Efficient normalization by evaluation

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15 August 2009







The conversion test

$$\frac{\Gamma \vdash A : s \qquad \Gamma \vdash B : s \qquad \Gamma \vdash t : A}{\Gamma \vdash t : B} A \equiv_{\beta} B$$

The conversion test

$$\frac{\Gamma \vdash A : s}{\Gamma \vdash t : B} \xrightarrow{\Gamma \vdash t : A} A \equiv_{\beta} B$$

A simple algorithm:

- 1. Reduce A and B to their canonical forms.
- 2. Compare canonical forms.

fast

fast cheap

fast cheap general

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- Solution: reuse them!

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- Advantage: separation of concerns.

Eval vm_compute in fib 30.

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B. Grégoire and X. Leroy, "A compiled implementation of strong reduction," Proceedings ICFP'02, 2002.

Extended Terms:

$$b ::= x \mid \lambda x. \ b \mid b_1 \ b_2 \mid [\tilde{x} \ v_1 \ \dots \ v_n]$$
$$v ::= \lambda x. \ b \mid [\tilde{x} \ v_1 \ \dots \ v_n]$$

Symbolic weak reduction:

$$(\lambda x. b) v \to b[x := v]$$
$$[x v_1 \dots v_n] v \to [x v_1 \dots v_n v]$$
$$\Gamma_v(a) \to \Gamma_v(a') \quad \text{if } a \to a'$$

with $\Gamma_v ::= [v \mid b[].$

$$\mathcal{N}(b) = \mathcal{R}(\mathcal{V}(b)) \tag{1}$$
$$\mathcal{R}(\lambda x. b) = \lambda y. \mathcal{N}((\lambda x. b) [\tilde{y}]) \tag{2}$$
$$\mathcal{R}([\tilde{x} \ v_1 \dots \ v_n]) = x \ \mathcal{R}(v_1) \ \dots \ \mathcal{R}(v_n) \tag{3}$$

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Objective: be cheap, not just semi-cheap.

Normalization by Evaluation

Optimizations

Uncurrying Embedding pattern matching

Benchmarks

Conclusion

data Code = Con String| $Lam (Code \rightarrow Code)$ | Neu Code Code

Interpretation

$$\begin{bmatrix} \underline{x} \end{bmatrix} n = \hat{x} & \text{if } x < n \\ \begin{bmatrix} \underline{x} \end{bmatrix} n = Con \underline{x} & \text{otherwise} \\ \begin{bmatrix} \underline{\lambda}. t \end{bmatrix} n = Abs (\lambda \hat{n} \to \llbracket t \rrbracket (n+1)) \\ \begin{bmatrix} \underline{t_1} t_2 \end{bmatrix} n = app (\llbracket t_1 \rrbracket n) (\llbracket t_2 \rrbracket n)$$

 $app (Abs t_1) t_2 = t_1 t_2$ $app t_1 t_2 = Neu t_1 t_2$

Interpretation

$$\begin{split} \llbracket \underline{x} \rrbracket & n = \hat{x} & \text{if } x < n \\ \llbracket \underline{x} \rrbracket & n = Con \underline{x} & \text{otherwise} \\ \llbracket \underline{\lambda} \underline{t} \rrbracket & n = Abs \ (\lambda \hat{n} \to \llbracket t \rrbracket \ (n+1)) \\ \llbracket \underline{t_1 \ t_2} \rrbracket & n = app \ (\llbracket t_1 \rrbracket \ n) \ (\llbracket t_2 \rrbracket \ n) \end{split}$$

app (Abs
$$t_1$$
) $t_2 = t_1 \ t_2$
app (Con x) $t_2 = Neu$ (Con x) t_2
app (Neu $t_1 \ t_1'$) $t_2 = Neu$ (Neu $t_1 \ t_1'$) t_2



$\llbracket (\lambda x. (\lambda y. y x)) z \rrbracket$



$\llbracket (\lambda x. (\lambda y. y x)) z \rrbracket$

 $app (Abs (\lambda x \rightarrow Abs (\lambda y \rightarrow app y x))) (Con "0")$

Algorithm

norm n (Con c) =
$$\underline{c}$$

norm n (Abs t) = $\underline{\lambda}$. (norm (n + 1) (t (Con \hat{n})))
norm n (Neu $t_1 t_2$) = (norm n t_1) @ (norm n t_2)

Eval/Apply

$$\begin{bmatrix} x \end{bmatrix} n = \hat{x} & \text{if } x < n \\ \begin{bmatrix} x \end{bmatrix} n = \operatorname{Con} \underline{x} & \text{otherwise} \\ \end{bmatrix} \underbrace{\left[\underline{\lambda} \dots \cdot \underline{\lambda} \dots t \right]}_{n} n = \operatorname{Abs}_{m} (\lambda \hat{n} \dots \widehat{n+m} \to \llbracket t \rrbracket (n+m)) \\ \begin{bmatrix} \underline{t_{1}} \dots t_{m} \end{bmatrix} n = \operatorname{ap}_{m} (\llbracket t_{1} \rrbracket n) \dots (\llbracket t_{m} \rrbracket n)$$

A family of ap operators 1. $ap_n (Abs_m f) t_1 \dots t_n =$ $Abs_{m-n} (f t_1 \dots t_n)$ 2. $ap_n (Abs_m f) t_1 \dots t_n = f t_1 \dots t_n$ 3. $ap_n (Abs_m f) t_1 \dots t_n =$ $ap_{n-m} (f t_1 \dots t_m) t_{m+1} \dots t_n$ Condition on (1): n < mCondition on (2): n = mCondition on (3): n > m.

Eval/Apply: Remarks

- Drastically reduces number of intermediate closures constructed in the common case.
- ▶ No help in pathological cases. But they are rare.
- Only need (small) finite number of ap operators.

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Idea: Extend model with constructors for all constructors in all datatypes introduced in the object language.

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Idea: Extend model with constructors for all constructors in all datatypes introduced in the object language. \rightarrow Space and time efficient representation of data.



fast cheap general

fast √ cheap general

fast \checkmark cheap \checkmark general

$\mathsf{fast} \checkmark \qquad \mathsf{cheap} \checkmark \qquad \mathsf{general} \checkmark$

Final words

Limitations:

- Fixed evaluation order
- Potential impedance mismatch between object-level pattern matching and meta-level pattern matching.

Future work:

- COQ integration
- Short-circuit evaluation.