $\mu \in \mathcal{M}(X)$ and $B \in \Lambda$, as
$$\bar{T}_\tau(\mu)(B) = \int_X \tau(x, B) \, d\mu(x).$$
- 3 It is easy to show that this map is linear and ω -continuous.

What do they mean?

- 1 The operator \bar{T}_τ transforms measures “forwards in time”; if μ is a measure on X representing the current state of the system, $\bar{T}_\tau(\mu)$ is the resulting measure on Y after a transition through τ .
- 2 The operator T_τ may be interpreted as a likelihood transformer which propagates information “backwards”, just as we expect from predicate transformers.
- 3 $T_\tau(f)(x)$ is just the expected value of f after one τ -step given that one is at x .

The definition

An **abstract Markov kernel** from (X, Σ, p) to (Y, Λ, q) is an ω -continuous linear map $\tau : L_{\infty}^{+}(Y) \rightarrow L_{\infty}^{+}(X)$ with $\|\tau\| \leq 1$.

LAMPS

A **labelled abstract Markov process** on a probability space (X, Σ, p) with a set of labels (or actions) \mathcal{A} is a family of abstract Markov kernels $\tau_a : L_{\infty}^{+}(X, p) \rightarrow L_{\infty}^{+}(X, p)$ indexed by elements a of \mathcal{A} .

The approximation map

The expectation value functors project a probability space onto another one with a possibly coarser σ -algebra.

Given an AMP on (X, p) and a map $\alpha : (X, p) \rightarrow (Y, q)$ in \mathbf{Rad}_∞ , we have the following approximation scheme:

Approximation scheme

$$\begin{array}{ccc} L_\infty^+(X, p) & \xrightarrow{\tau_a} & L_\infty^+(X, p) \\ P_\infty(\alpha) \uparrow & & \mathbb{E}_\infty(\alpha) \downarrow \\ L_\infty^+(Y, q) & \xrightarrow{\alpha(\tau_a)} & L_\infty^+(Y, q) \end{array}$$

A special case

- Take (X, Σ) and (X, Λ) with $\lambda \subset \Sigma$ and use the measurable function $id : (X, \Sigma) \rightarrow (X, \Lambda)$ as α .

Coarsening the σ -algebra

$$\begin{array}{ccc} L_{\infty}^{+}(X, \Sigma, p) & \xrightarrow{\tau_a} & L_{\infty}^{+}(X, \Sigma, p) \\ P_{\infty}(\alpha) \uparrow & & \mathbb{E}_{\infty}(\alpha) \downarrow \\ L_{\infty}^{+}(X, \Lambda, p) & \xrightarrow{id(\tau_a)} & L_{\infty}^{+}(X, \Lambda, p) \end{array}$$

- Thus $id(\tau_a)$ is the approximation of τ_a obtained by averaging over the sets of the coarser σ -algebra Λ .
- We now have the machinery to consider approximating along arbitrary maps α .

- The special case on the previous slide can also be done for the L_1 situation, we get the map $\mathbb{E}_1(id) : L_1^+(X, \Sigma, p) \rightarrow L_1^+(X, \Lambda, p)$.
- This is exactly the map that is written as $\mathbb{E}(\cdot|\Lambda)$ in probability theory books.
- The tower law is written $\mathbb{E}[\mathbb{E}[X|\Lambda_2]|\Lambda_1] = \mathbb{E}[X|\Lambda_1]$ where $\Lambda_1 \subset \Lambda_2$ and is given a half-page proof.
- But this is just functoriality!