

# From Skyrim to Metal Gear Solid - A buddy AI journey

**Jonathan Tremblay**





Player



Companion





Combat: targeting an enemy

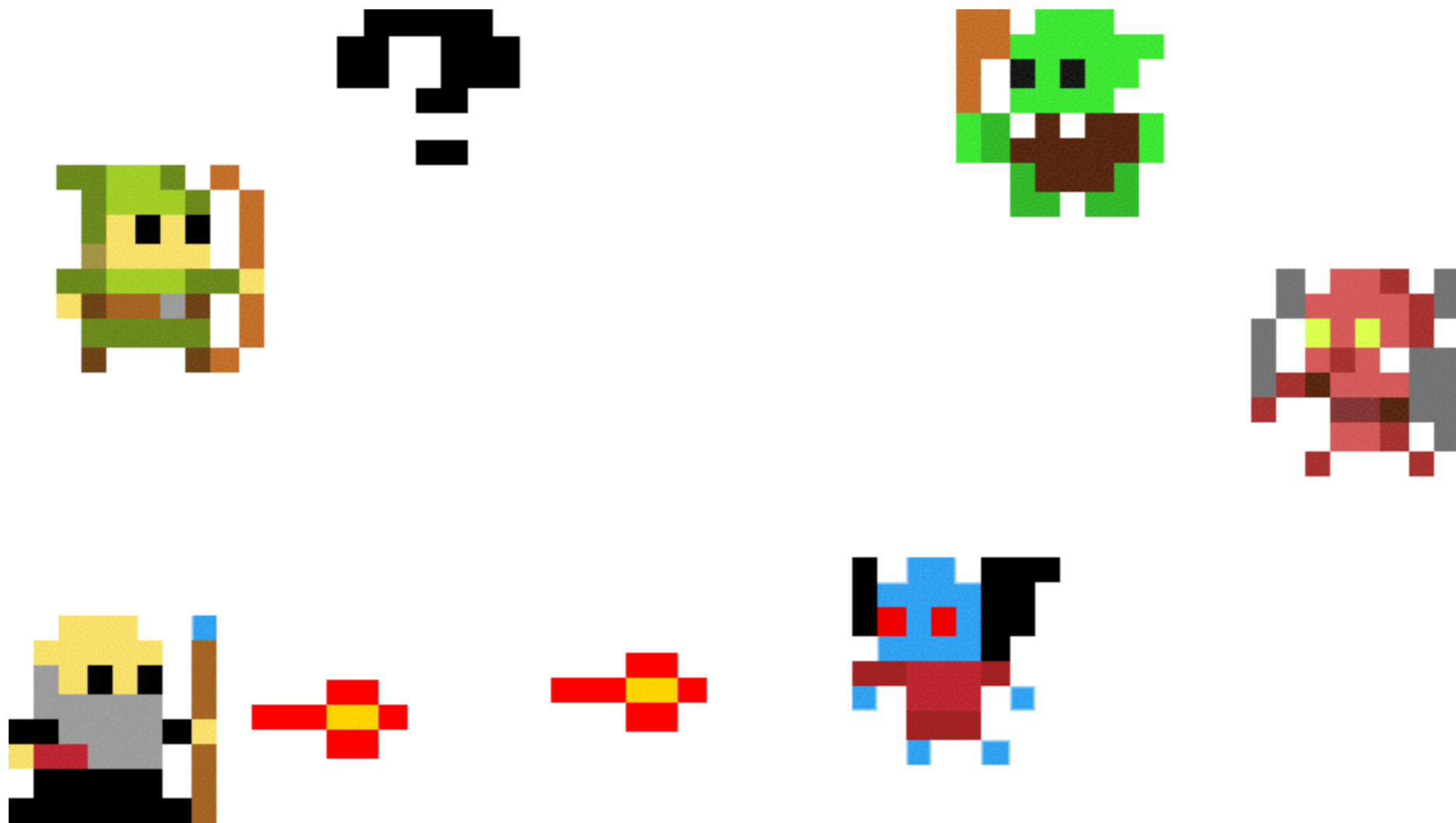


Stealth movement

Understanding player



# Targeting problem

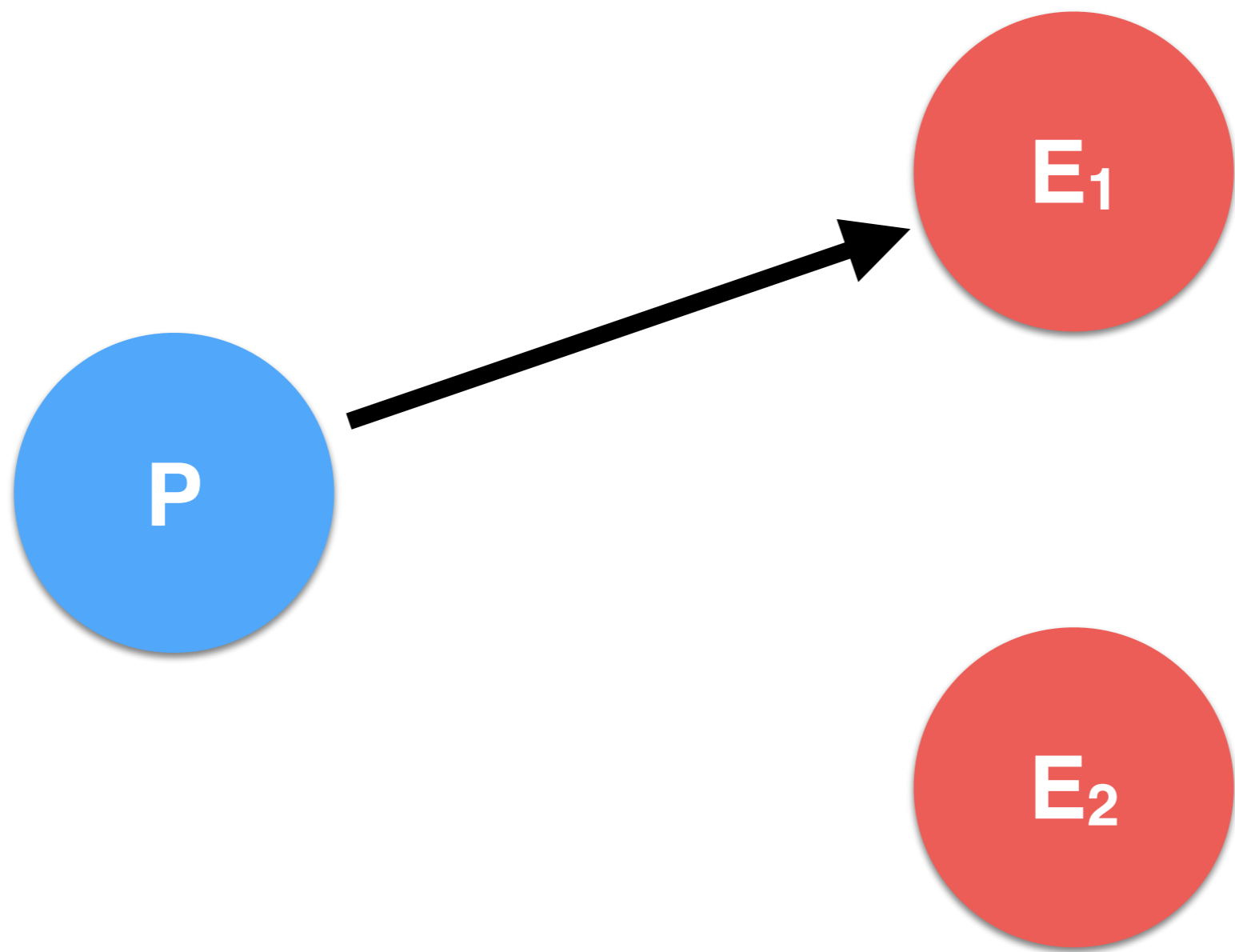


# Companions' influence

- Strategies are poor
- Player needs to interact with their behaviour
- Player do not trust them









Attack:  $a$   
Health:  $h$

# Rules

- Entities select target to attack
- Blue team attacks first
- Attack value is subtracted from targets' health

# Strategies

- Target randomly
- Target lowest health
- Target highest attack

# Lowest health

$h:12$   
 $a:2$

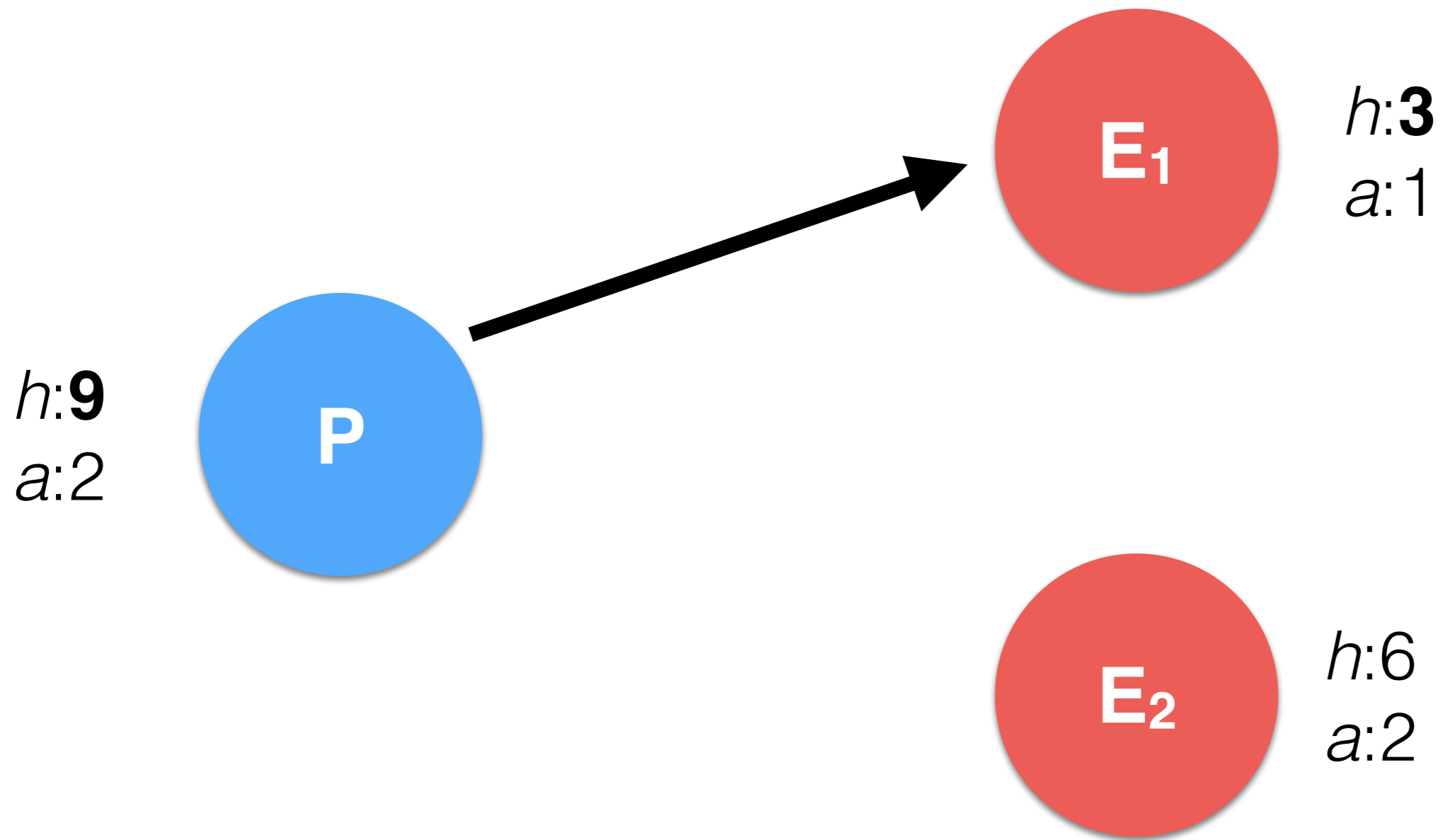


$h:5$   
 $a:1$

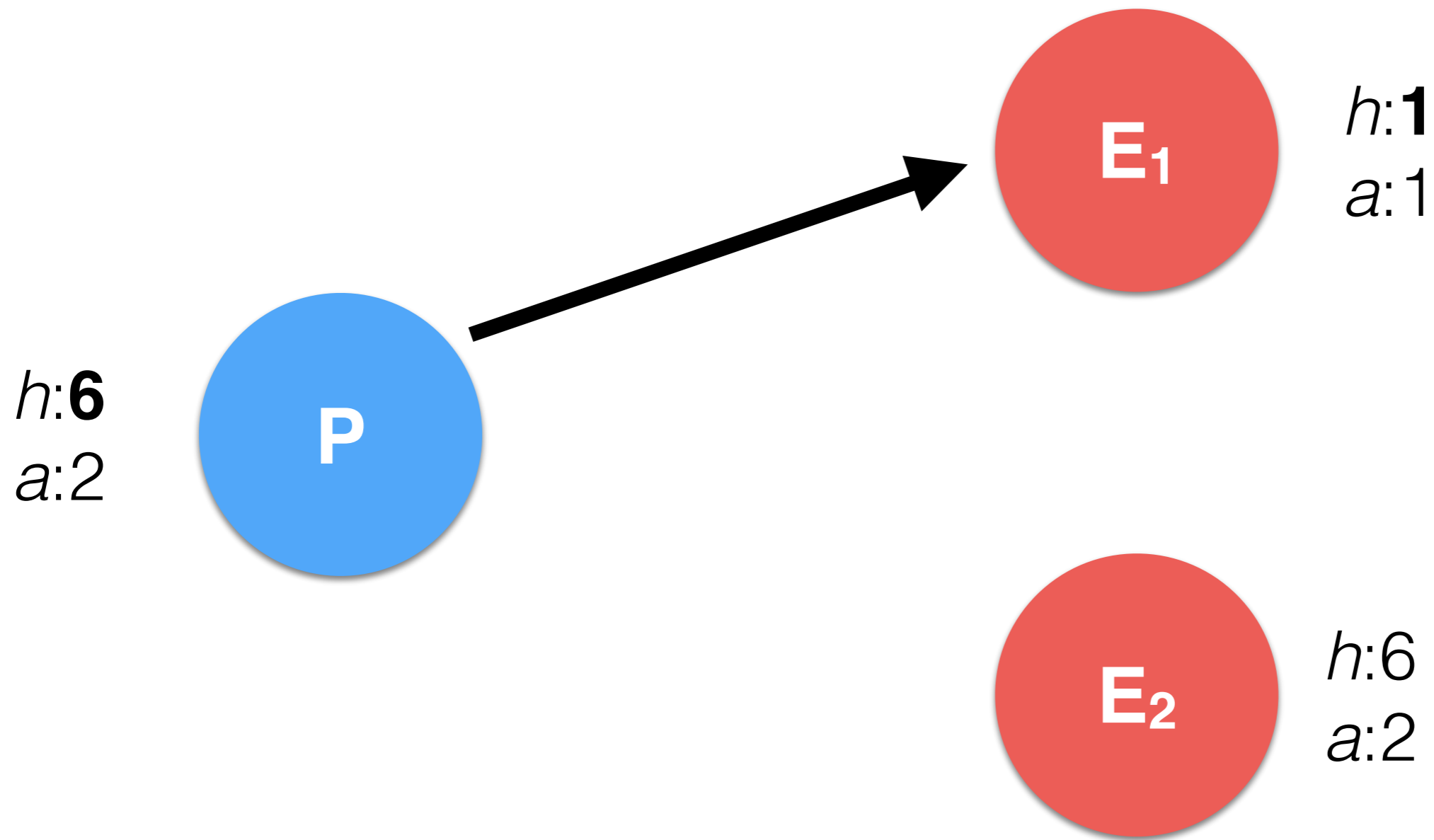


$h:6$   
 $a:2$

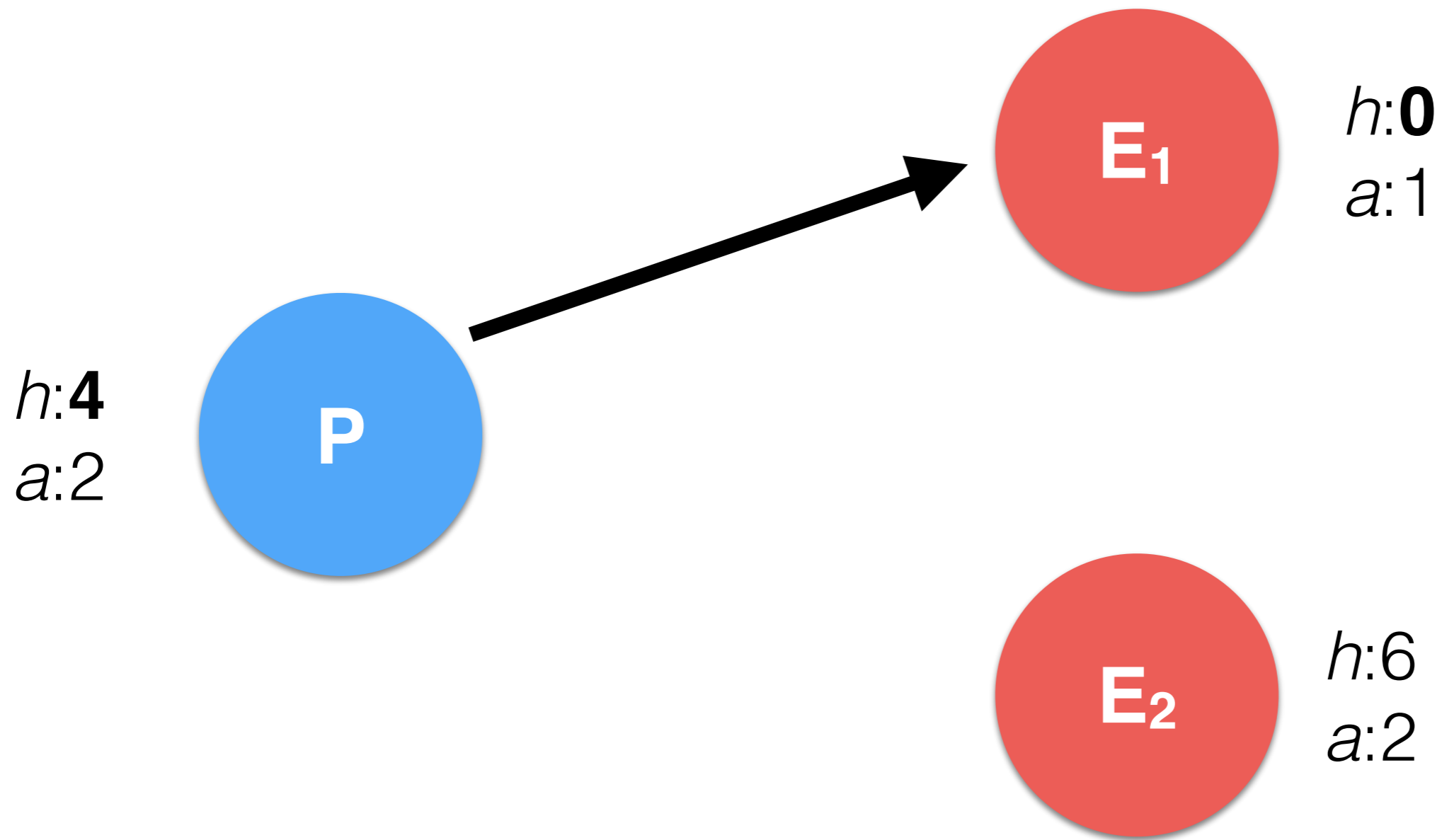
# Lowest health



# Lowest health

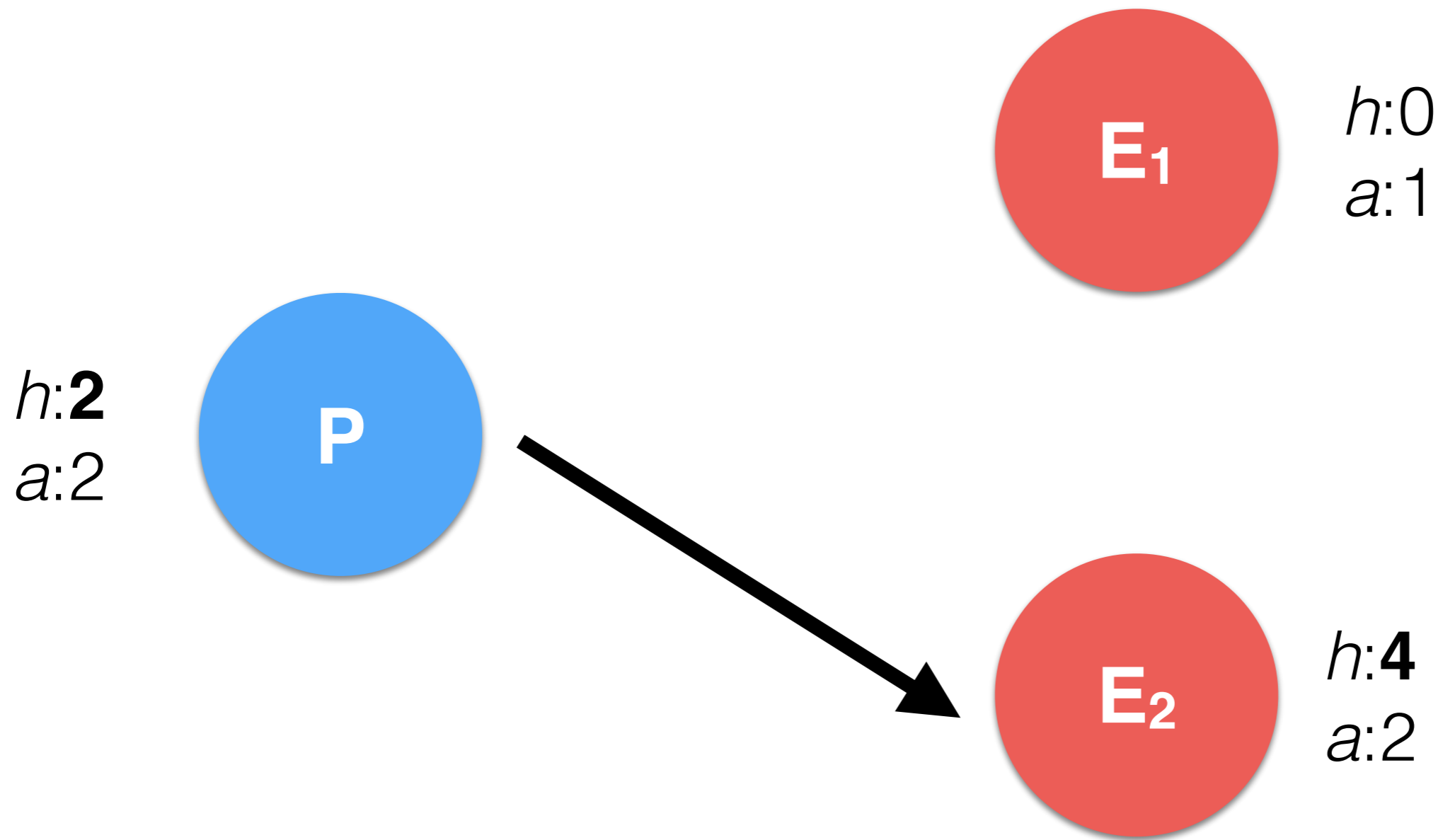


# Lowest health

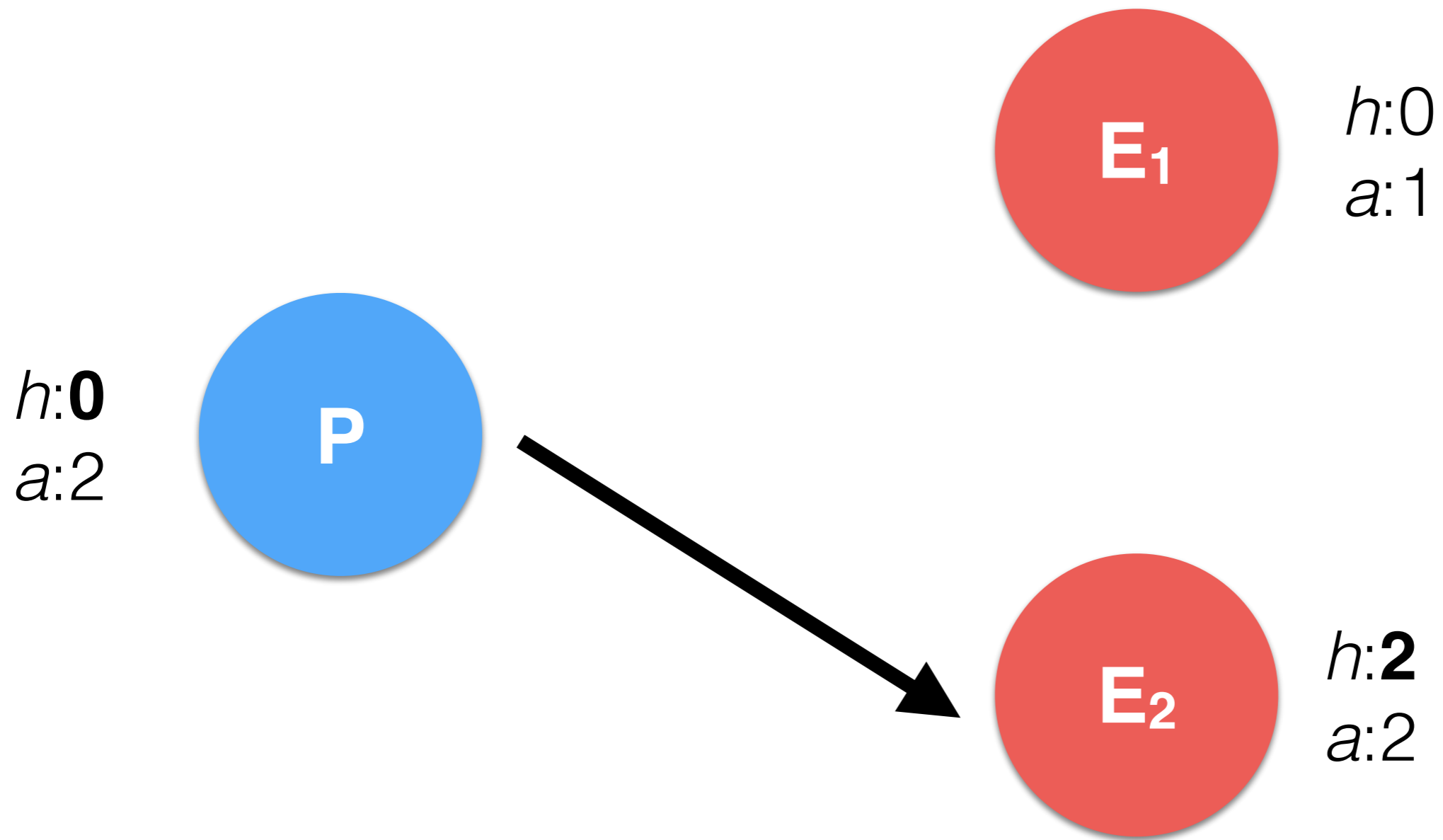




# Lowest health



# Lowest health



# Lowest health

$h:0$   
 $a:2$

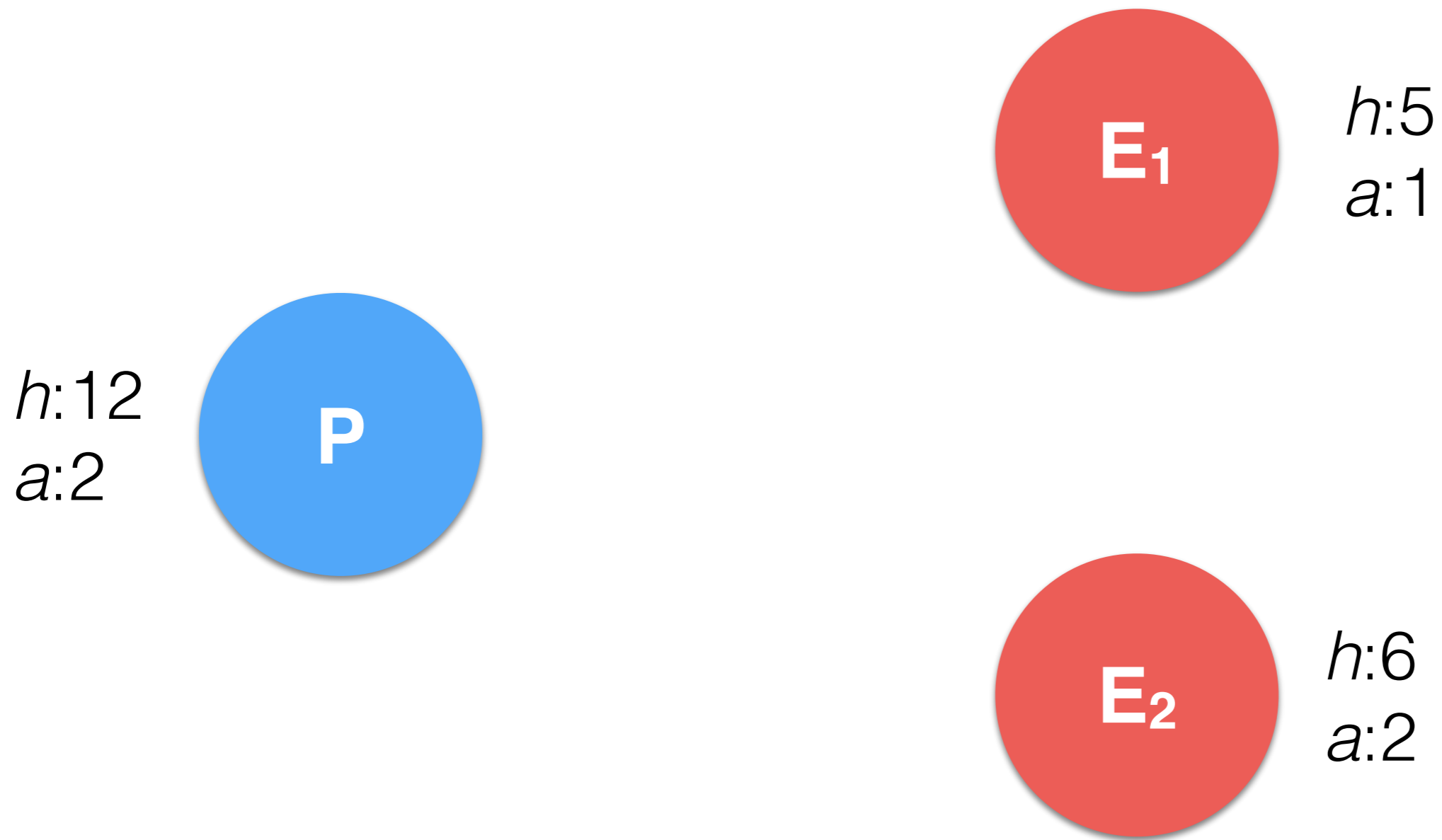


$h:0$   
 $a:1$

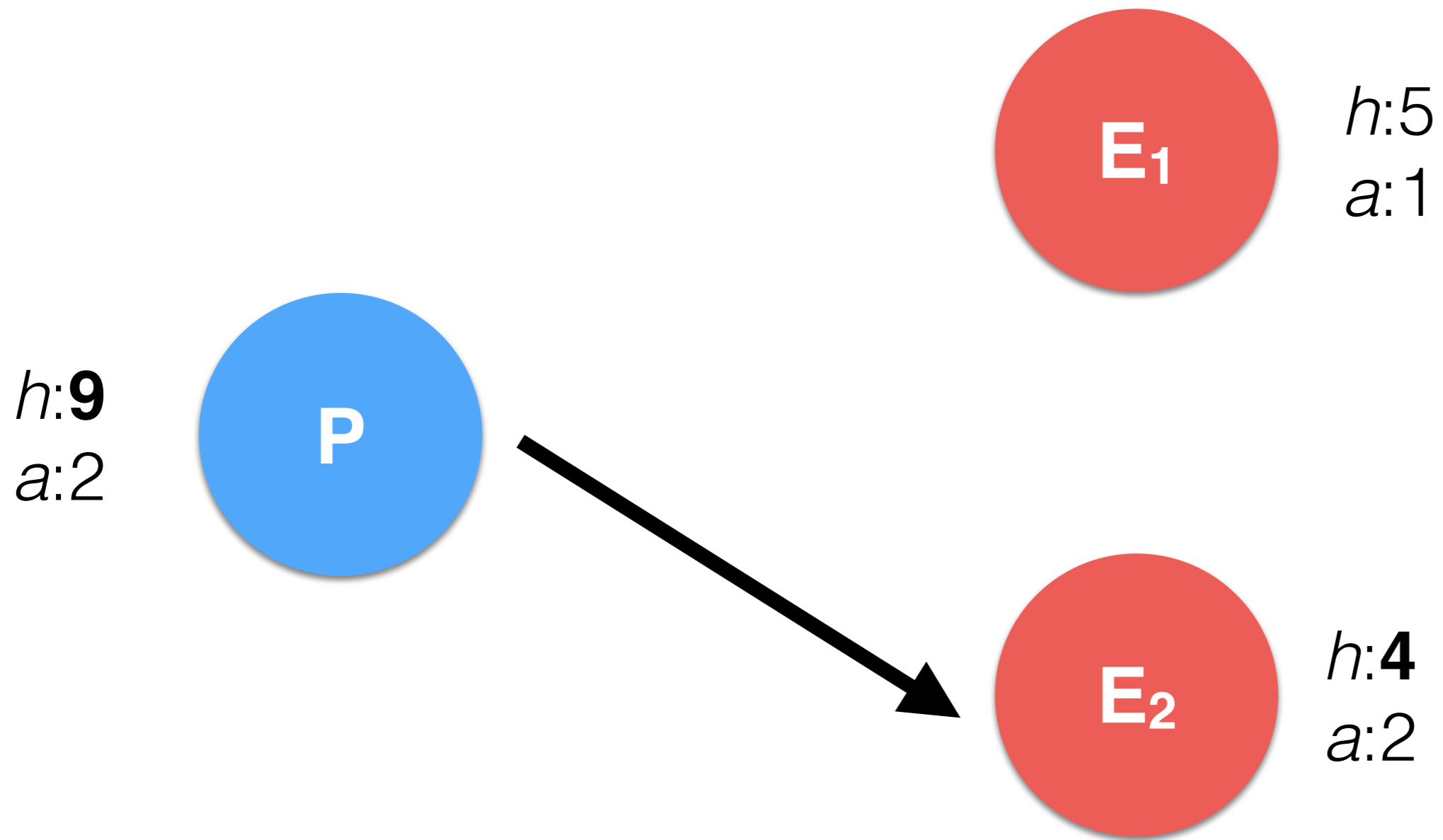


$h:2$   
 $a:2$

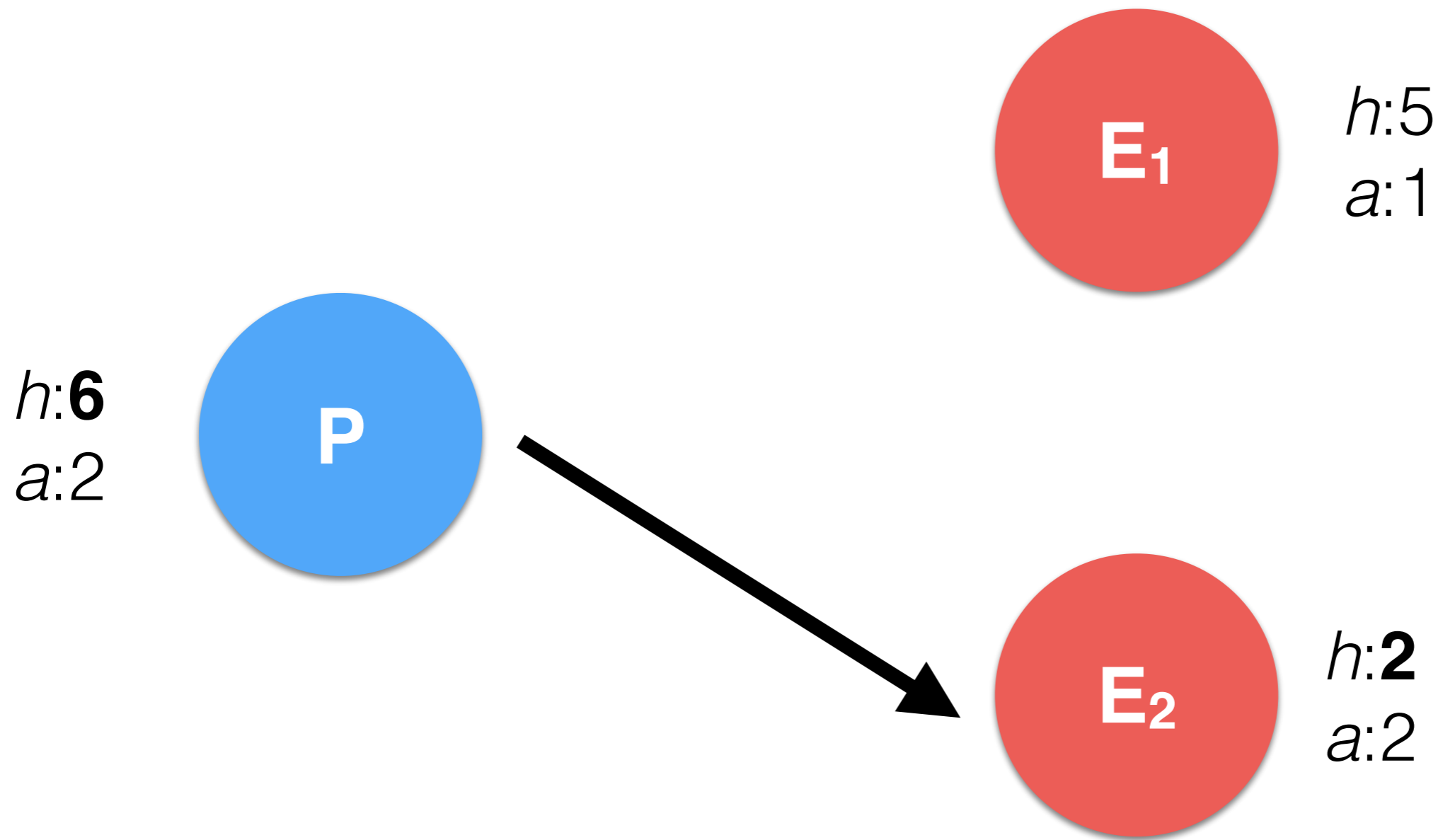
# Highest Attack



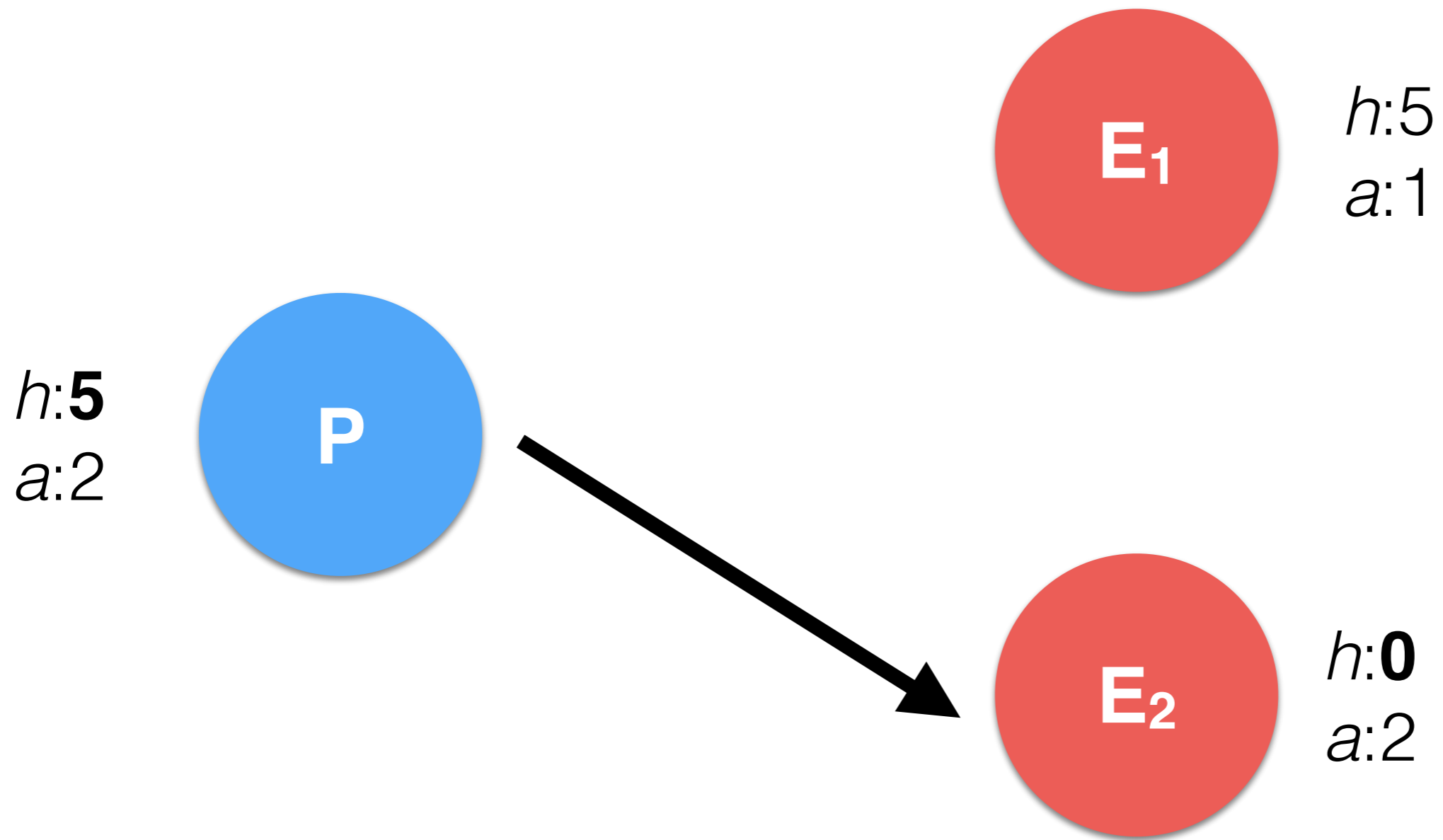
# Highest Attack



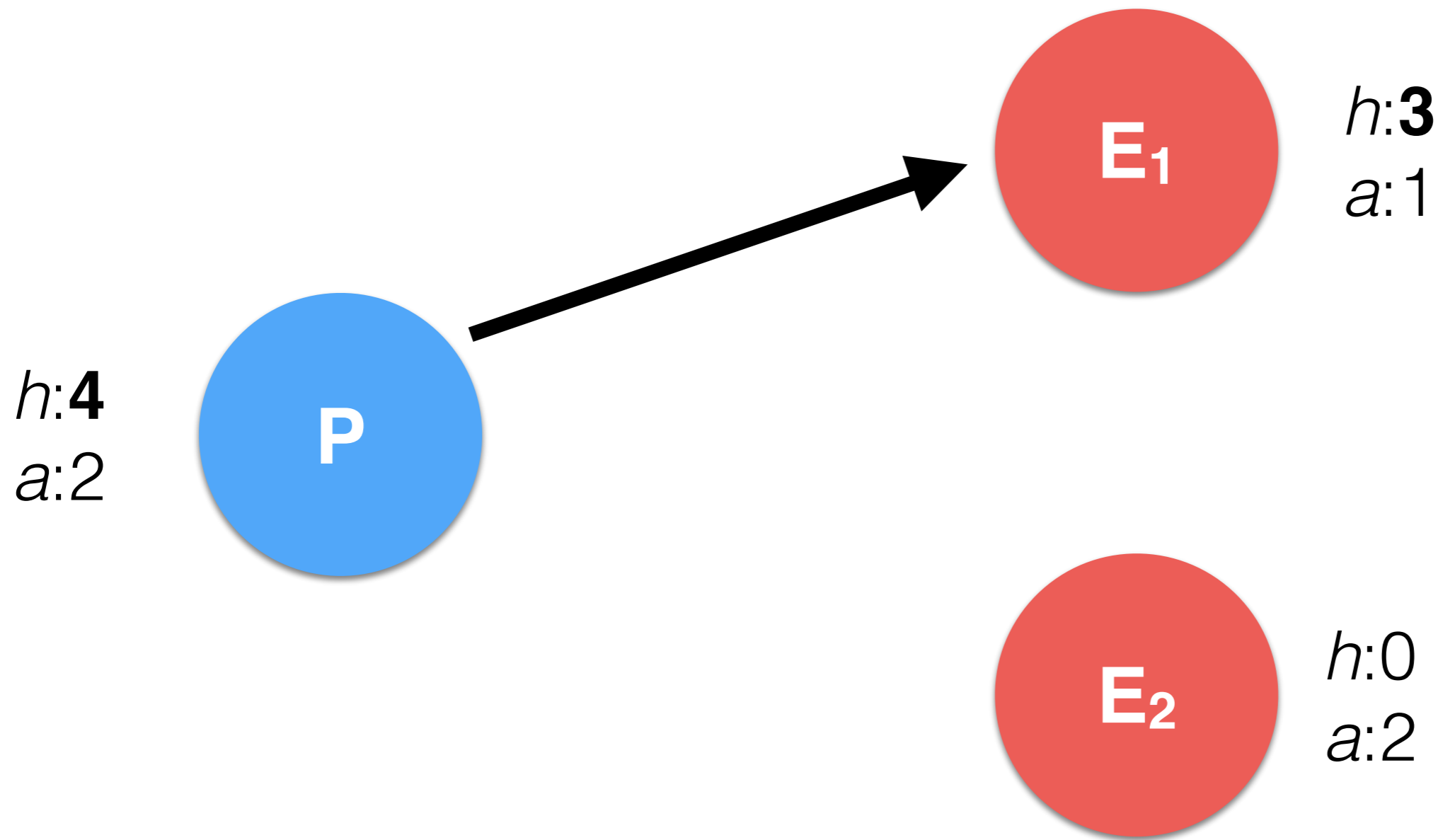
# Highest Attack



# Highest Attack

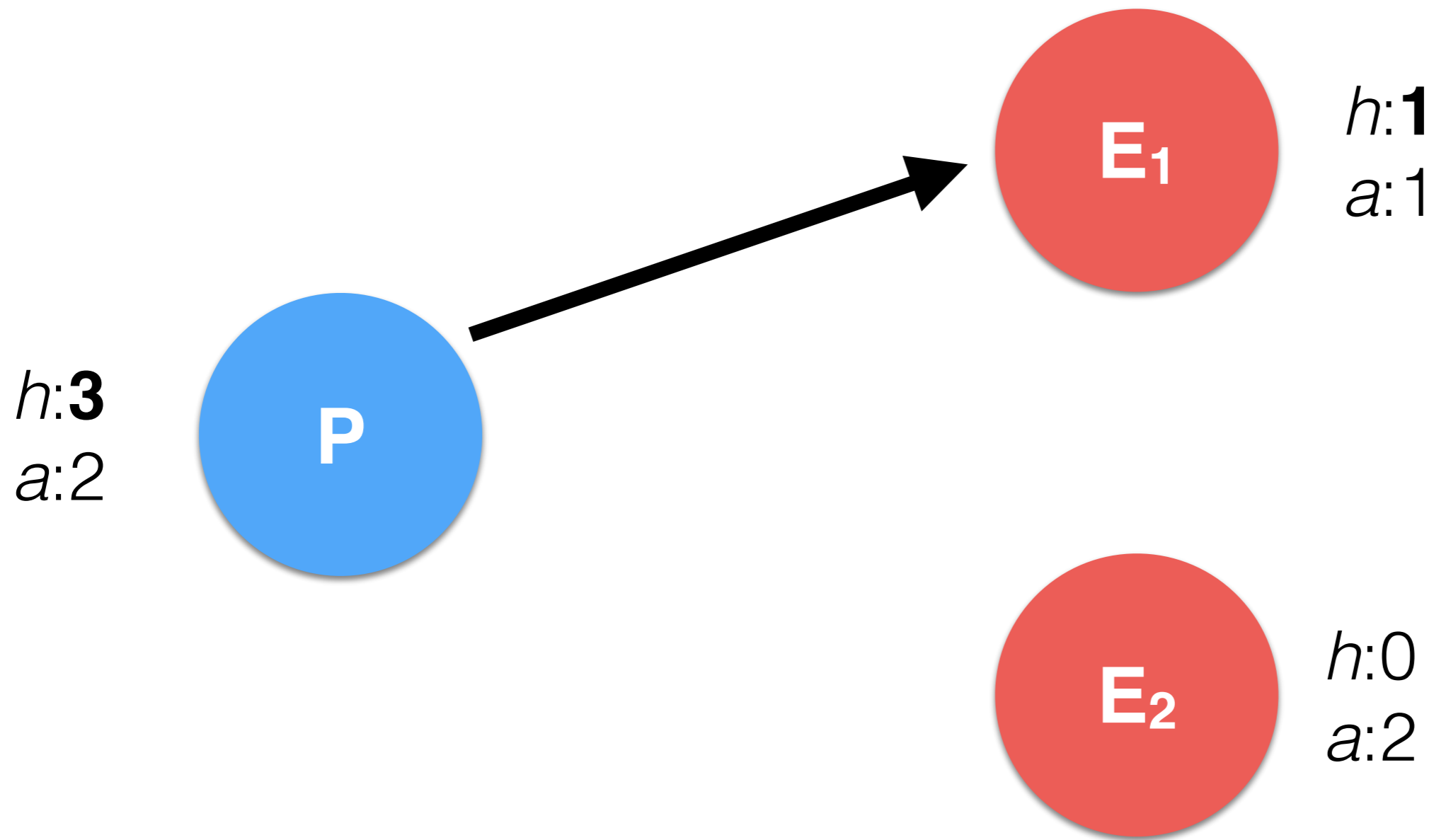


# Highest Attack

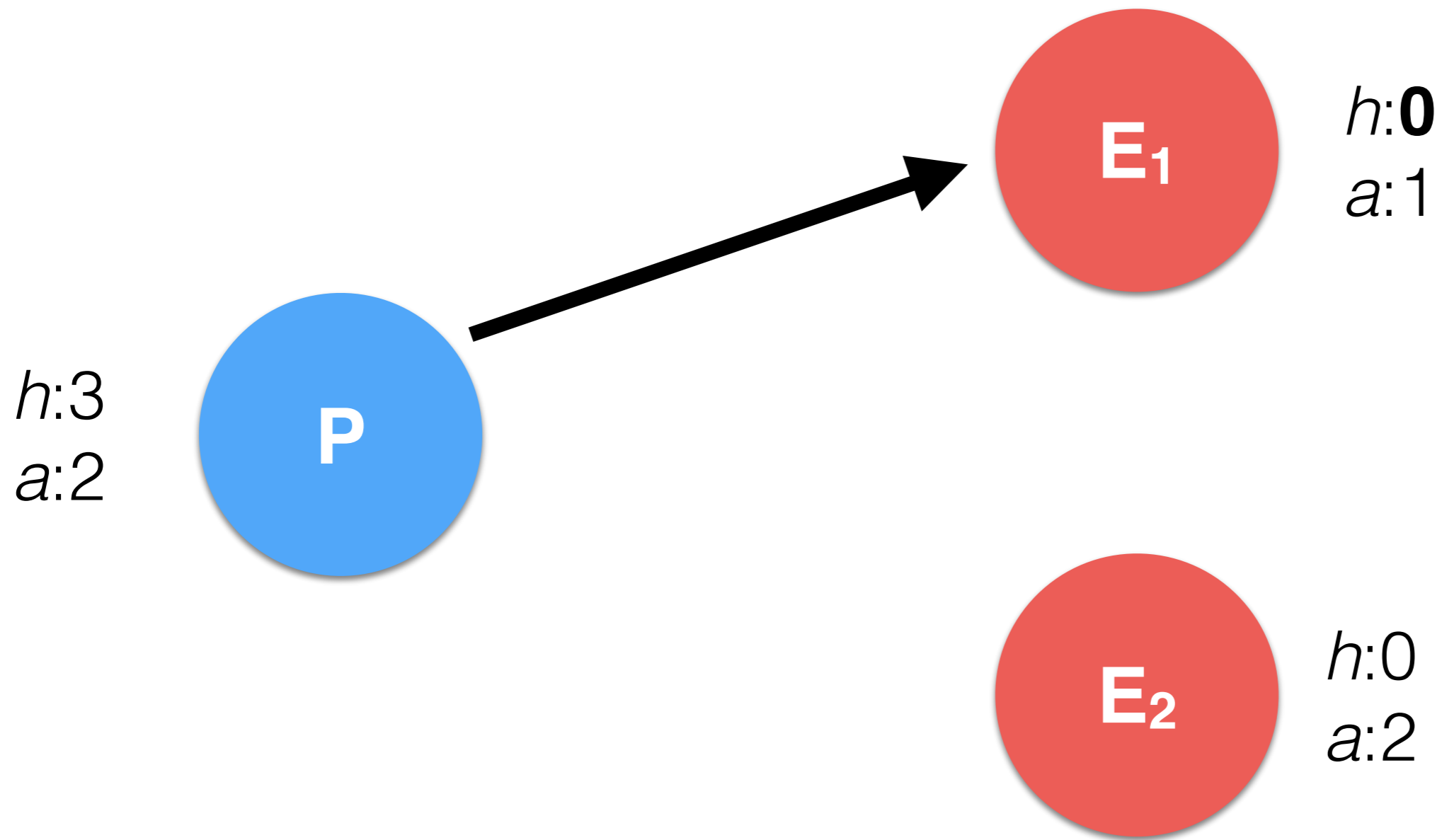




# Highest Attack



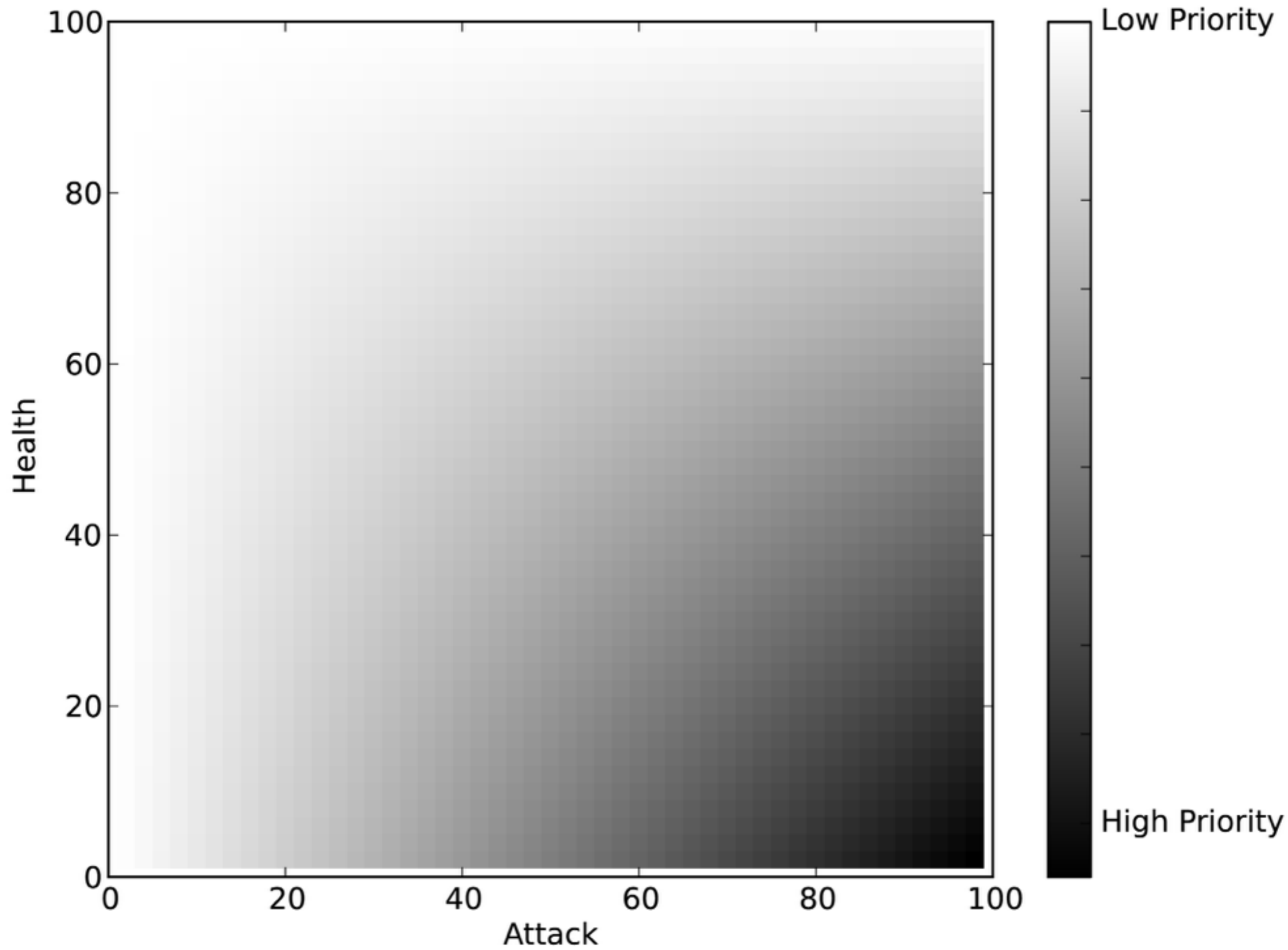
# Highest Attack



PSPACE-Hard [Furtak *et al.*]

# Threat Ordering

- What is the threat of an enemy?
- Attack within respect of health
- The benefit of killing that enemy and not an other one



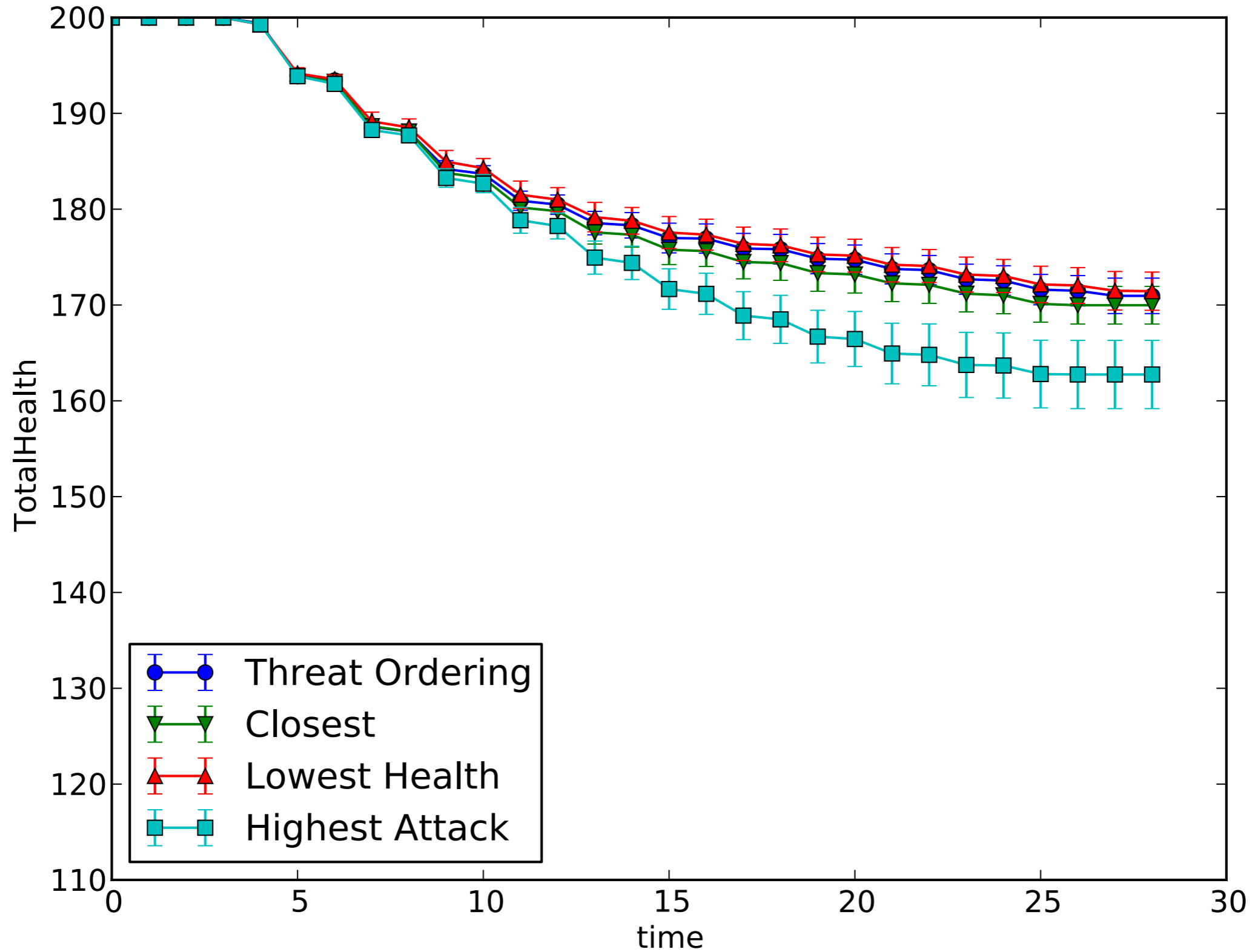
# $M$ enemies vs. $N$ players



# Strategies

- Threat ordering
- Closest
- Highest attack
- Lowest health

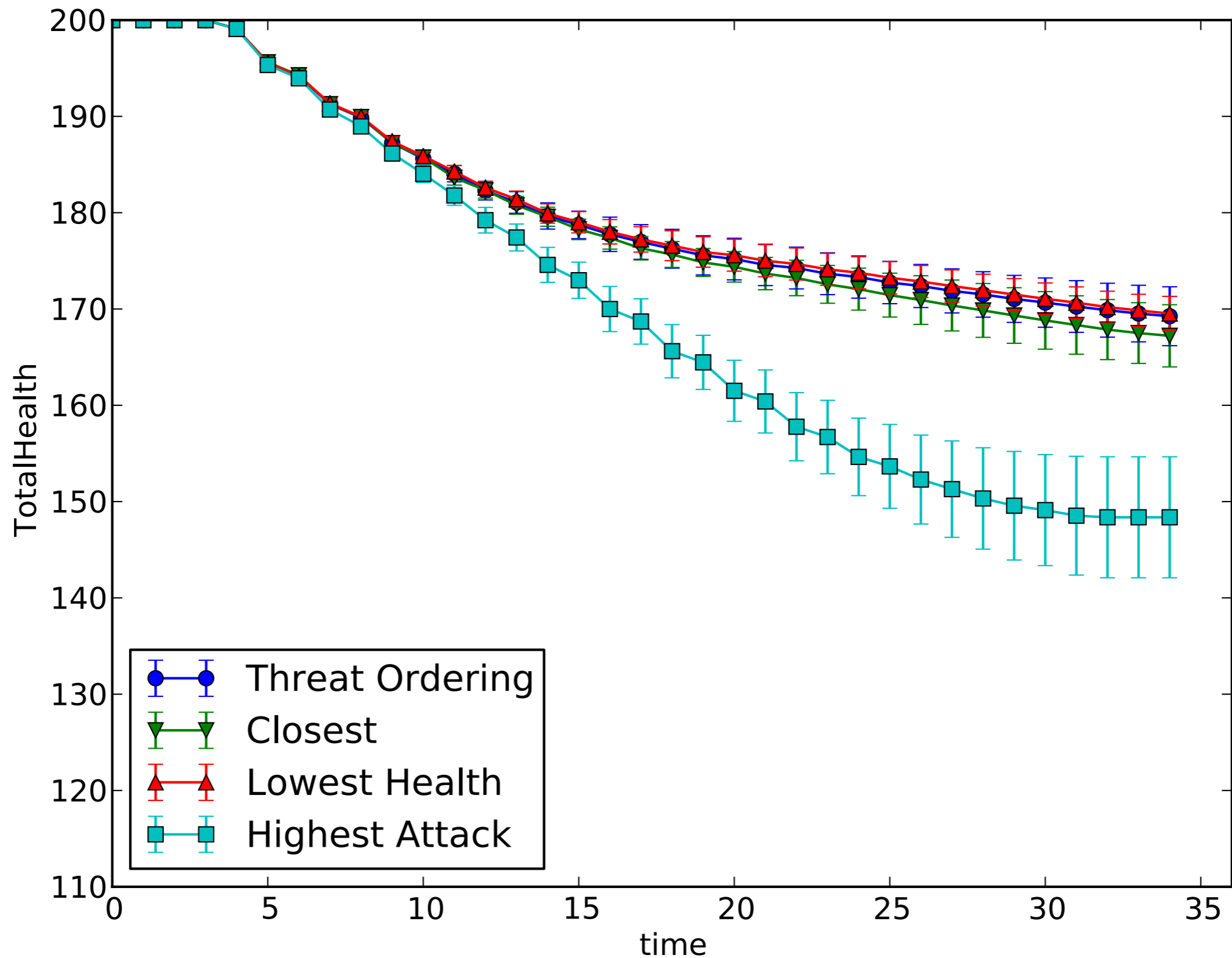
# Tank level



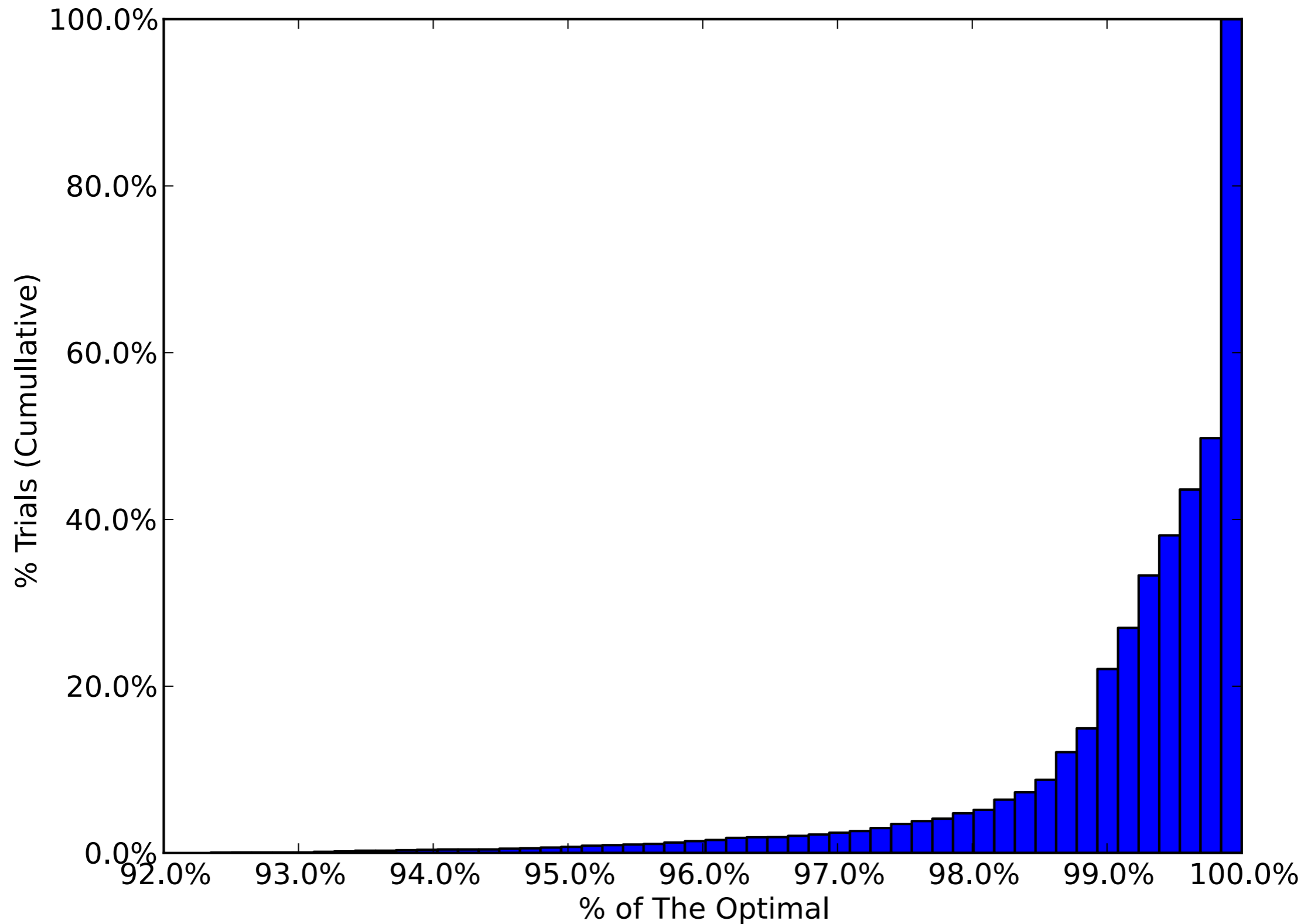


Independent  
*vs.*  
Mimicking

# Tank level - mimic



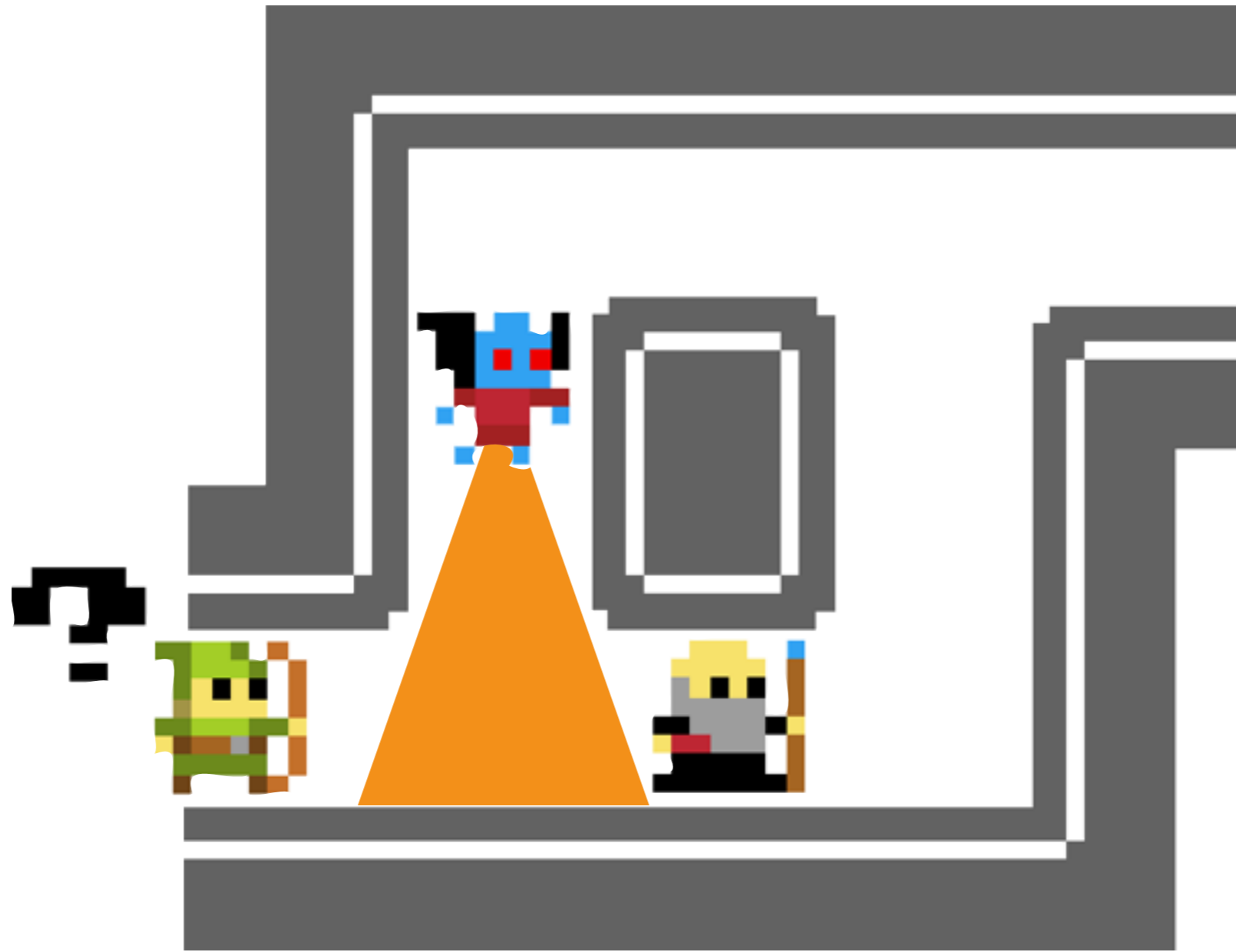
# Heuristic vs. Optimal



# Threat Ordering

- Approximation of a hard problem
- Insights on the cost of bad strategies
- 50% time finds optimal and usually within 1% of the optimal

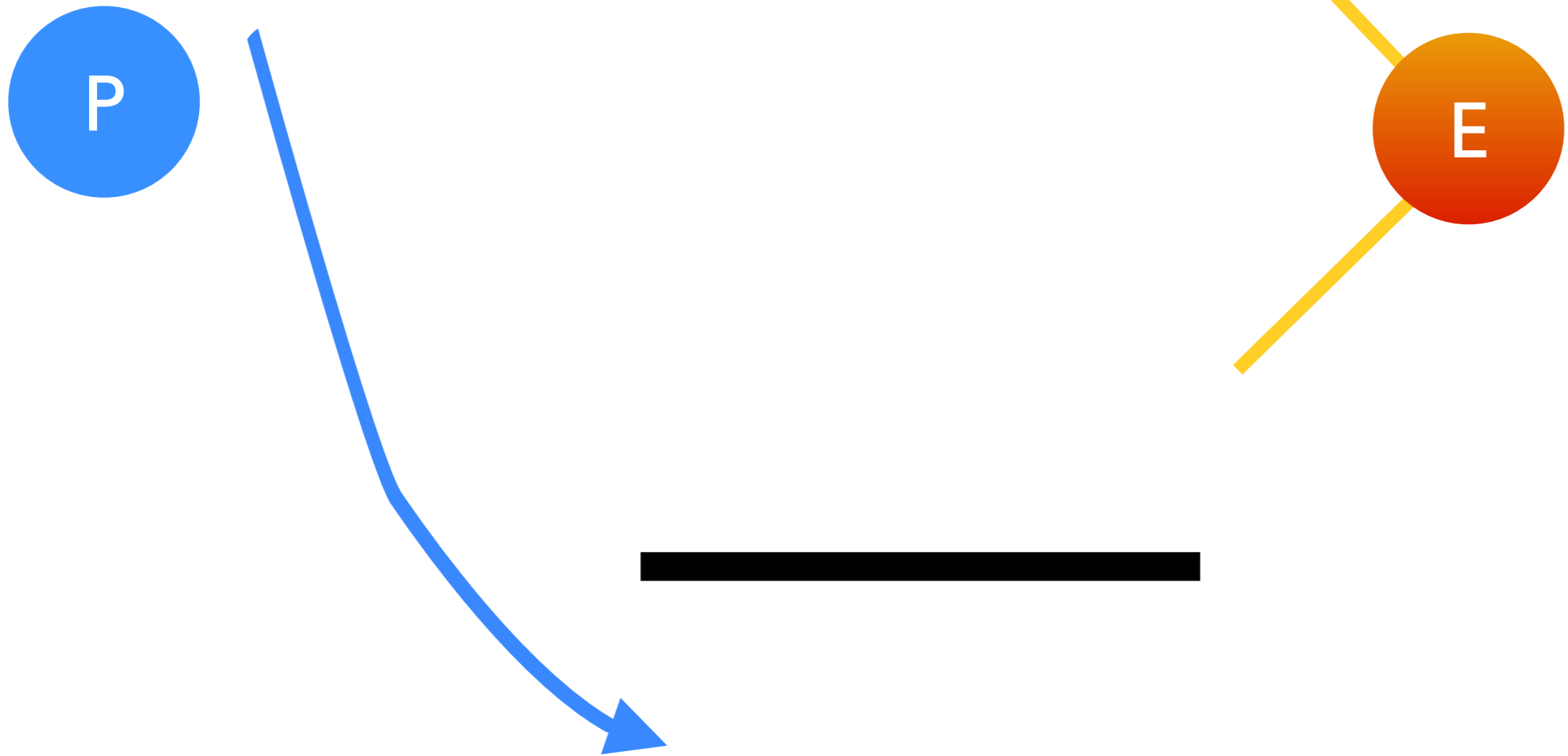
# Stealth movement



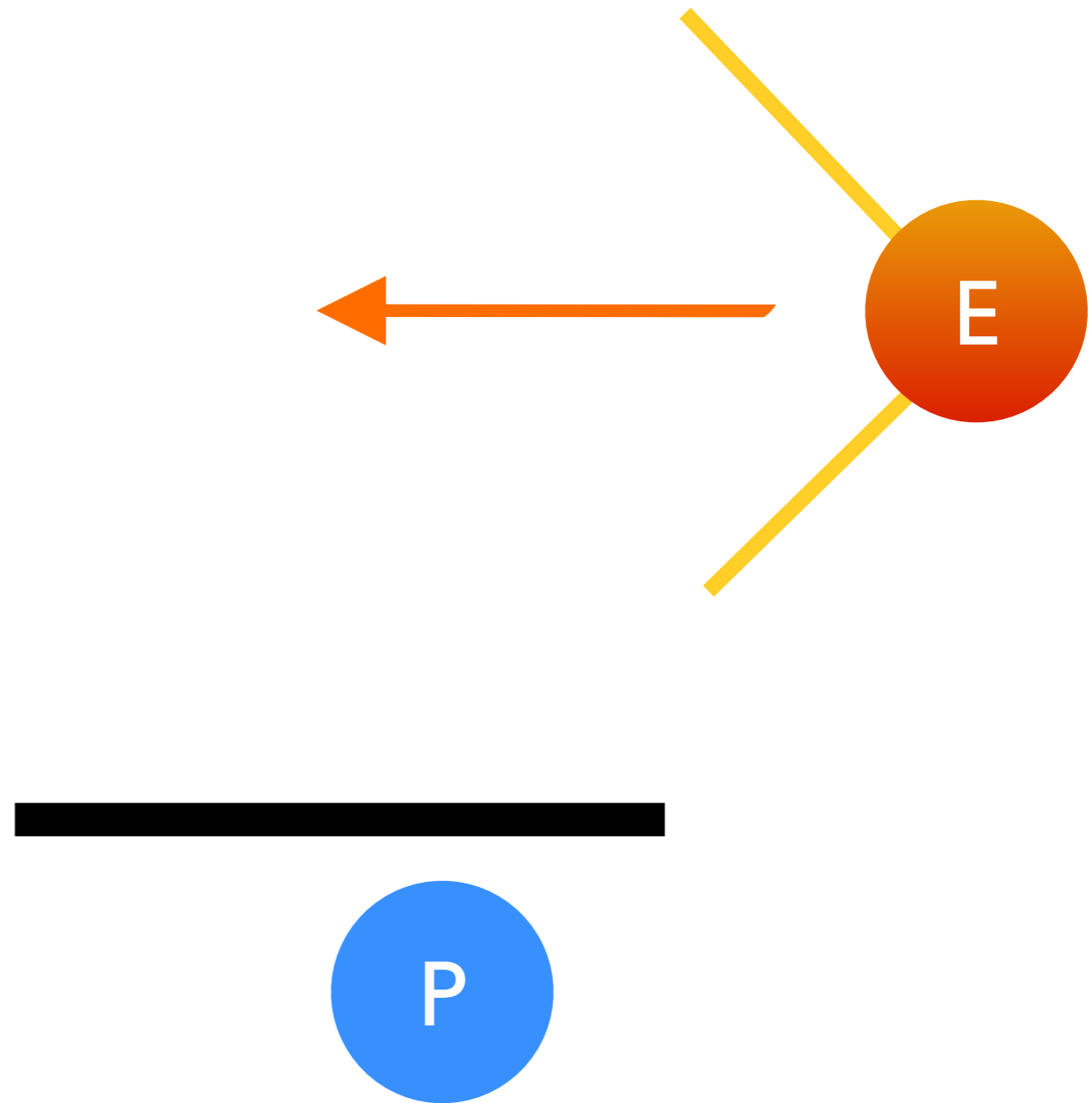
# Sneaking



# Sneaking

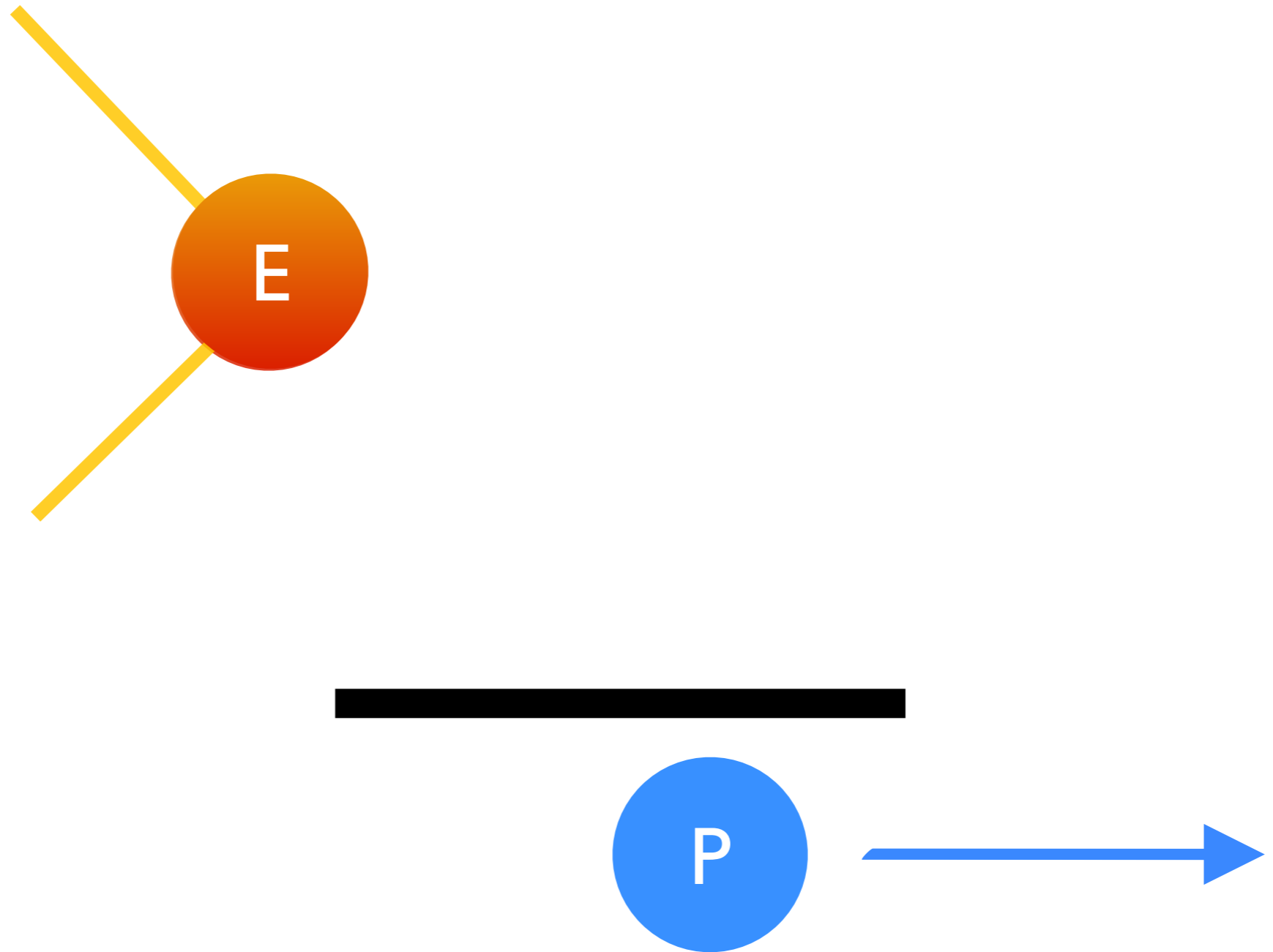


# Sneaking

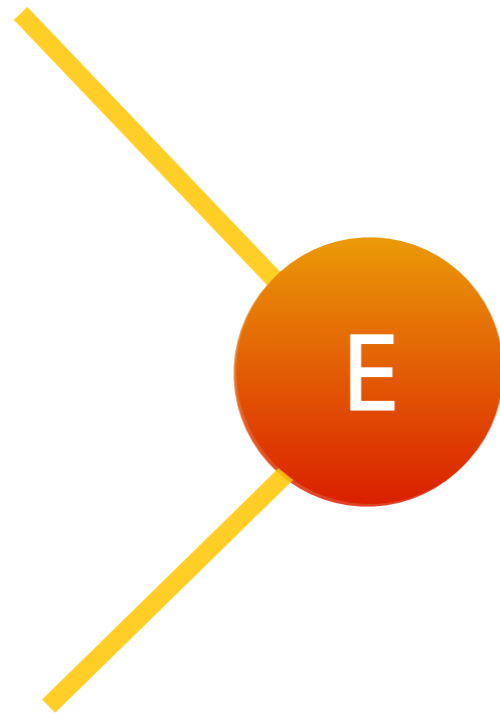




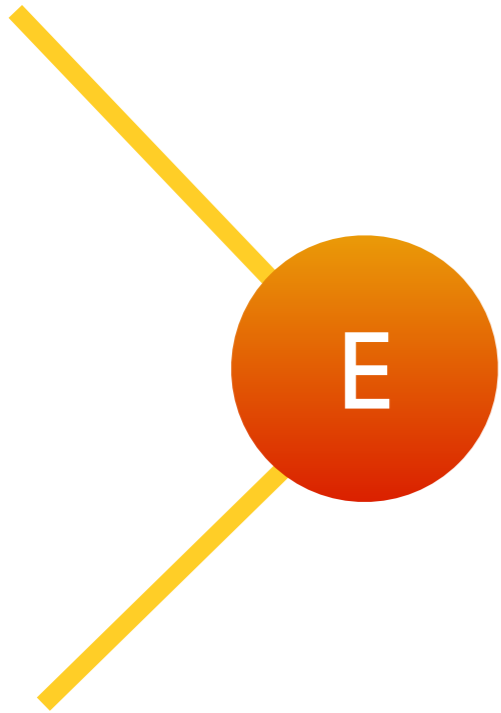
# Sneaking



# Sneaking



Can we compute an  
undetected path  
from A to B?



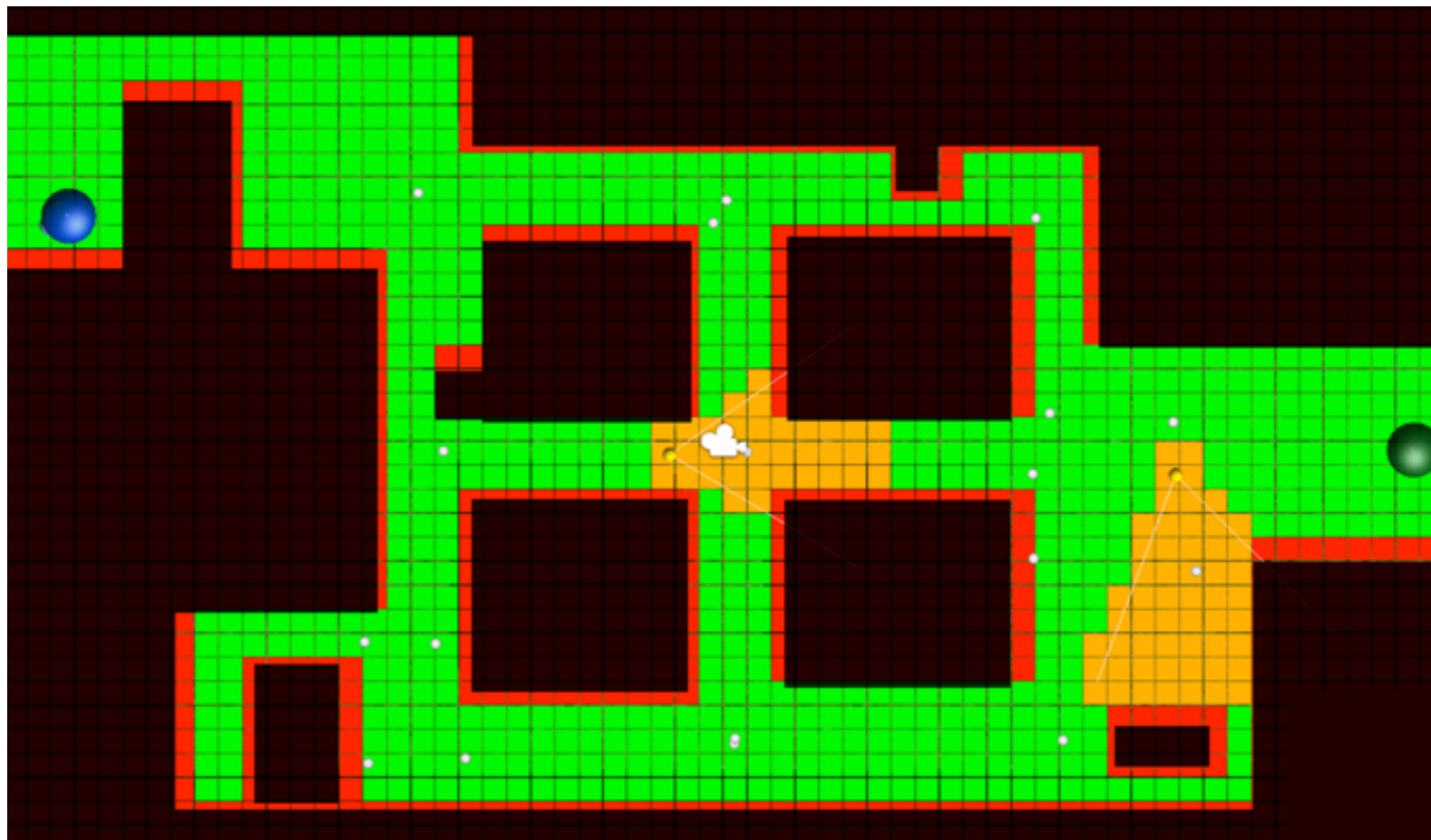
# Assumptions

- Level geometry
- Enemies' deterministic movement
- Cannot be detected
- Initial and goal position

# Overview

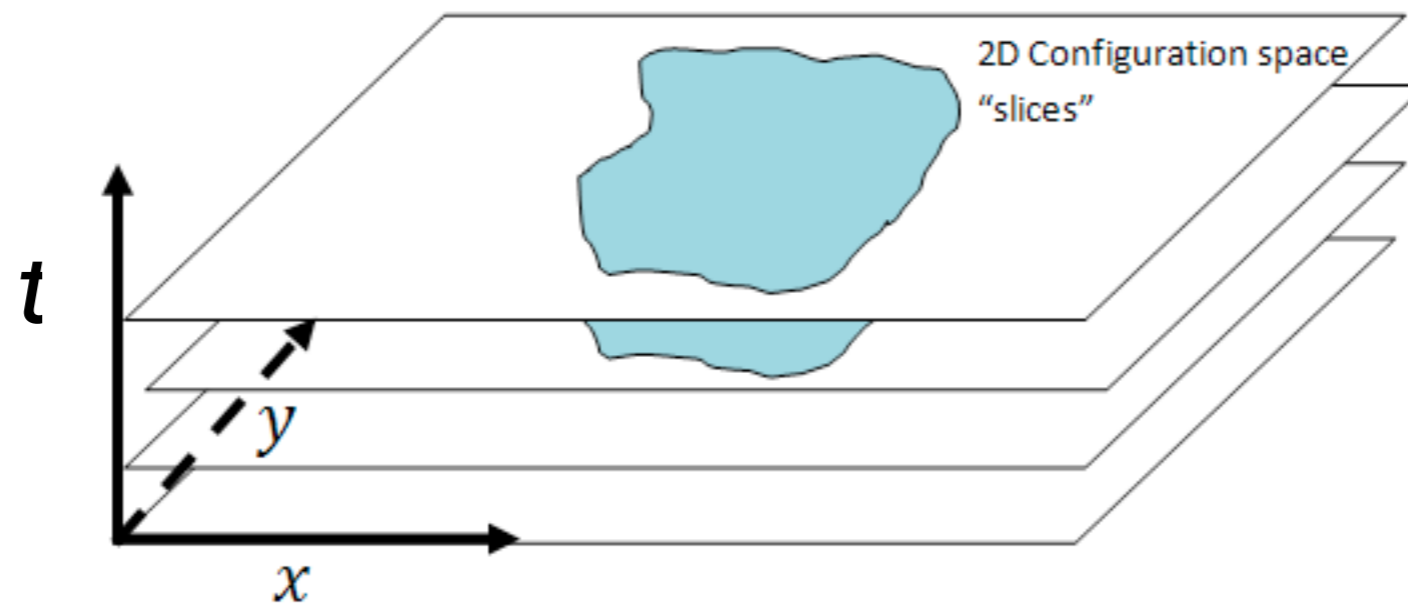
- Defining the state space
- Rapidly exploring Random Tree (RRT)
- Presenting results

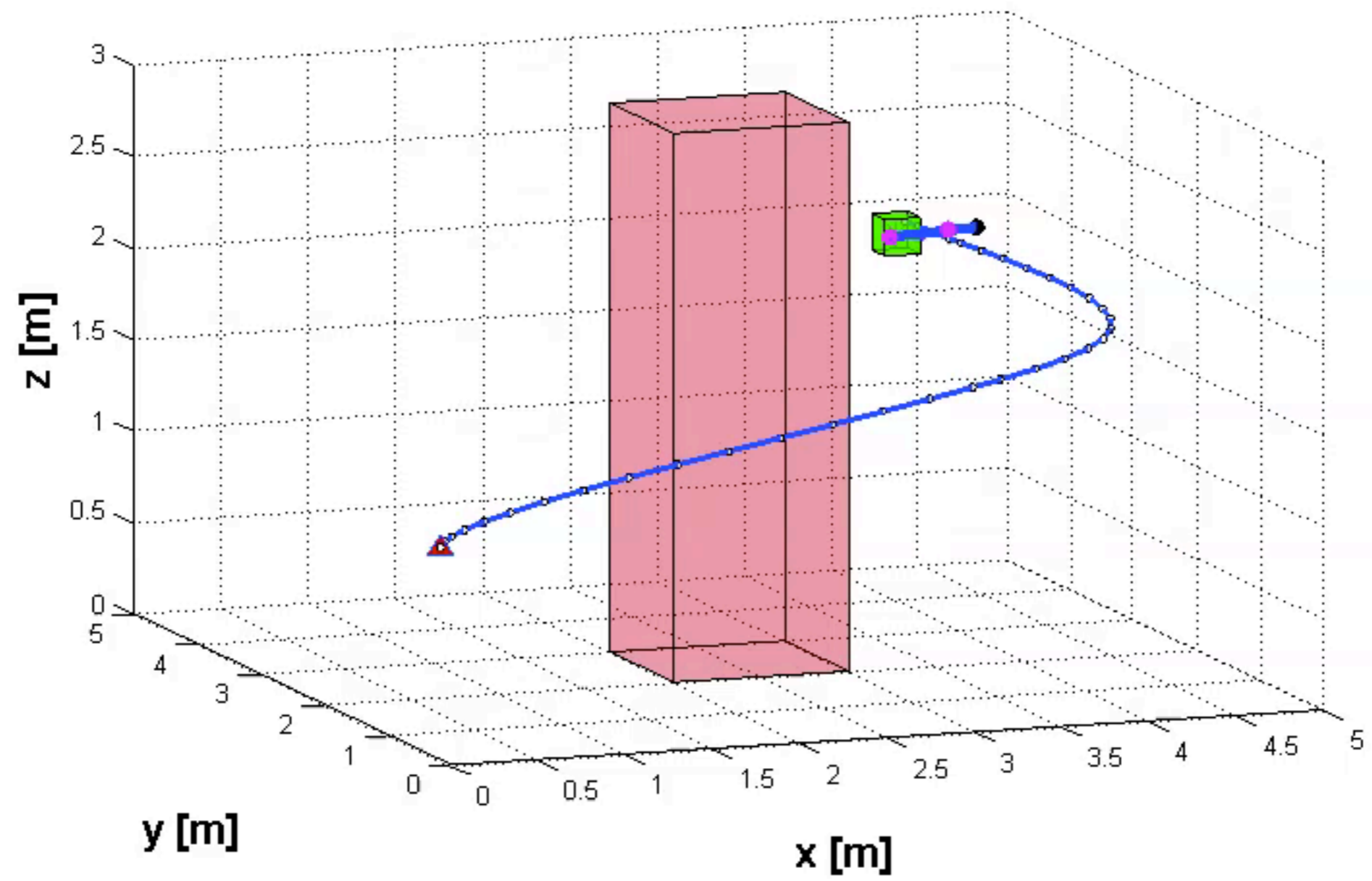
# Discretized Space



■ Obstacles ■ Seen ■ Walkable

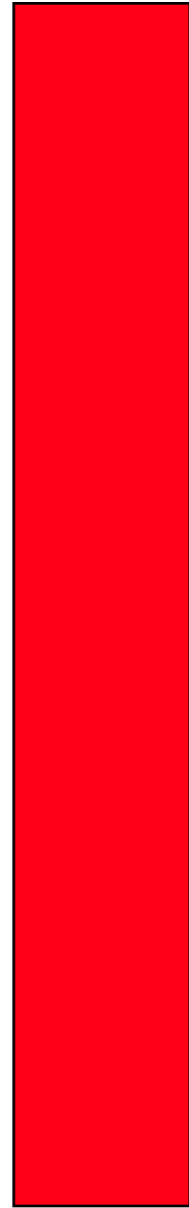
# Search Space



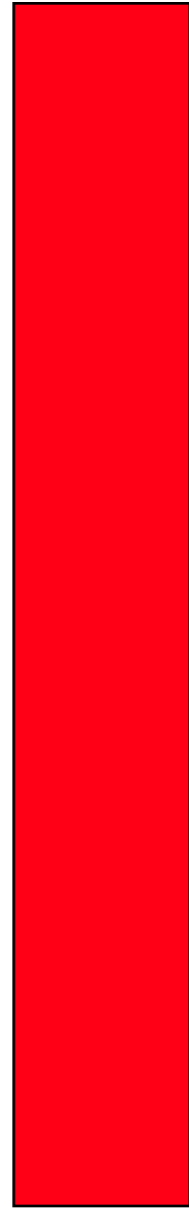




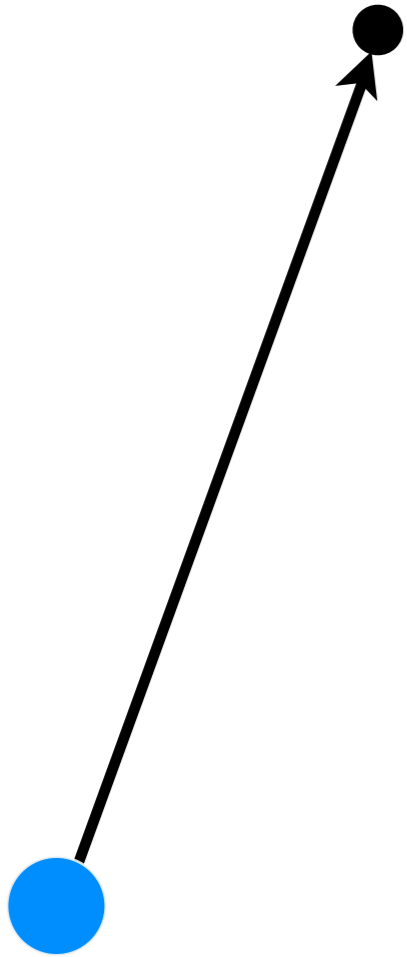
# RRT



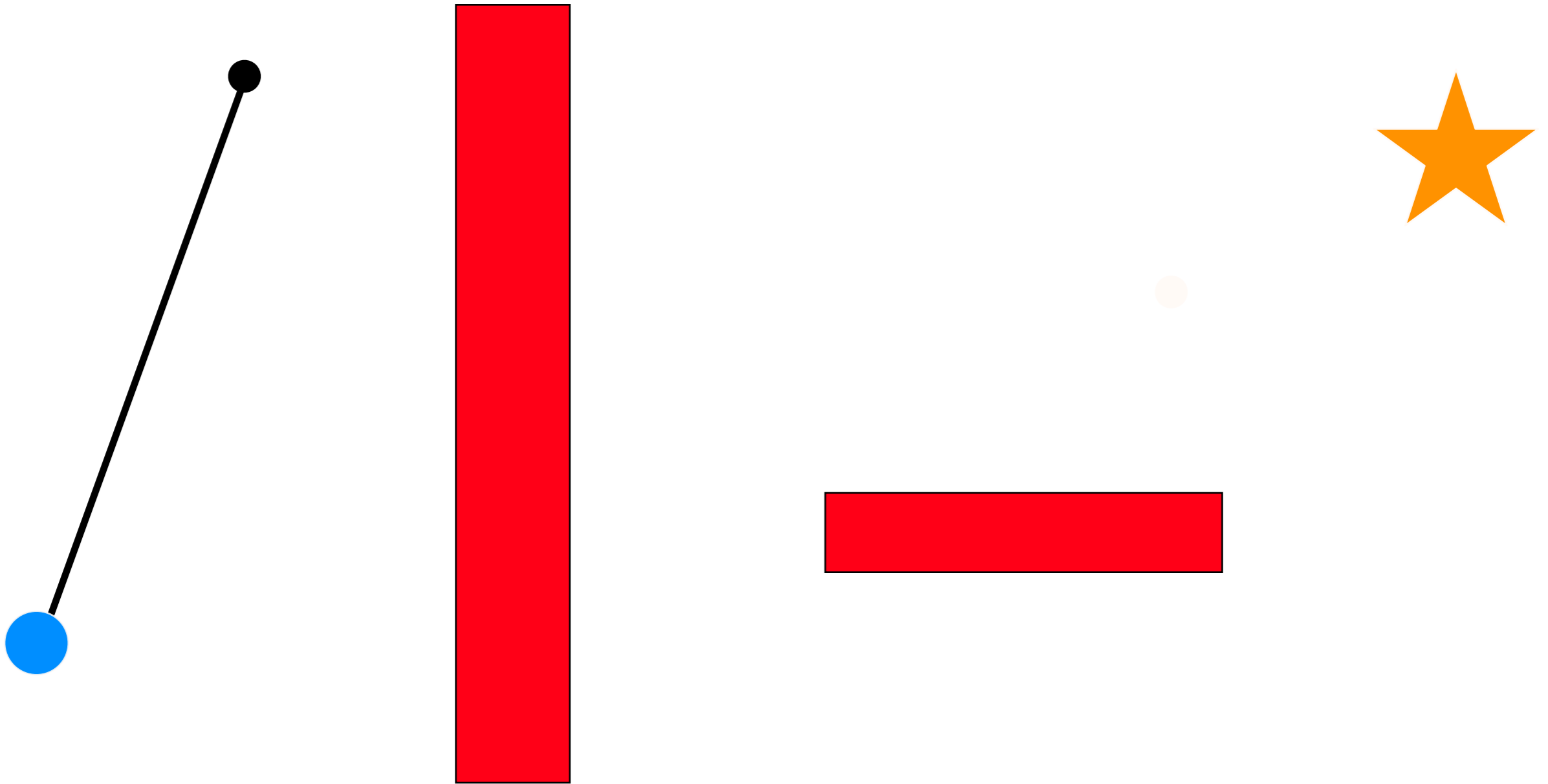
# RRT



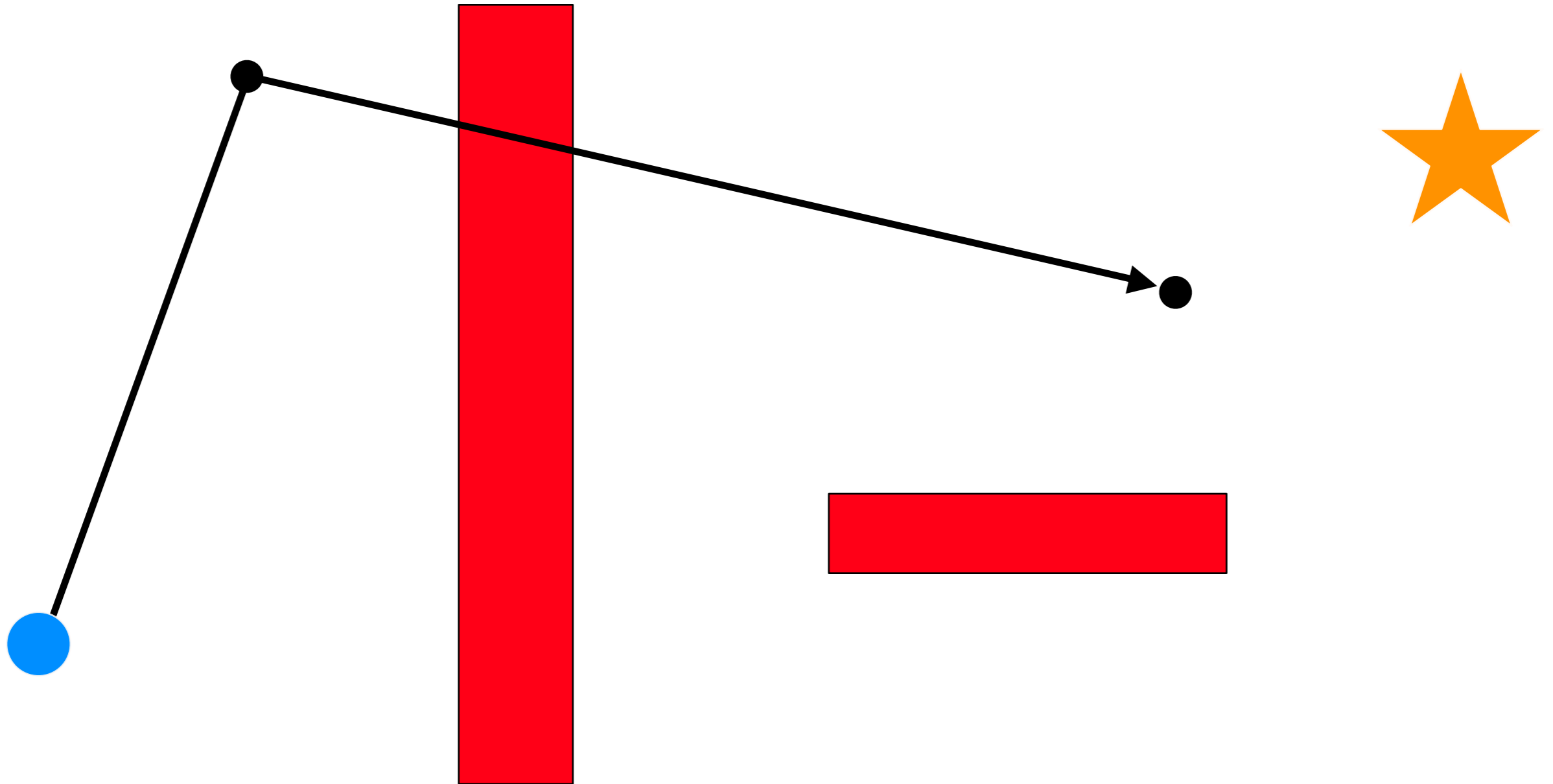
# RRT



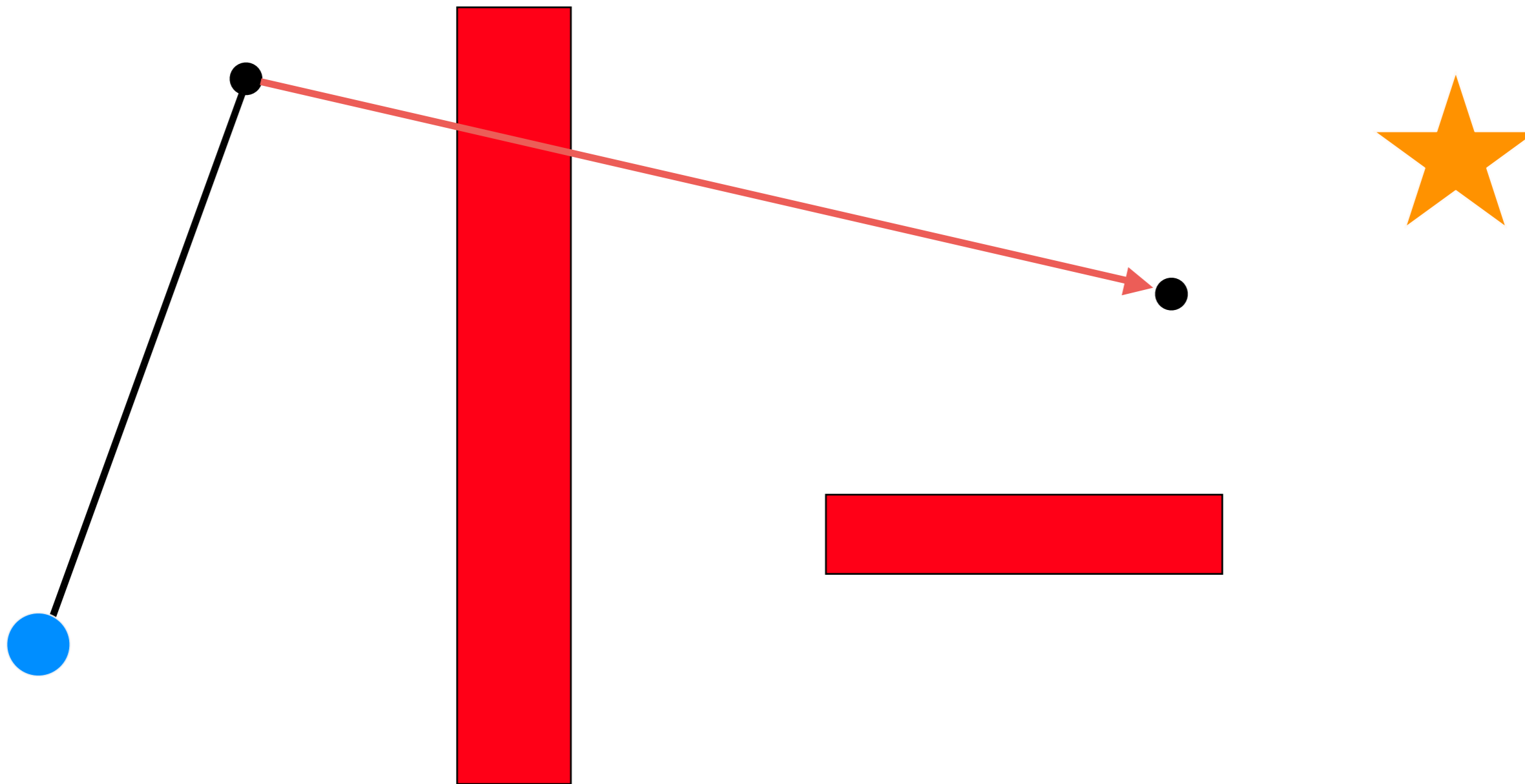
# RRT



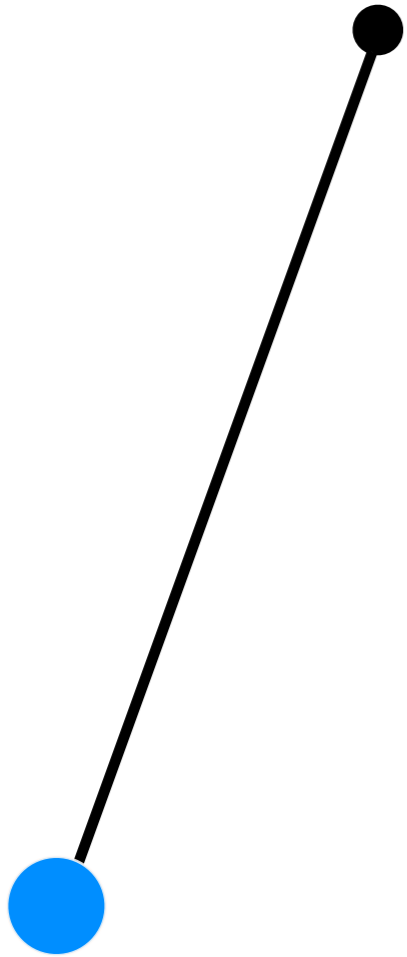
# RRT



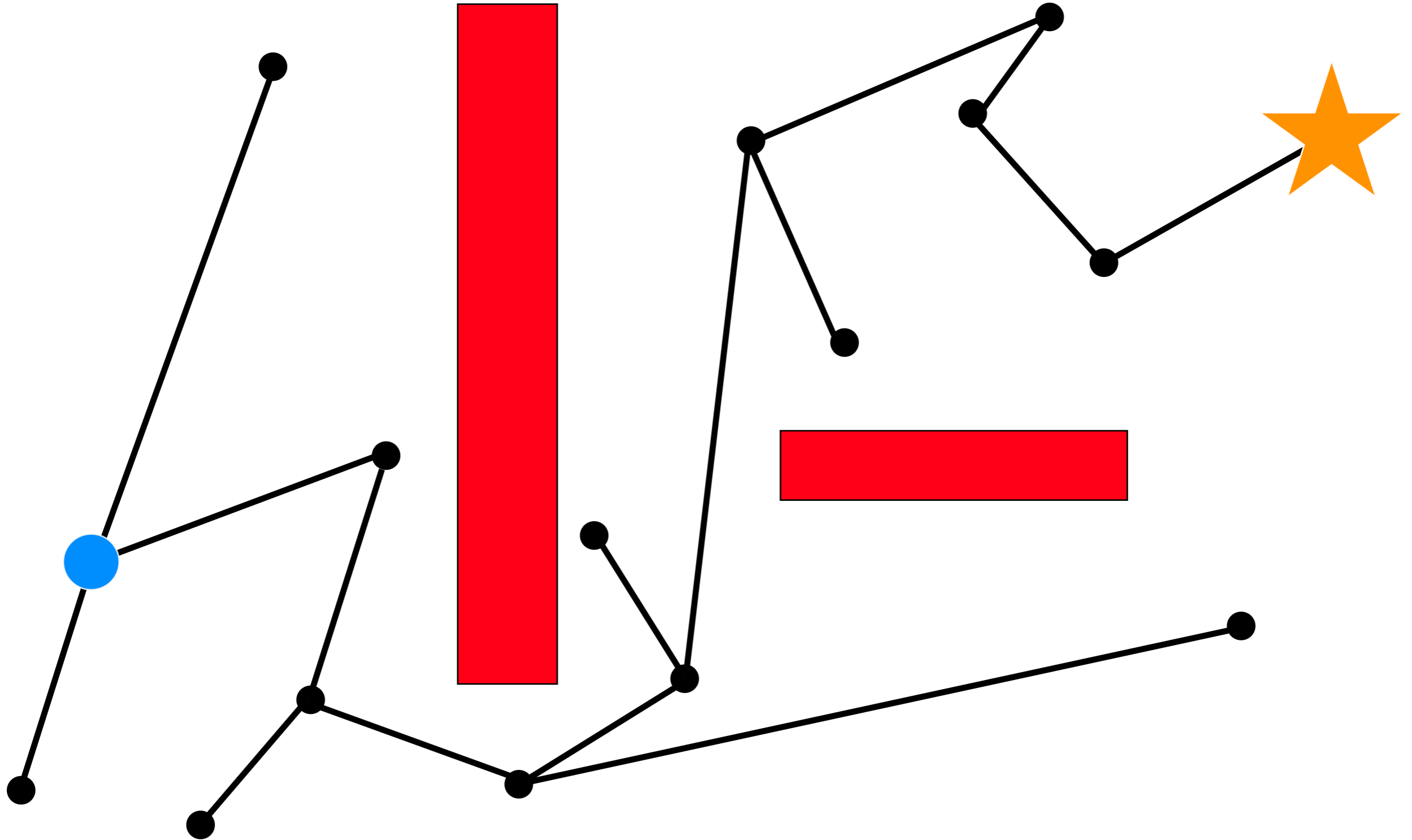
# RRT



# RRT

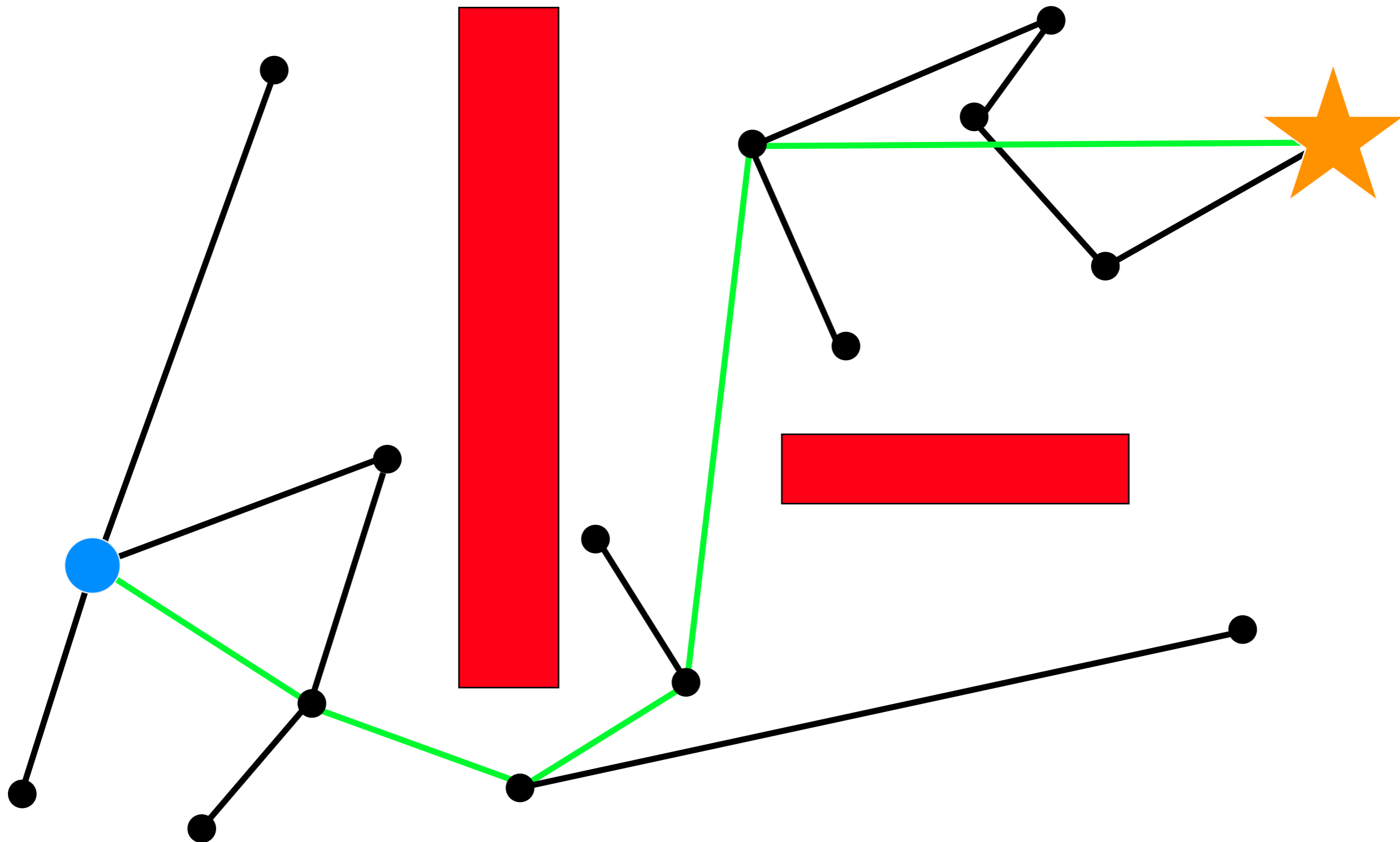


# RRT





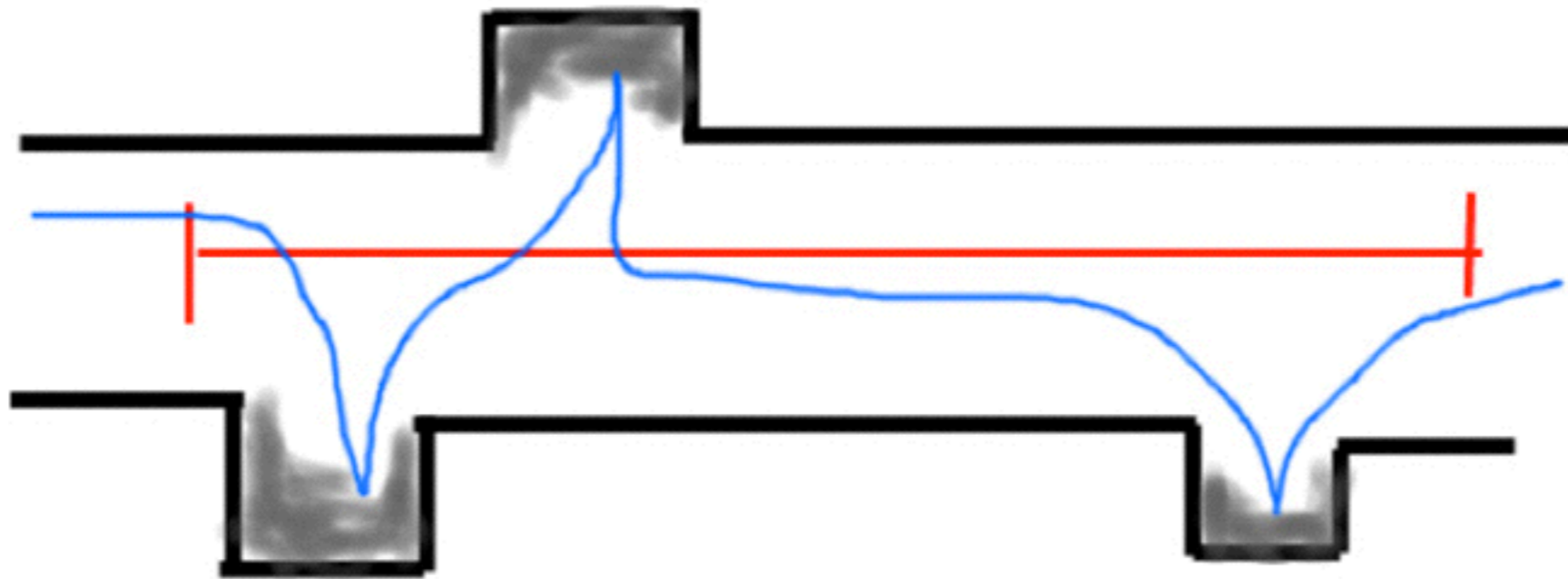
# RRT



# RRT

- Run multiple times
- Randomly exploring the space
- None optimal paths

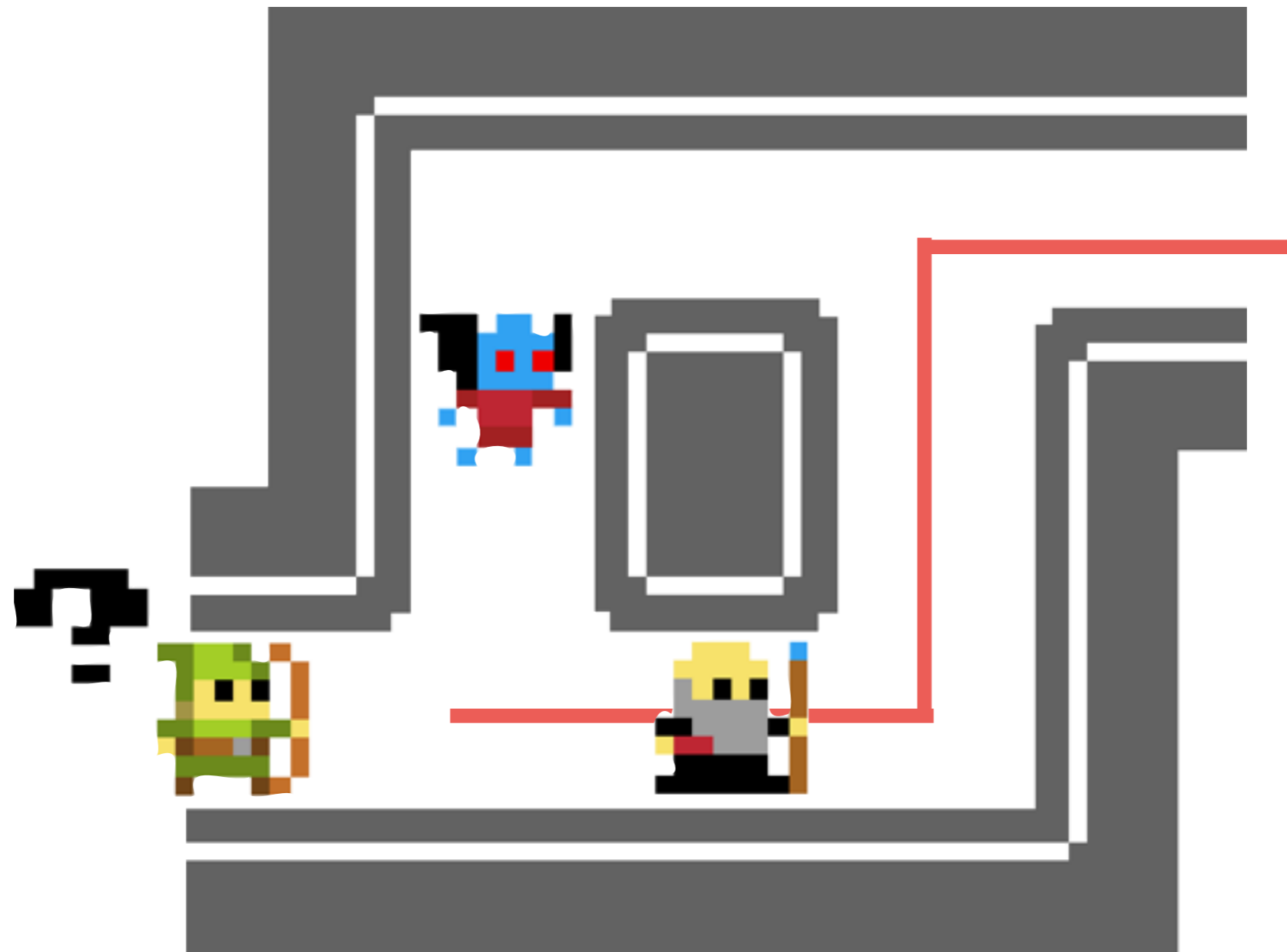
# Clustering



[Smith 06]

# Quick Demo

# Understanding the player





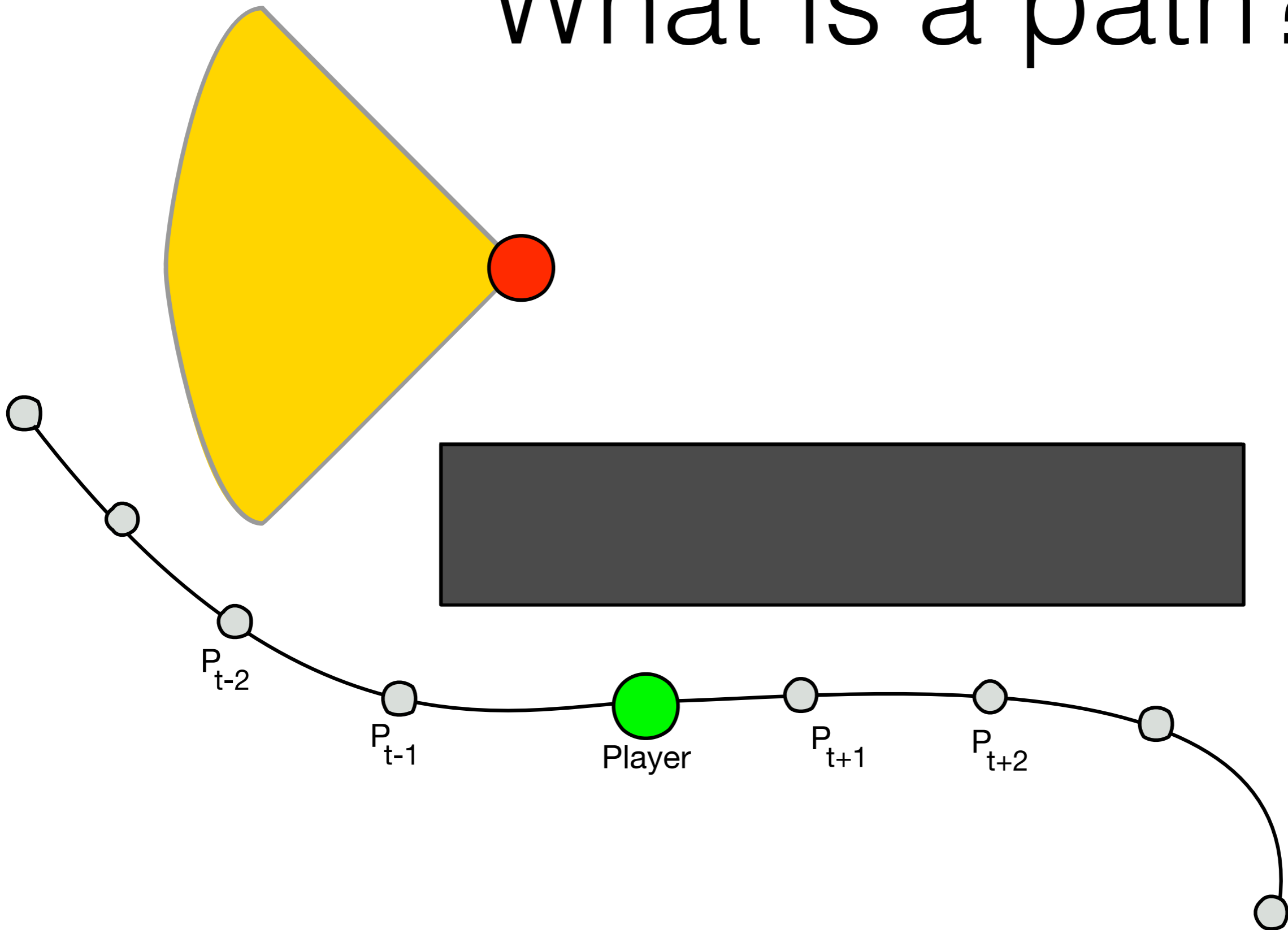
# Defining risk

- Distance to the enemy
- Distance to the enemy's field of view
- Nearly seen
- Shortest path
- *etc.*





# What is a path?



# Metrics

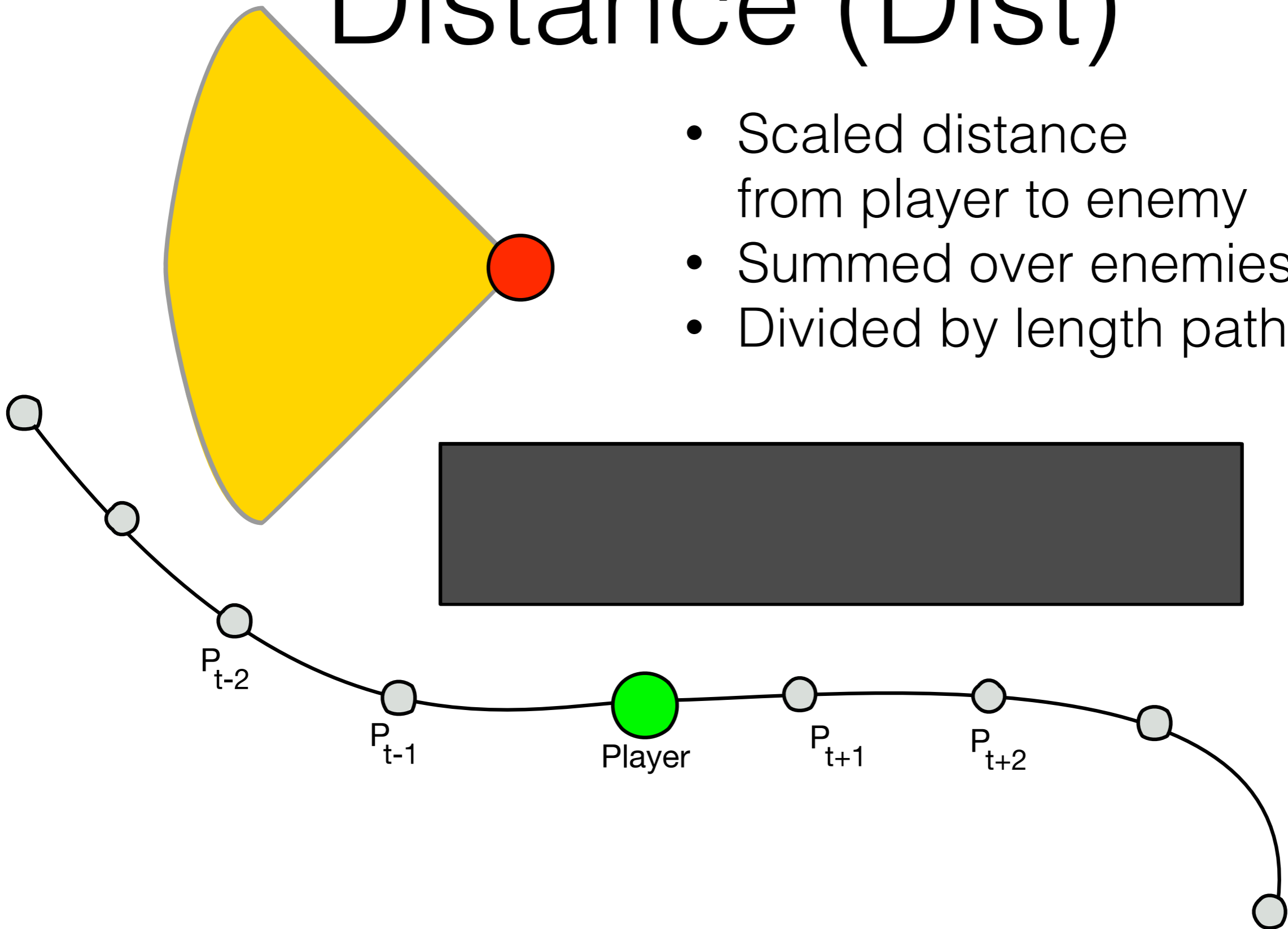
Distance to the enemy (DIST)

Line of sight cost (LOS)

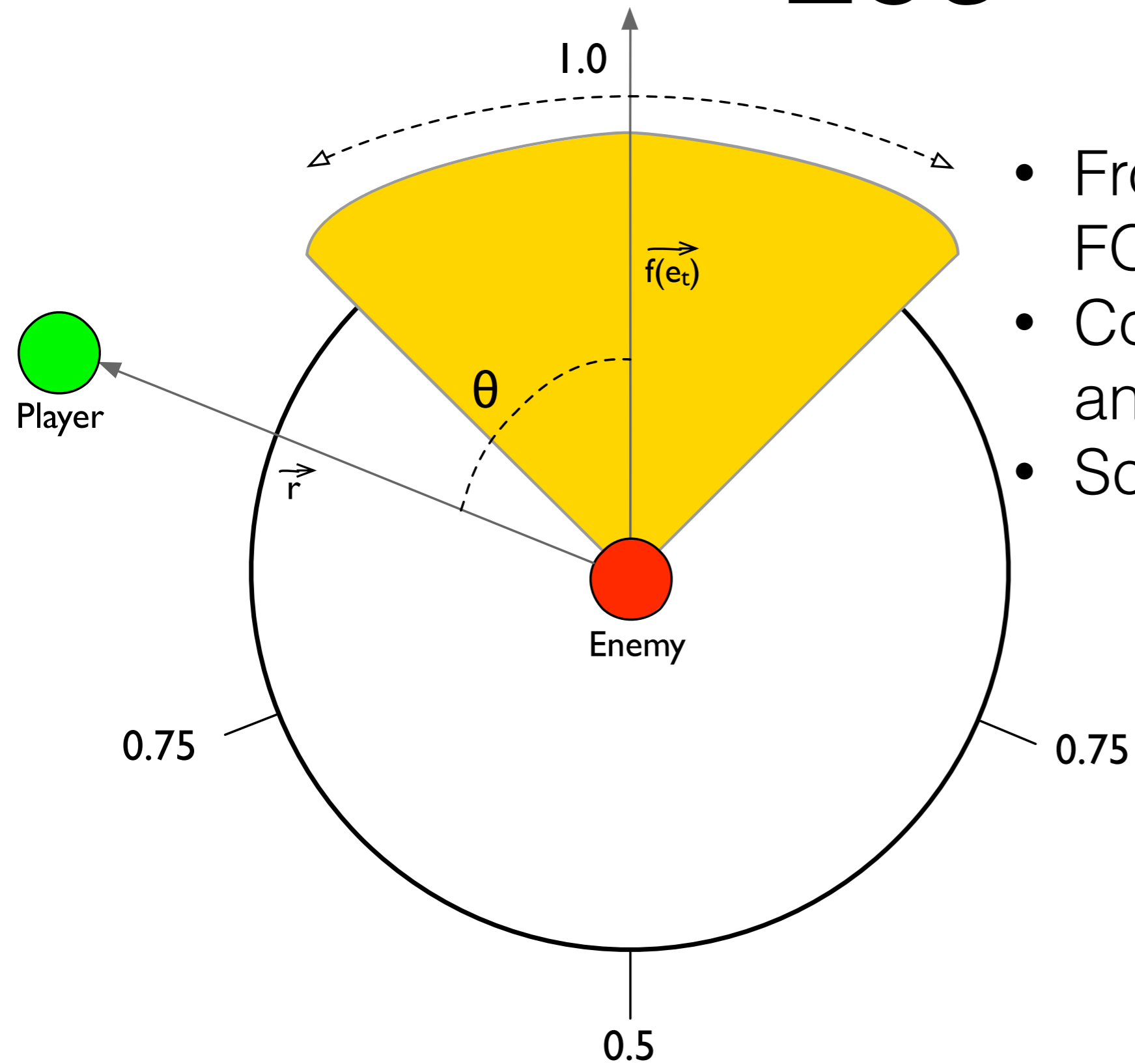
Nearly missed (NM)

# Distance (Dist)

- Scaled distance from player to enemy
- Summed over enemies
- Divided by length path

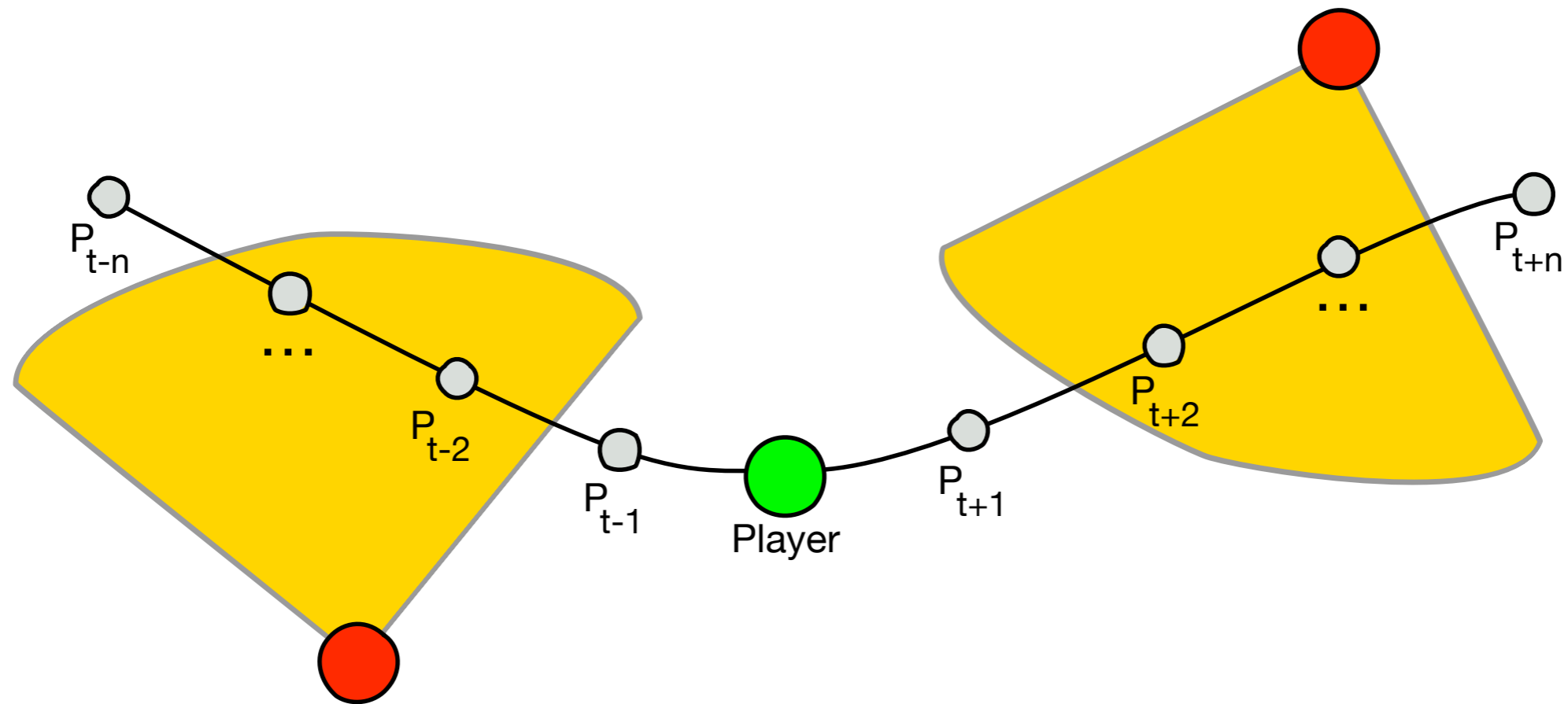


# LOS



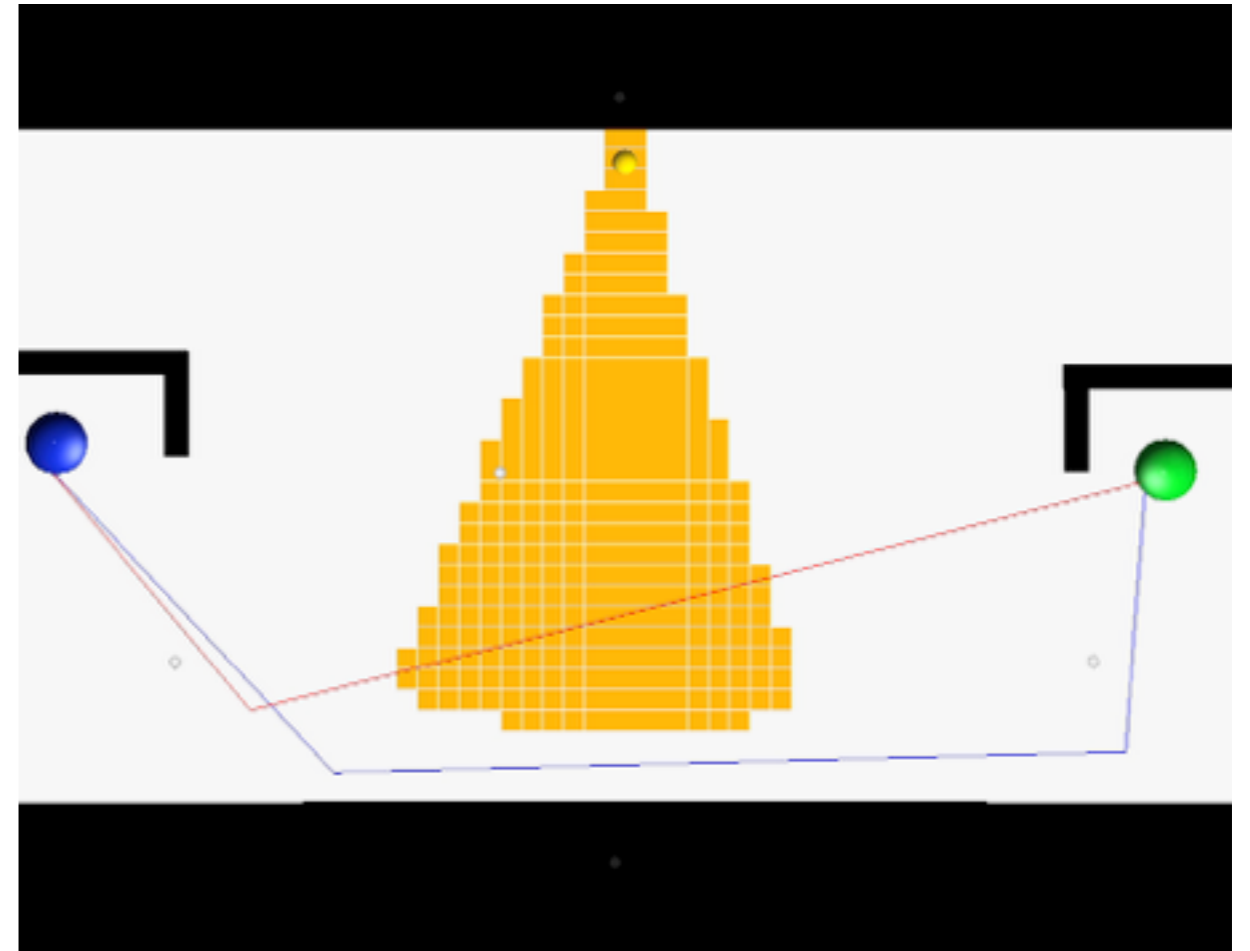
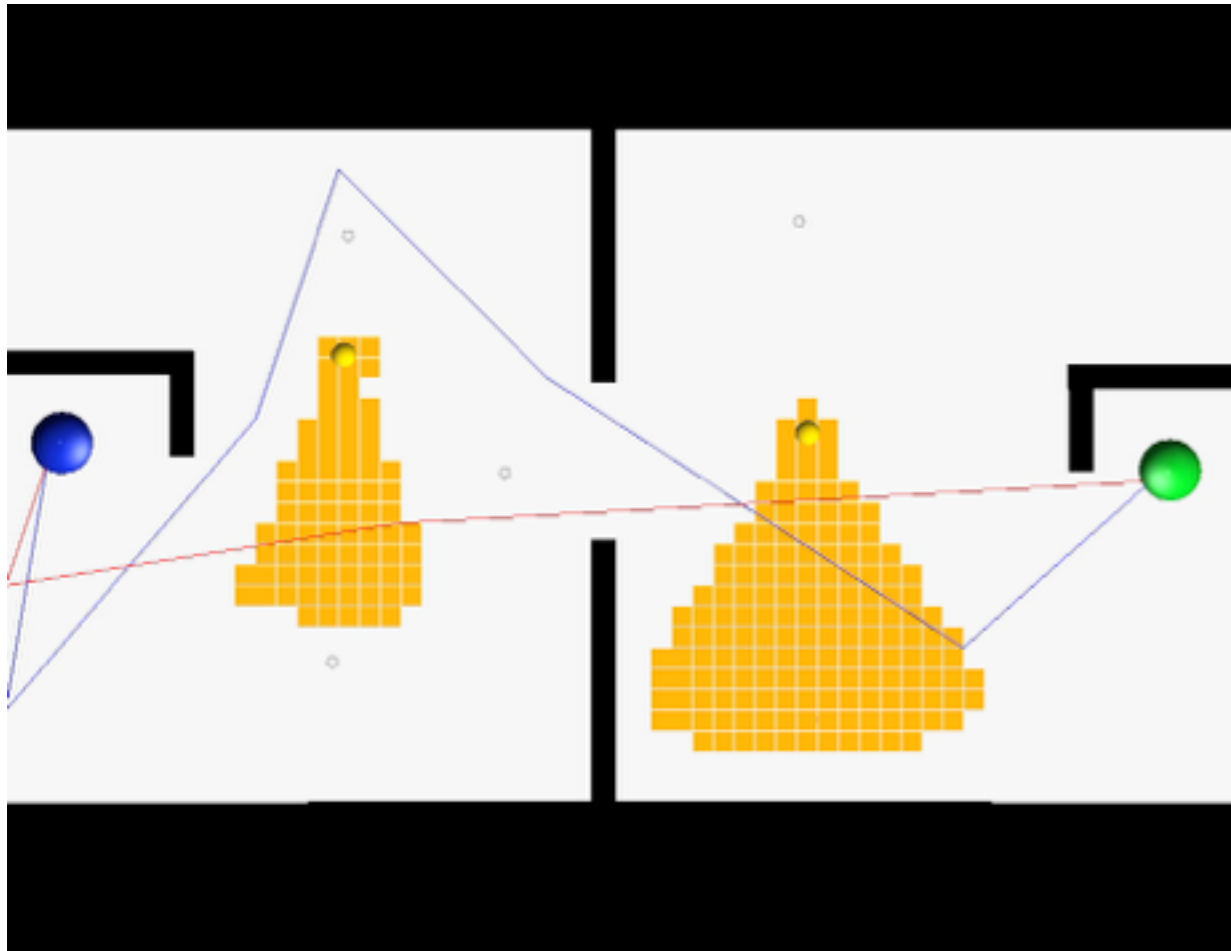
- From player to enemy's FOV.
- Cost function based on angle
- Scale to the distance

# Nearly Missed



- Check the past and future positions
- Cost if seen based on time

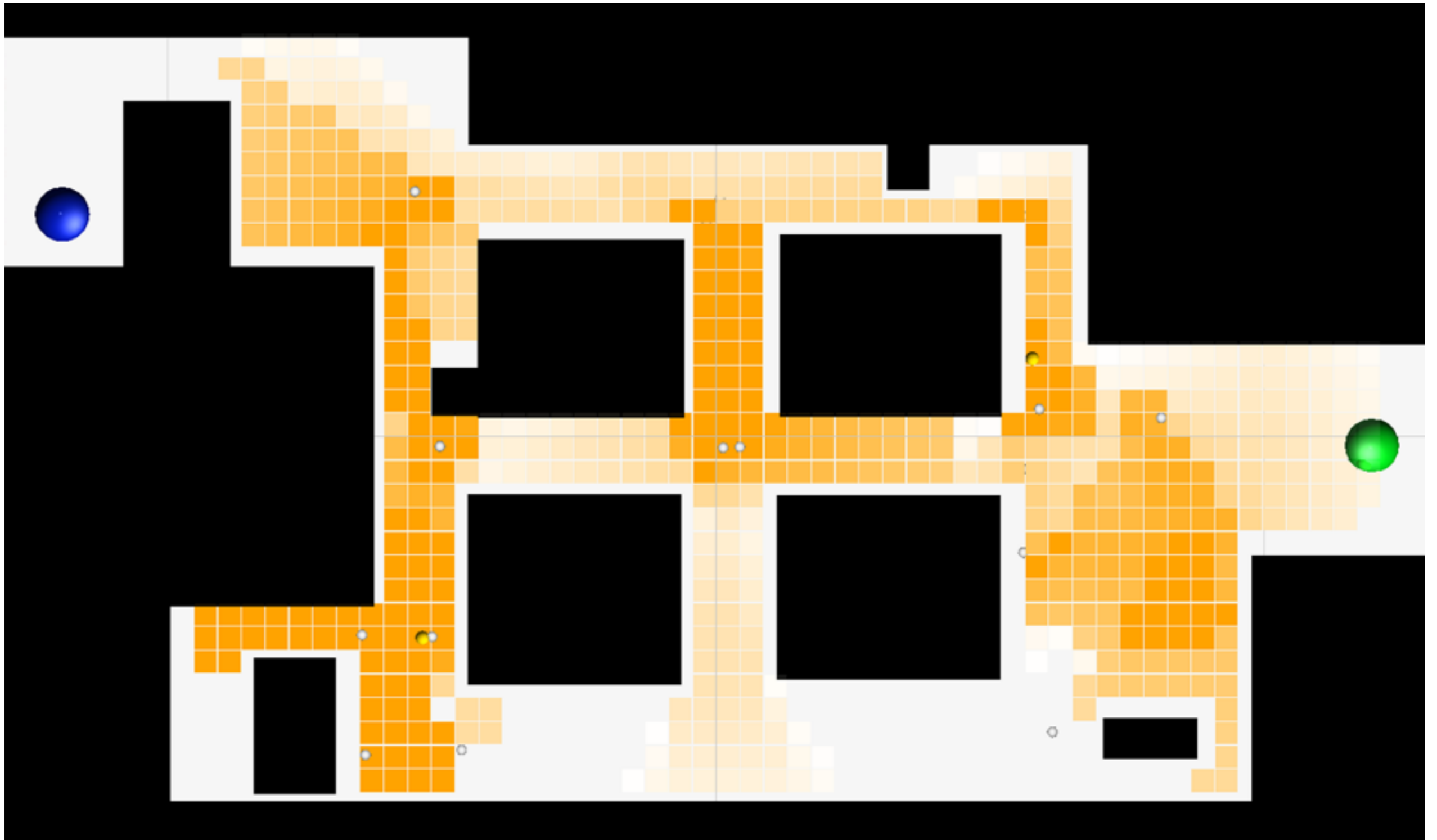
# Human study



# Results

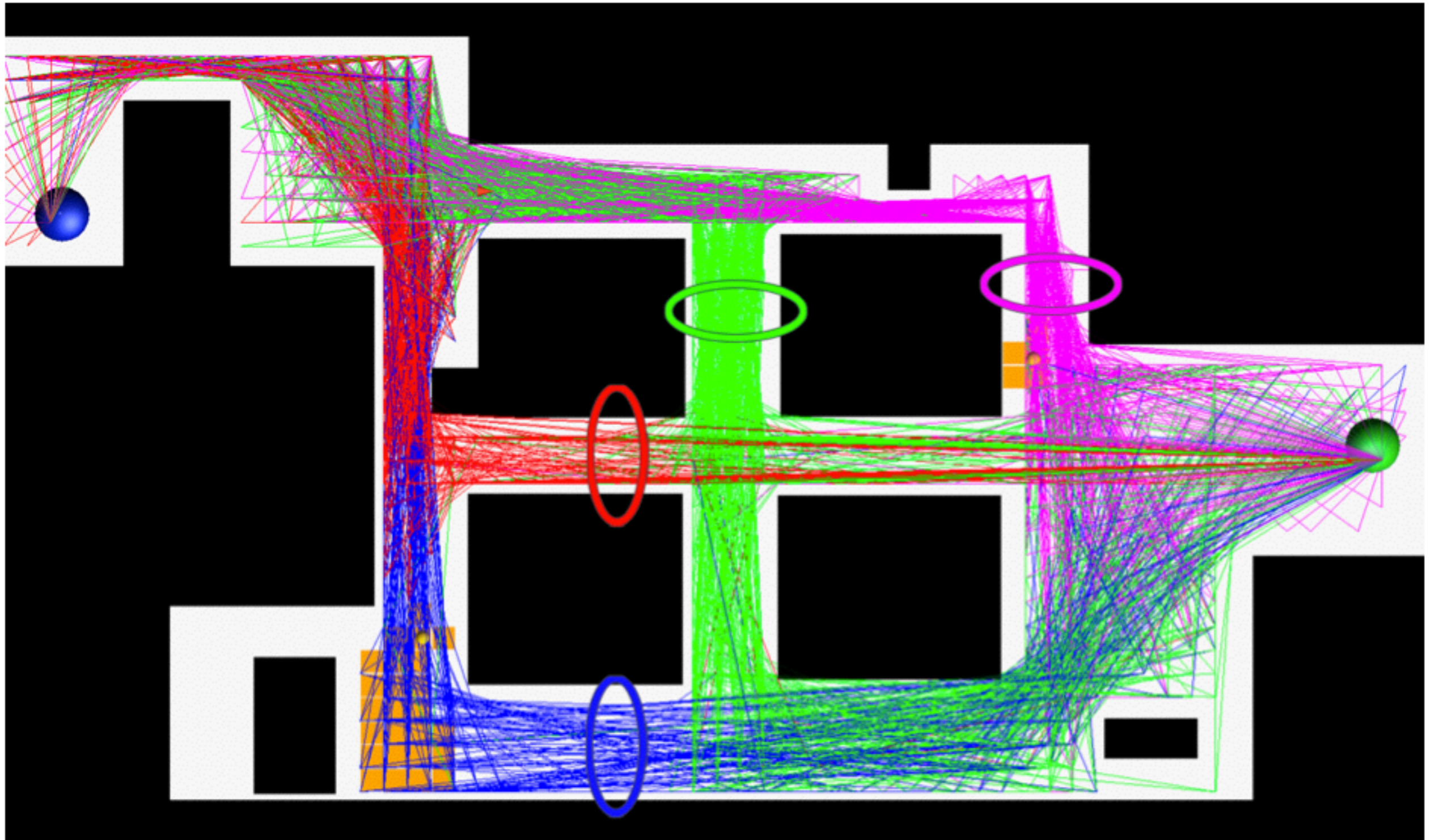
Level	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	#
Human	Blue	Red	White	Blue	Blue	White	White	White	Red	Red	Red	Blue	Red	Blue	White	-
Dist	Blue	Red	Blue	Blue	Blue	Red	Red	Red	Red	Red	Red	Blue	Red	Blue	Blue	10
LOS	Blue	Red	Blue	Blue	Red	Blue	Red	Red	Red	Red	Red	Red	Red	Red	Red	8
NM	White	Red	Red	Blue	Blue	Blue	Blue	Red	Red	Red	Red	Blue	Red	Red	Blue	9

# Evaluating level difficulty





# Evaluating level difficulty



# Evaluating level difficulty

Metrics	Red		Blue		Green		Magenta	
	Avg	Med	Avg	Med	Avg	Med	Avg	Med
Dist ( $\times 10^{-3}$ )	0.6	0.2	3.7	0.9	1.8	1.0	0.2	0.9
LOS ( $\times 10^{-2}$ )	0.7	0.02	13.8	0.4	1.6	0.01	4.7	0.3
NM ( $\times 10^5$ )	2.0	1.6	2.8	2.4	2.5	1.9	1.9	0.7

# Metrics

- Quantitative metrics to measure player's experience
- Metrics correlate with human perception of *risk*
- Help understand level design

# So Far

- Companion makes better target choices
- Offline stealth path finding
- Understanding notions of stealth risk

# Still to come

- Guard interactions planning
- Online stealth path finding for companion

# Not presented

- Combat/stealth simulator
- Player simulator in the platformer domain
- Clustering similar paths
- Advance visualization of stealth space
- Automatically placing guards in a level

# Special thanks

- Clark Verbrugge
- Pedro Andrade Torres
- Qihan Xu
- Christopher Dragert
- Nir Ricovitch
- Eugène Jancorda-Vadnais
- Alexander Borodovski
- Jonathan Campbell

# References

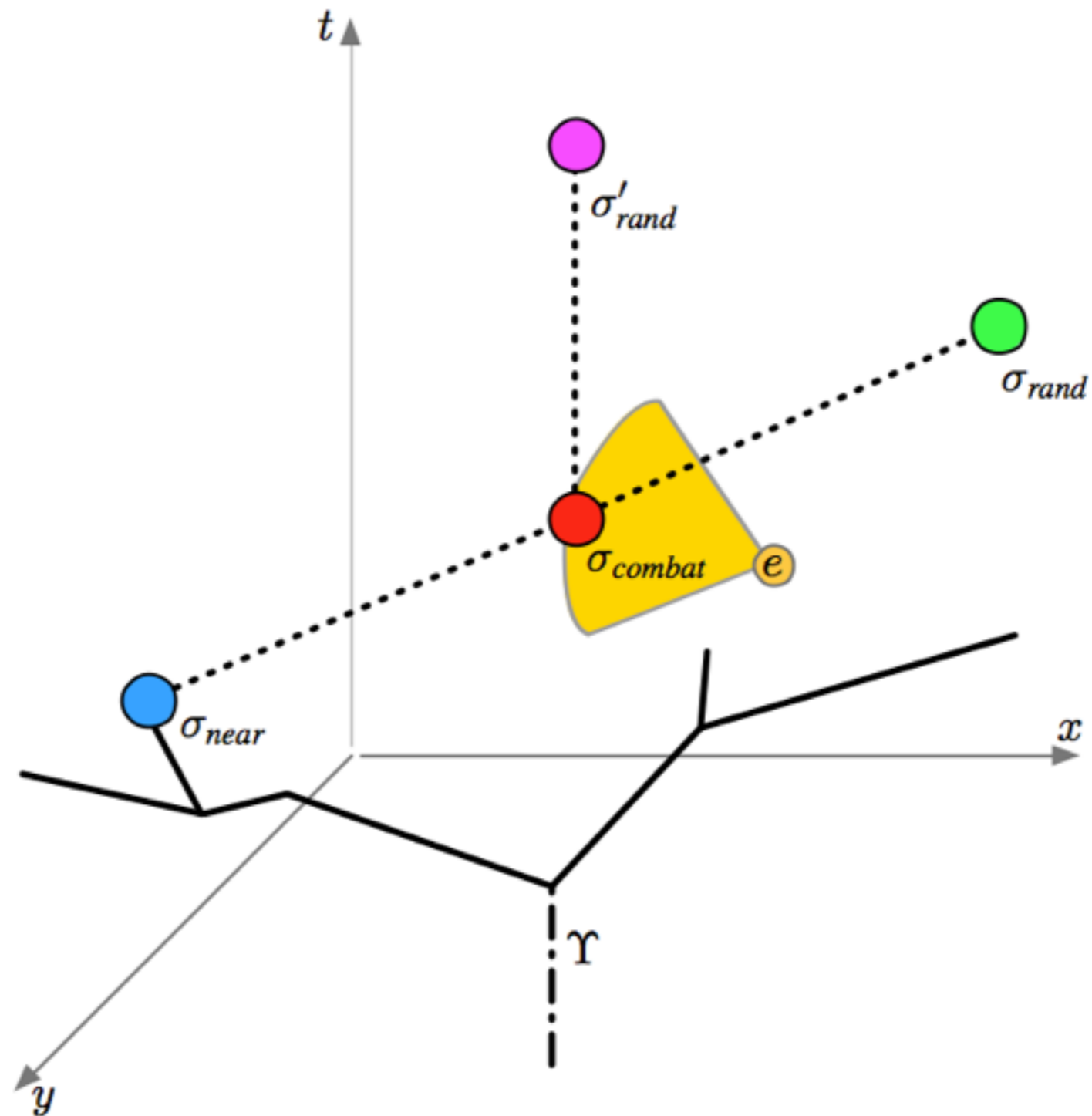
- T. Furtak and M. Buro. On the complexity of two-player attrition games played on graphs. In AAAI Conference on Artificial Intelligence and Interactive Digital Entertainment, 2010.
- Randy Smith. Level Building for Stealth Gameplay. Online resource, 2009.  
[www.roningamedeveloper.com/Materials.html](http://www.roningamedeveloper.com/Materials.html)



Thank you

Jonathan Tremblay  
[jtremblay@cs.mcgill.ca](mailto:jtremblay@cs.mcgill.ca)

# Adding combat



# Threat ordering

$$\max_{e \in E} [e.a \cdot (E_h - e_h)]$$

# Distance

$$\text{Dist}(p) = \sum_{t=1}^T \left[ \sum_{e \in E} \frac{1}{d^*(g(p, t), g(e, t))^3} \right]$$

# LOS

$$\text{LOS}(p) = \frac{\sum_{t=1}^T \left[ \sum_{e \in E} \frac{\text{Cost}(\theta(g(p,t), g(e,t)))}{d^*(g(p,t), g(e,t))^3} \text{Vis}(p, e, t) \right]}{L}$$

# Nearly Missed

$$\text{Seen}(\alpha, \tau) = \begin{cases} 1 & \text{if } (\alpha_x, \alpha_y, \tau) \in \chi_{FOV} \\ 0 & \text{otherwise} \end{cases}$$

$$W^-(t, n) = \sum_{i=1}^n (n - i)^2 \cdot \text{Seen}(g(p, t - i), t)$$

$$W^+(t, m) = \sum_{i=1}^m (m - i)^2 \cdot \text{Seen}(g(p, t + i), t)$$

$$\text{NM}(\text{Path}) = \sum_{t=1}^T (W^-(t, n) + W^+(t, m))$$