Applied Machine Learning

Linear Regression

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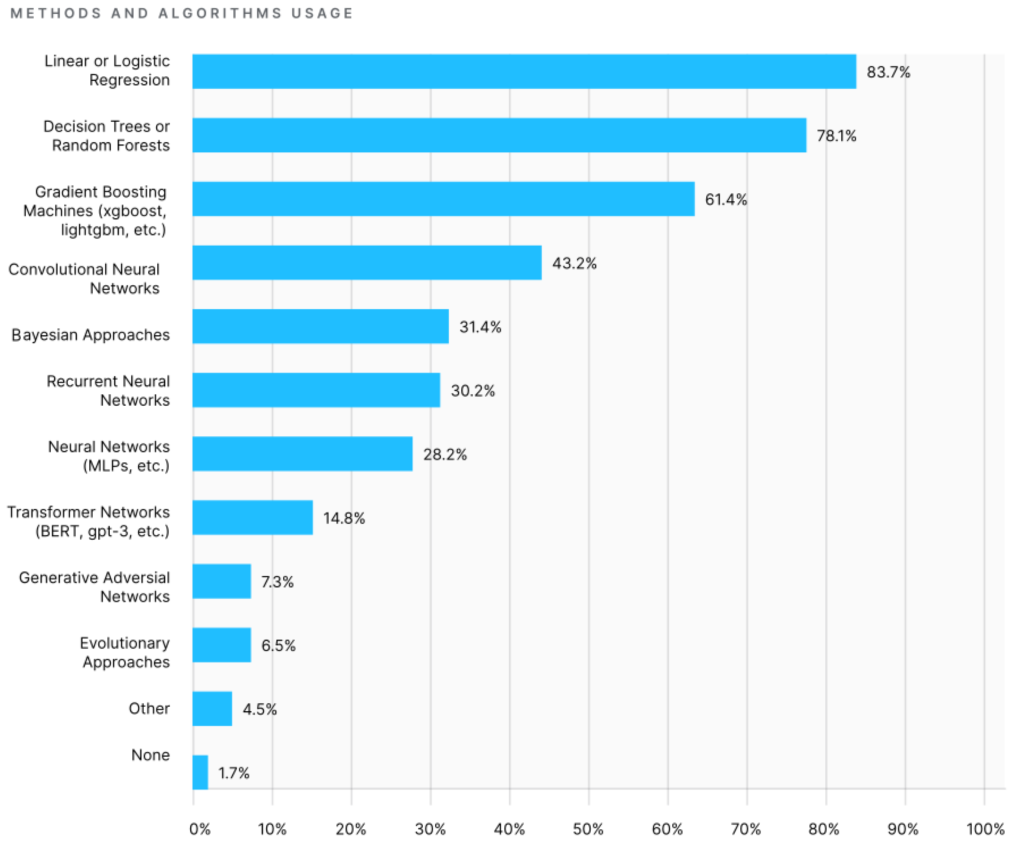
Sometimes all you need is a linear regression ...



from 2020 Kaggle's survey on the state of Machine Learning and Data Science,
you can read the full version here

Learning objectives

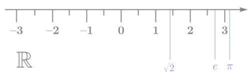
- linear model
- evaluation criteria
- how to find the best fit
- geometric interpretation
- maximum likelihood interpretation

x | input features $\rightarrow$ **ML algorithm** **with parameters θ** $f(x;\theta)$ $\rightarrow$ y | output labels

Notation

each instance: $x \in \mathbb{R}^D$, $y \in \mathbb{R}$

$\mathbb{R}$ denotes set of real numbers



vectors are assume to be column vectors $x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_D \end{bmatrix} = \begin{bmatrix} x_1, & x_2, & \ldots, & x_D \end{bmatrix}^\top$

a feature (x_1)

example

<tumorsize, texture, perimeter> = <18.2, 27.6, 117.5> $\rightarrow$ growth = +2

$$x = \begin{bmatrix} 18.2, & 27.6, & 117.5 \end{bmatrix}^\top$$

$$x = \begin{bmatrix} x_1, & x_2, & x_3 \end{bmatrix}^\top$$

$$y = 2$$

Notation

x | input features $\rightarrow$ **ML algorithm** **with parameters θ** $\rightarrow$ y | output labels

$f(x^{(n)}; \theta)$

training: parameter estimation

$\mathcal{D} = \{(x^{(n)}, y^{(n)})\}_{n=1}^{N}$

instance number

each instance: $x^{(n)} \in \mathbb{R}^D$

$y^{(n)} \in \mathbb{R}$

we assume N instances in the dataset $\mathcal{D} = \{(x^{(n)}, y^{(n)})\}_{n=1}^{N}$

each instance has D features indexed by d

for example, $x_d^{(n)} \in \mathbb{R}$ is the feature d of instance n

Notation

design matrix: *concatenate all instances* $\mathcal{D} = \{(x^{(n)}, y^{(n)})\}_{n=1}^{N}$

each row is a datapoint, each column is a feature

$$X = \begin{bmatrix} x^{(1)\top} \\ x^{(2)\top} \\ \vdots \\ x^{(N)\top} \end{bmatrix} = \begin{bmatrix} x_1^{(1)}, & x_2^{(1)}, & \cdots, & x_D^{(1)} \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{(N)}, & x_2^{(N)}, & \cdots, & x_D^{(N)} \end{bmatrix} \in \mathbb{R}^{N \times D}$$

one instance

one feature

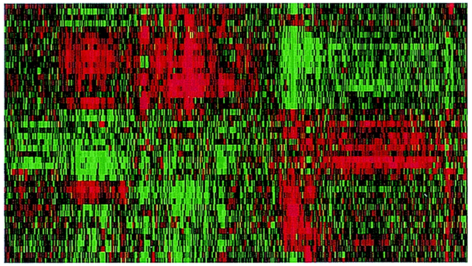
$$Y = \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(N)} \end{bmatrix} \in \mathbb{R}^{N \times 1}$$

Example:
instances: 5 documents
features: 7 words

	it	is	puppy	cat	pen	a	this
it is a puppy	1	1	1	0	0	1	0
it is a kitten	1	1	0	0	0	1	0
it is a cat	1	1	0	1	0	1	0
that is a dog and this is a pen	0	1	0	0	1	1	1
it is a matrix	1	1	0	0	0	1	0

Example:
Micro array data (X), contains gene expression levels
labels (y) can be {cancer/no cancer classification} label for each patient, or how fast it is growing (regression)

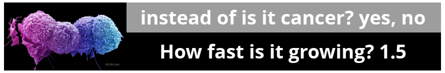
patient (n)



gene (d)

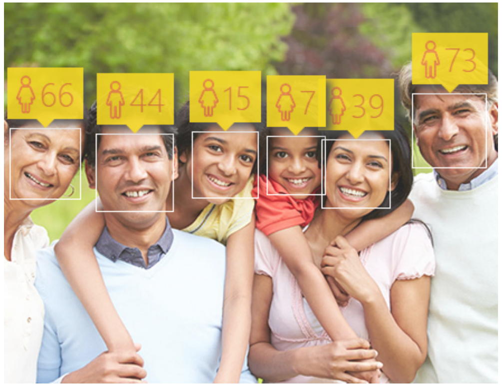
$\in \mathbb{R}^{N \times D}$

Regression: examples



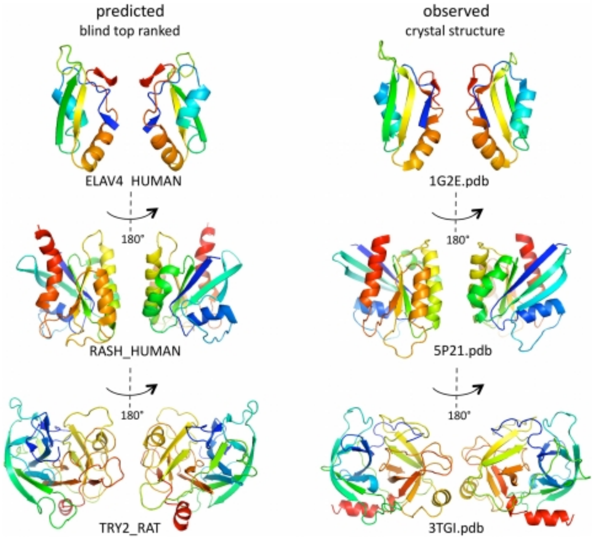
Age-estimating.
input: face
output: age

image from Microsoft age estimator here



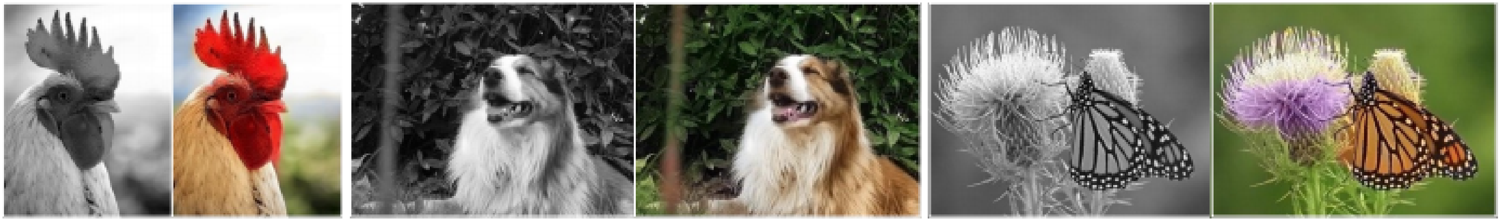
Protein folding.
input: sequences
output: 3D structure

Image from Marks et al. link



Colourization.
input: gray scale image
output: colour image

Image from Zhang et al. link



Origin of Regression

Method of least squares was invented by **Legendre** and **Gauss** (1800's)

Gauss used it to predict the future location of Ceres (largest asteroid in the asteroid belt)

ocean navigation

image from wiki history of navigation

Gauss

used it

Legendre

published it

Pearson

named it regression

find more here

Linear model of regression

x | input features → **ML algorithm** **with parameters w** $f(x; w)$ → y | output labels

$$f_w(x) = w_0 + w_1 x_1 + \ldots + w_D x_D$$

model parameters or weights (we also called them θ before)

$[w_0, w_1, \ldots w_D]$

bias or intercept

assuming a scalar output $f_w : \mathbb{R}^D \rightarrow \mathbb{R}$

will generalize to a vector later

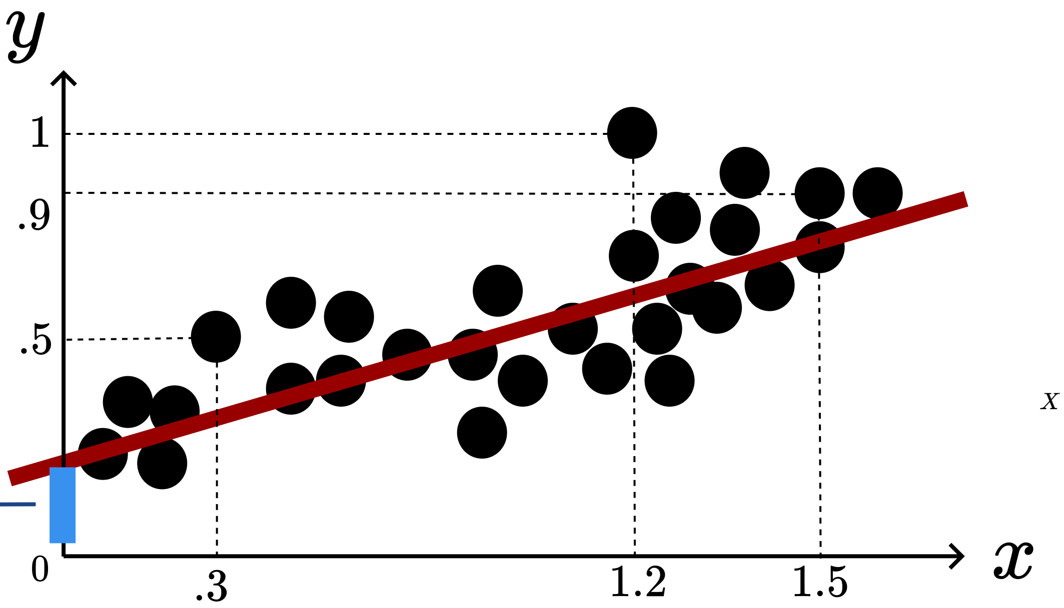
Linear model of regression: example $D = 1$

$$f_w(x) = w_0 + w_1 x_1$$

forms a line in 1 dimension

model parameters or weights

$$[w_0, w_1]$$



$f_w(0)$: bias or intercept

$$X = \begin{bmatrix} .3 \\ 1.2 \\ 1.5 \\ . \\ . \\ . \end{bmatrix}, \; Y = \begin{bmatrix} .5 \\ .9 \\ 1 \\ . \\ . \\ . \end{bmatrix}$$

Linear model of regression

$$f_w(x) = w_0 + w_1 x_1 + \ldots + w_D x_D$$

model parameters or weights

bias or intercept

simplification

concatenate a 1 to x $\longrightarrow$ $x = [1, x_1, \ldots, x_D]^\top$

$$\boxed{f_w(x) = w^\top x}$$

$w = [w_0, w_1, \ldots, w_D]^\top$

Linear regression: Objective

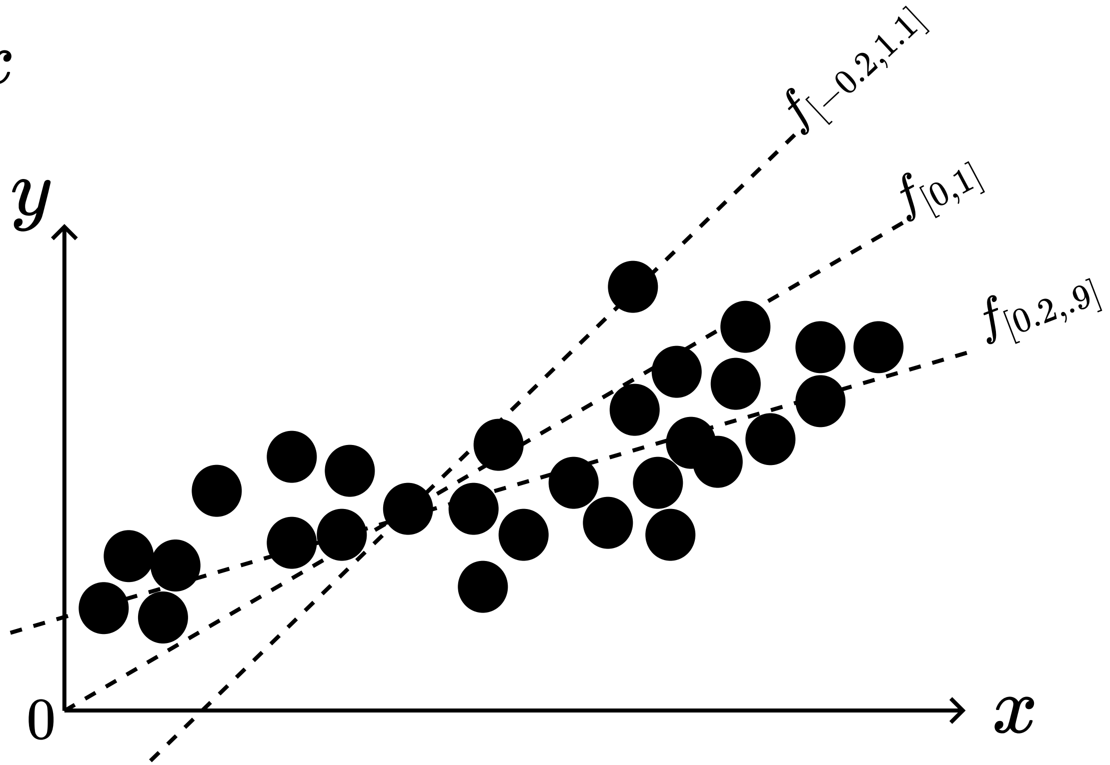
objective: find parameters to fit the data

model: $f_w(x) = w^\top x$

example $D = 1$

$$w = [w_0, w_1]$$

Which line is better?



Linear regression: Objective

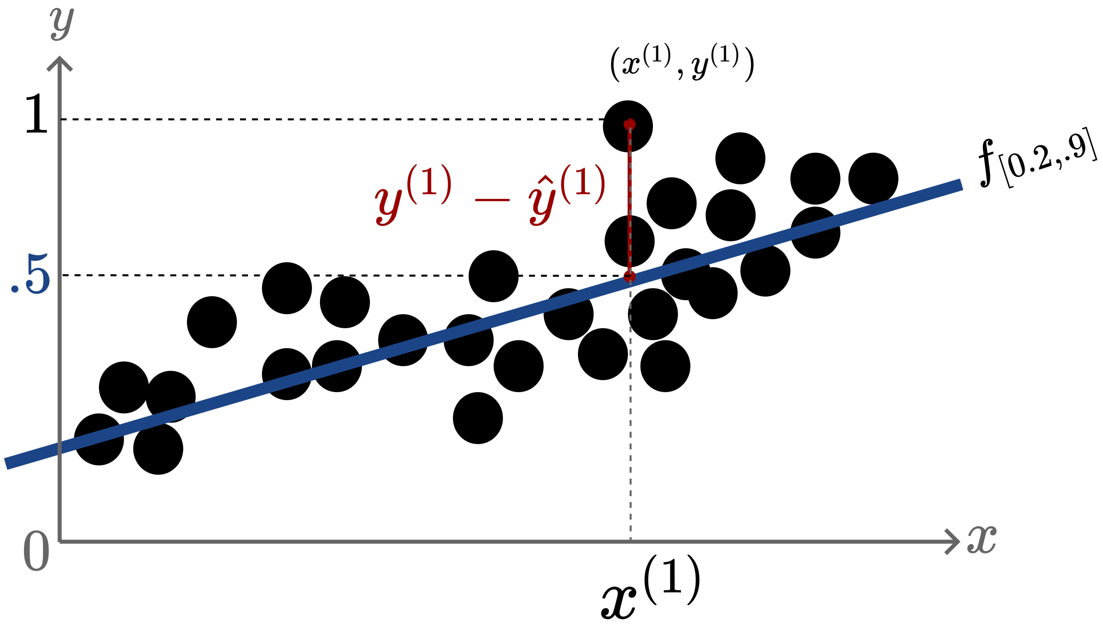
objective: find parameters to fit the data

true: $y^{(1)} = 1$

predicted: $\hat{y}^{(1)} = f(x^{(1)}) = .5$

residual: $y^{(1)} - f_w(x^{(1)})$

difference between
predicted (model output)
and true (observation)



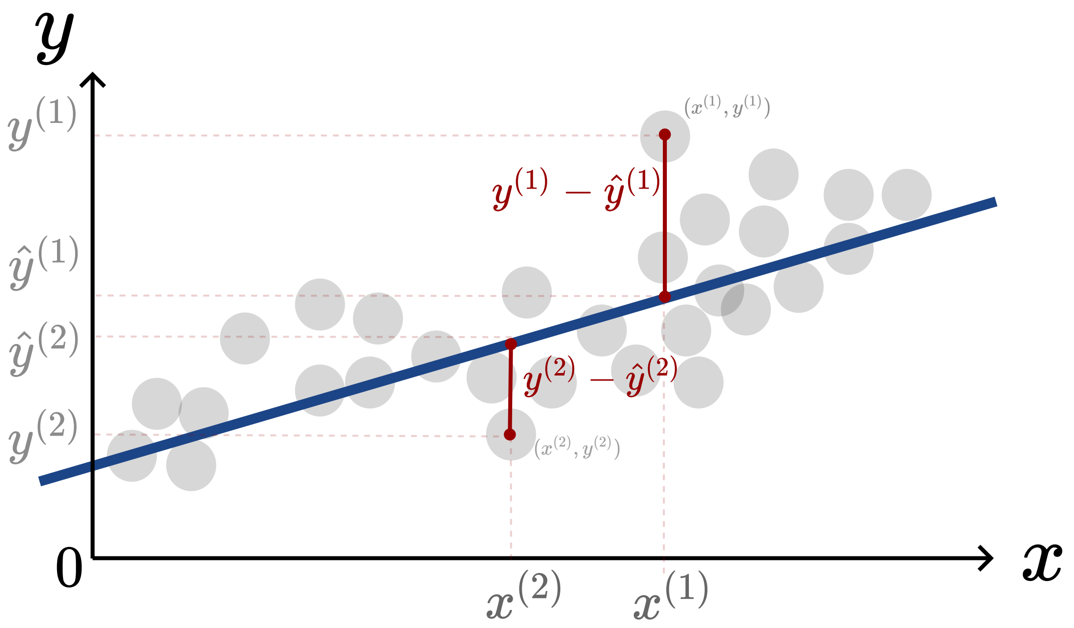
Linear regression: Objective

objective: find parameters to fit the data

how to consider all observations? sum all residuals?

square error **loss** (a.k.a. **L2** loss)

$$L(y, \hat{y}) \triangleq (y - \hat{y})^2$$



Linear regression: cost function

objective: find parameters to fit the data

$$f_w(x^{(n)}) \approx y^{(n)} \quad x^{(n)}, y^{(n)} \quad \forall n$$

minimize a measure of difference between $\hat{y}^{(n)} = f_w(x^{(n)})$ and $y^{(n)}$

square error **loss** (a.k.a. **L2** loss) $L(y, \hat{y}) \triangleq \frac{1}{2}(y - \hat{y})^2$

for a single instance (a function of labels)

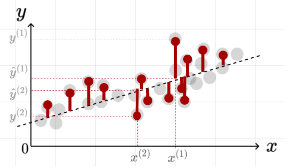
for future convenience

versus

for the whole dataset

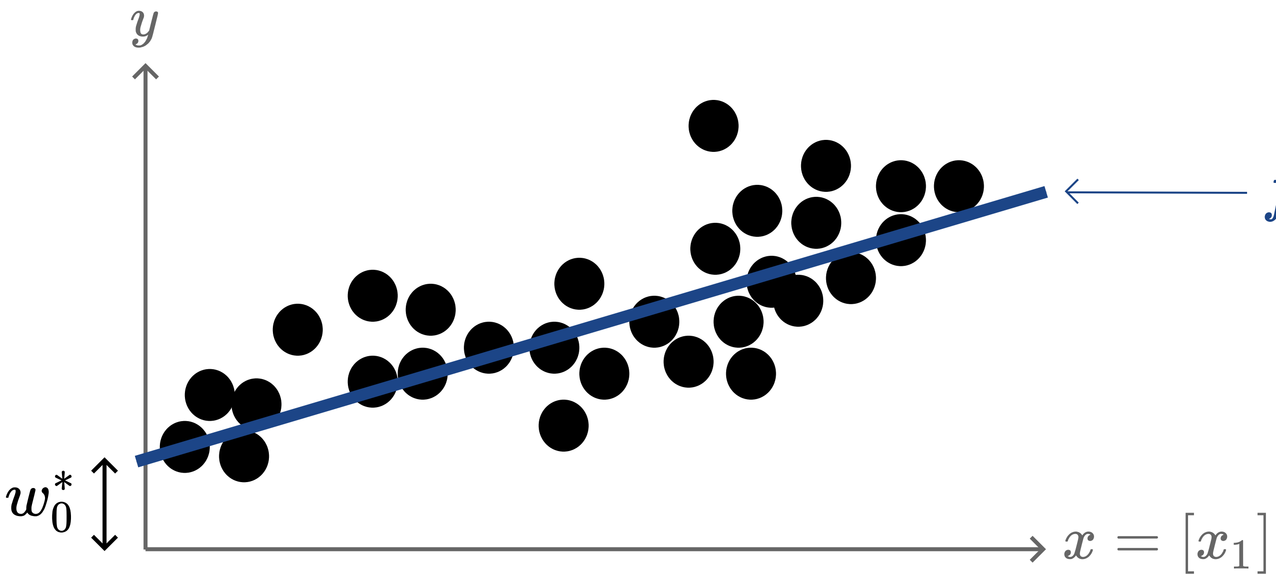
sum of squared errors **cost function**

$$J(w) = \frac{1}{2} \sum_{n=1}^{N} \left(y^{(n)} - w^\top x^{(n)} \right)^2$$



$$w^* = \arg\min_w J(w)$$

Example (D = 1) +bias (D=2)!

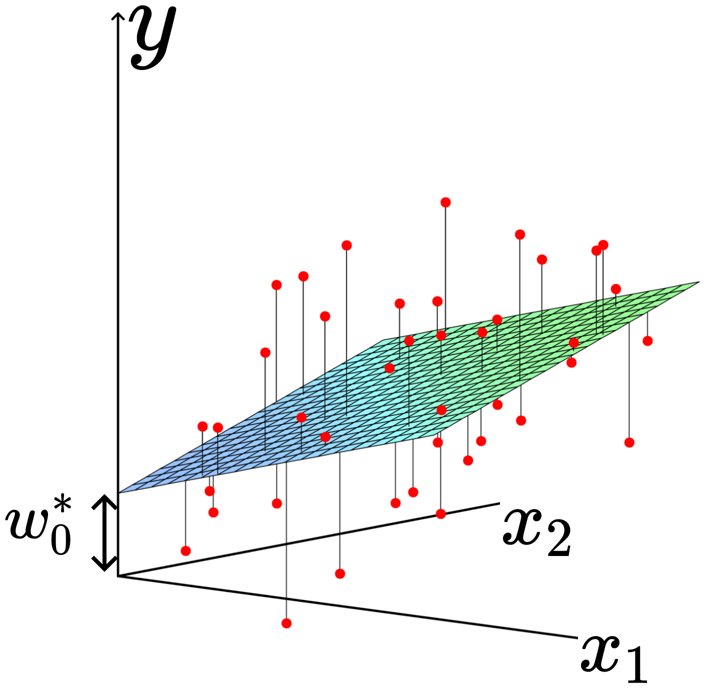


$$f_{w^*}(x) = w_0^* + w_1^* x$$

$$X = \begin{bmatrix} 1 & .3 \\ 1 & 1.2 \\ 1 & 1.5 \\ \cdot & \\ \cdot & \\ \cdot & \end{bmatrix}, \quad Y = \begin{bmatrix} .5 \\ .9 \\ 1 \\ \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

Linear Least Squares solution: $w^* = \arg\min_w \sum_n \frac{1}{2} \left(y^{(n)} - w^T x^{(n)} \right)^2$

Example (D=2) +bias (D=3)!



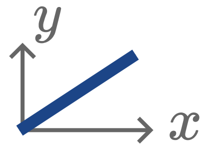
$$f_{w^*}(x) = w_0^* + w_1^* x_1 + w_2^* x_2$$

$$X = \begin{bmatrix} 1 & .3 & .5 \\ 1 & 1.2 & 1.6 \\ 1 & 1.5 & 1.2 \\ . & & \\ . & & \\ . & & \end{bmatrix}, \quad Y = \begin{bmatrix} .5 \\ .9 \\ 1 \\ . \\ . \\ . \end{bmatrix}$$

Linear Least Squares

$$w^* = \arg\min_w \sum_n \left(y^{(n)} - w^T x^{(n)} \right)^2$$

Minimizing the cost

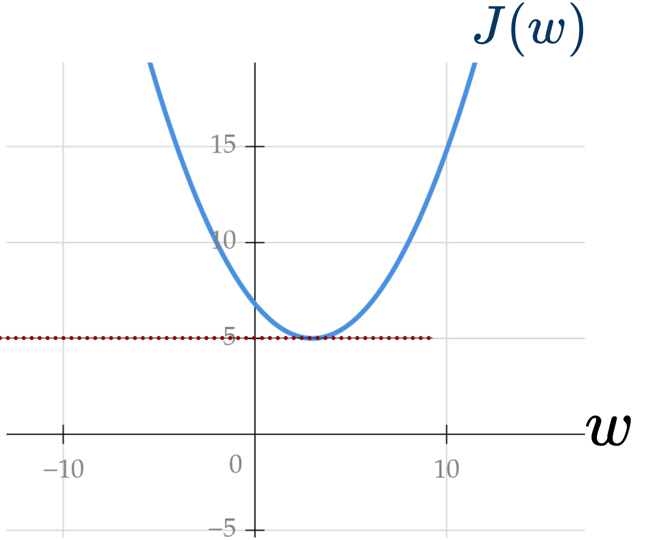


Simple case: D = 1 (no intercept)

model: $f_w(x) = \boxed{wx}$

both scalar

cost function $J(w) = \frac{1}{2}\sum_n (y^{(n)} - wx^{(n)})^2$



derivative: $\frac{\mathrm{d}J}{\mathrm{d}w} = \sum_n x^{(n)}(wx^{(n)} - y^{(n)})$

set to 0: $0 = w\sum_n x^{(n)}x^{(n)} - \sum_n x^{(n)}y^{(n)})$

setting the derivative to zero $w^* = \frac{\sum_n x^{(n)}y^{(n)}}{\sum_n x^{(n)\,2}}$

global minimum because the cost function is smooth and *convex*

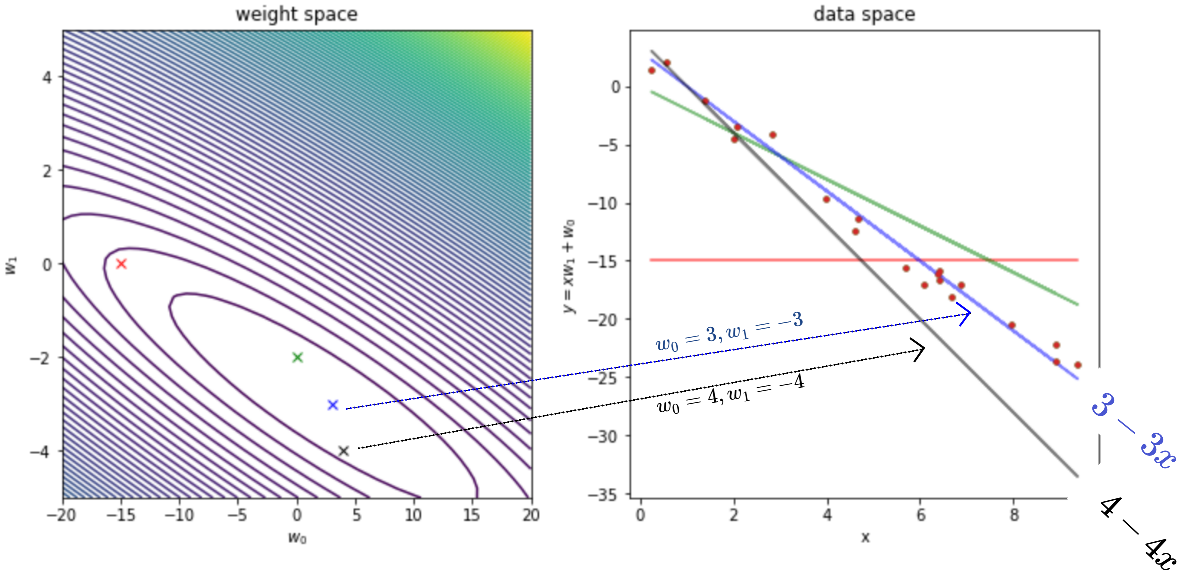
more on convexity layer

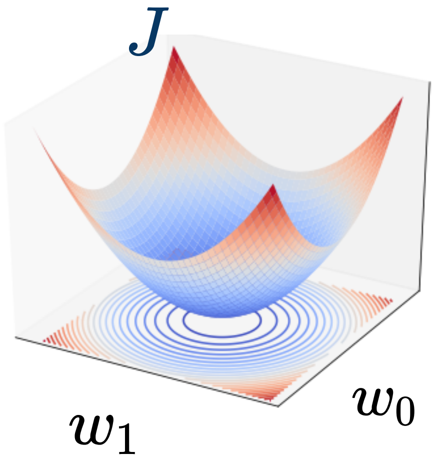
Minimizing the cost

D = 1 (with intercept)

model: $f_w(x) = w_0 + w_1 x$

cost: a multivariate function $J(w_0, w_1)$





the cost function is a smooth function of w

find minimum by setting partial derivatives to zero

Minimizing the cost

for a multivariate function $J(w_0, w_1)$

partial derivatives instead of derivative

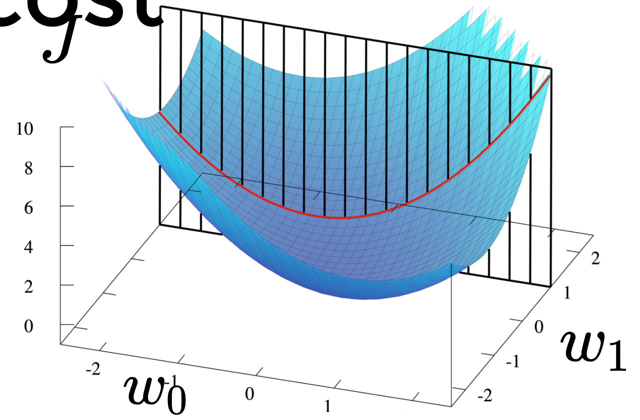
= derivative when other vars. are fixed

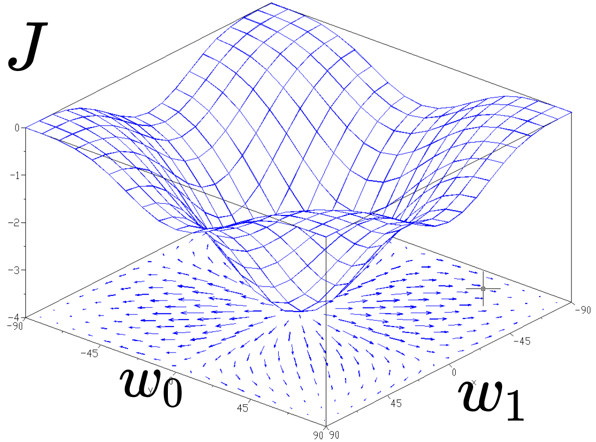
$$\frac{\partial}{\partial w_0} J(w_0, w_1) \triangleq \lim_{\epsilon \to 0} \frac{J(w_0+\epsilon, w_1) - J(w_0, w_1)}{\epsilon}$$

critical point: all partial derivatives are zero

gradient: vector of all partial derivatives

$$\nabla J(w) = [\frac{\partial}{\partial w_1} J(w), \cdots \frac{\partial}{\partial w_D} J(w)]^\top$$





Minimizing the cost

for general case (any D)

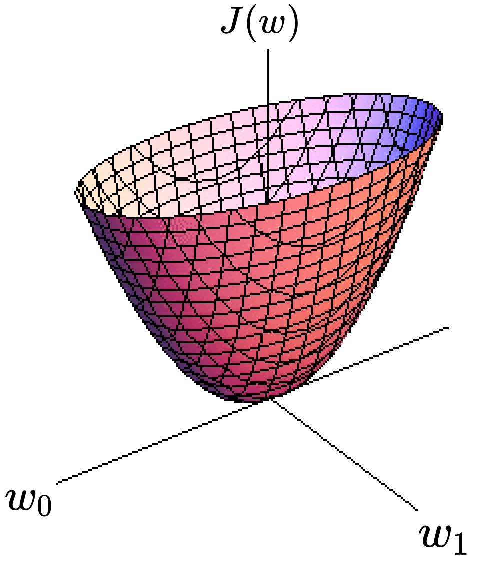
find the critical point by setting $\frac{\partial}{\partial w_d} J(w) = 0$

$$\frac{\partial}{\partial w_d} \sum_n \frac{1}{2}\left(y^{(n)} - f_w(x^{(n)})\right)^2 = 0$$

using **chain rule**: $\frac{\partial J}{\partial w_d} = \frac{\mathrm{d}J}{\mathrm{d}f_w} \frac{\partial f_w}{\partial w_d}$

we get $\sum_n (w^\top x^{(n)} - y^{(n)}) x_d^{(n)} = 0 \quad \forall d \in \{1, \ldots, D\}$

D equations with *D* unknowns



cost is a smooth and convex function of w

we are ignoring the bias term here, with the bias term, it would be D+1 equations and D+1 unknown for d in [0,D]

Linear regression: Matrix form

instead of $\underset{\in \mathbb{R}}{\hat{y}^{(n)}} = \underset{1 \times D}{w^\top} \underset{D \times 1}{x^{(n)}}$

Note: *D* is in fact dimensions of the input +1 due to the simplification and adding the bias/intercept term

use **design matrix** to write $\underset{N \times 1}{\hat{y}} = \underset{N \times D}{X} \underset{D \times 1}{w}$

$\hat{y}^{(1)} = w_0 + x_1^{(1)} w_1 + x_2^{(1)} w_2 + \cdots + x_D^{(1)} w_D$

$$\hat{Y} = \begin{bmatrix} \hat{y}^{(1)} \\ \hat{y}^{(2)} \\ \vdots \\ \hat{y}^{(N)} \end{bmatrix} = \begin{bmatrix} 1 & x_1^{(1)}, & x_2^{(1)}, & \cdots, & x_D^{(1)} \\ 1 & \vdots & \vdots & \ddots & \vdots \\ 1 & x_1^{(N)}, & x_2^{(N)}, & \cdots, & x_D^{(N)} \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ w_2 \\ \vdots \\ w_D \end{bmatrix}$$

Linear least squares

$$\arg\min_w \frac{1}{2}||y - Xw||_2^2 = \frac{1}{2}(y - Xw)^\top (y - Xw)$$

squared L2 norm of the **residual** vector

Minimizing the cost: Matrix form

Linear least squares

$$J(w) = \frac{1}{2}||y - Xw||^2 = \frac{1}{2}(y - Xw)^T(y - Xw)$$

$$y^T Xw = w^T X^T y$$

$$\frac{\partial J(w)}{\partial w} = \frac{\partial}{\partial w}[y^T y + w^T X^T Xw - 2y^T Xw]$$

$$\frac{\partial Xw}{\partial w} = X^T$$

Using matrix differentiation

$$\frac{\partial w^T Xw}{\partial w} = 2Xw$$

$$\frac{\partial J(w)}{\partial w} = 0 + X^T Xw - X^T y = X^T(Xw - y)$$

Minimizing the cost: Matrix form

Linear least squares

$$\hat{y} = Xw$$

$N \times 1$ $\quad$ $N \times D$ $\quad$ $D \times 1$

$$J(w) = \frac{1}{2}||y - Xw||^2 = \frac{1}{2}(y - Xw)^T(y - Xw)$$

$$\frac{\partial J(w)}{\partial w_i} = \frac{1}{2}\frac{\partial}{\partial w_i}[y^Ty + w^TX^TXw - 2y^TXw]$$

Minimizing the cost: Matrix form

$$\hat{y} = Xw$$

$N \times 1$ $N \times D$ $D \times 1$

Linear least squares

$$J(w) = \frac{1}{2}||y - Xw||^2 = \frac{1}{2}(y - Xw)^T(y - Xw)$$

$$\frac{\partial J(w)}{\partial w_i} = \frac{1}{2}\frac{\partial}{\partial w_i}[y^T y + w^T X^T X w - 2y^T X w]$$

$$\frac{\partial J(w)}{\partial w_i} = \frac{1}{2}\frac{\partial}{\partial w_i}[\sum_j y_{j1}y_{j1} + \sum_{j,k,m} w_{j1}X_{kj}X_{km}w_{m1} - \sum_{j,k} 2y_{j1}X_{jk}w_{k1}]$$

Minimizing the cost: Matrix form

Linear least squares

$$\hat{y} = Xw$$

$N \times 1$ $N \times D$ $D \times 1$

$$J(w) = \frac{1}{2}||y - Xw||^2 = \frac{1}{2}(y - Xw)^T(y - Xw)$$

$$\frac{\partial J(w)}{\partial w_i} = \frac{1}{2}\frac{\partial}{\partial w_i}[y^T y + w^T X^T X w - 2y^T X w]$$

$$\frac{\partial J(w)}{\partial w_i} = \frac{1}{2}\frac{\partial}{\partial w_i}[\sum_j y_{j1} y_{j1} + \sum_{j,k,m} w_{j1} X_{kj} X_{km} w_{m1} - \sum_{j,k} 2 y_{j1} X_{jk} w_{k1}]$$

✨Einstein notation: implicit sum on repeated indices✨$(AB)_{ij} = A_{ik}B_{kj}$

$$\frac{\partial J(w)}{\partial w_i} = \frac{1}{2}\frac{\partial}{\partial w_{i1}}[y_{j1} y_{j1} + w_{j1} X_{kj} X_{km} w_{m1} - 2 y_{j1} X_{jk} w_{k1}]$$

Minimizing the cost: Matrix form

$$\underset{N \times 1}{\hat{y}} = \underset{N \times D}{X} \underset{D \times 1}{w}$$

Linear least squares

$$J(w) = \frac{1}{2}||y - Xw||^2 = \frac{1}{2}(y - Xw)^T(y - Xw)$$

$$\frac{\partial J(w)}{\partial w_i} = \frac{1}{2}\frac{\partial}{\partial w_i}[y^T y + w^T X^T X w - 2y^T X w]$$

$$\frac{\partial J(w)}{\partial w_i} = \frac{1}{2}\frac{\partial}{\partial w_{i1}}[y_{j1}y_{j1} + w_{j1}X_{kj}X_{km}w_{m1} - 2y_{j1}X_{jk}w_{k1}]$$

$$= \frac{1}{2}[\delta_{ij}X_{kj}X_{km}w_{m1} + w_{j1}X_{kj}X_{km}\delta_{mi} - 2y_{j1}X_{jk}\delta_{ki}]$$

Minimizing the cost: Matrix form

Linear least squares

$$\underset{N\times 1}{\hat{y}} = \underset{N\times D}{X}\,\underset{D\times 1}{w}$$

$$J(w) = \frac{1}{2}||y - Xw||^2 = \frac{1}{2}(y - Xw)^T(y - Xw)$$

$$(AB)_{ij} = A_{ik}B_{kj}$$

$$\begin{aligned}\frac{\partial J(w)}{\partial w_i} &= \frac{1}{2}\frac{\partial}{\partial w_{i1}}[y_{j1}y_{j1} + w_{j1}X_{kj}X_{km}w_{m1} - 2y_{j1}X_{jk}w_{k1}] \\ &= \frac{1}{2}[\delta_{ij}X_{kj}X_{km}w_{m1} + w_{j1}X_{kj}X_{km}\delta_{mi} - 2y_{j1}X_{jk}\delta_{ki}] \\ &= \frac{1}{2}[X_{ki}X_{km}w_{m1} + w_{j1}X_{kj}X_{ki} - 2y_{j1}X_{ji}] = \left(\frac{2}{2}X^T(Xw - y)\right)_{i1}\end{aligned}$$

Minimizing the cost: Matrix form

$$\hat{y} = Xw$$

$N \times 1$ $\quad N \times D \quad D \times 1$

Linear least squares

$$J(w) = \frac{1}{2}||y - Xw||^2 = \frac{1}{2}(y - Xw)^T(y - Xw)$$

$$\frac{\partial J(w)}{\partial w_i} = \frac{1}{2}\frac{\partial}{\partial w_i}[y^T y + w^T X^T X w - 2y^T X w]$$

$$(AB)_{ij} = A_{ik}B_{kj}$$

$$= \frac{1}{2}[\delta_{ij}X_{kj}X_{km}w_{m1} + w_{j1}X_{kj}X_{km}\delta_{mi} - 2y_{j1}X_{jk}\delta_{ki}]$$

$$= \frac{1}{2}[X_{ki}X_{km}w_{m1} + w_{j1}X_{kj}X_{ki} - 2y_{j1}X_{ji}] = \left(\frac{2}{2}X^T(Xw - y)\right)_{i1}$$

$$0 = \frac{\partial J(w)}{\partial w} = X^T(Xw - y)$$

Minimizing the cost: Matrix form

Linear least squares

$$\underset{N \times 1}{\hat{y}} = \underset{N \times D}{X} \underset{D \times 1}{w}$$

$$0 = \frac{\partial J(w)}{\partial w} = X^T(Xw - y)$$

$$0 = X^T X w - X^T y \implies X^T X w = X^T y$$

$$\implies w = \left(X^T X\right)^{-1} X^T y$$

Closed form solution

$$\underbrace{X^\top}_{D \times N} \underbrace{(y - Xw)}_{N \times 1} = \vec{0}$$

matrix form (using the design matrix)

$$X^\top X w = X^\top y$$

system of D linear equations ($Aw = b$)

each row enforces one of D equations

similar to non-matrix form: optimal weights w* satisfy

$$\sum_n (y^{(n)} - w^\top x^{(n)}) x_d^{(n)} = 0 \quad \forall d$$

D equations with *D* unknowns

pseudo-inverse of X

$$w^* = \underbrace{(X^\top X)^{-1}}_{D \times D} \underbrace{X^\top}_{D \times N} \underbrace{y}_{N \times 1}$$

closed form solution

Closed form solution

$$\overbrace{X^\top}^{D \times N}\overbrace{(y - Xw)}^{N \times 1} = \vec{0}$$ matrix form (using the design matrix)

Normal equation: because for optimal w, the residual vector is normal to column space of the design matrix

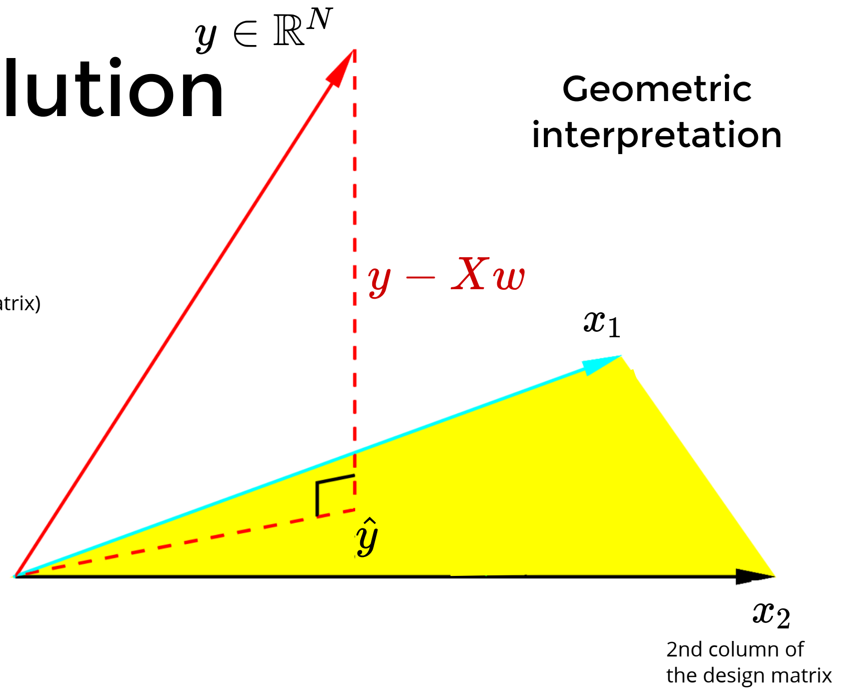
$X^\top X w = X^\top y$ system of D linear equations ($Aw = b$)

each row enforces one of D equations

$$w^* = \underbrace{(X^\top X)^{-1}}_{D \times D}\underbrace{X^\top}_{D \times N}\underbrace{y}_{N \times 1}$$

closed form solution

Geometric interpretation



$$\hat{y} = Xw = X(X^\top X)^{-1}X^\top y$$

projection matrix into column space of X

Uniqueness of the solution

we can get a closed form solution! $w^* = (X^\top X)^{-1} X^\top y$

unless $D \geq N$

or when the $X^\top X$ matrix is not invertible

this matrix is not invertible when some of eigenvalues are zero!

that is, if features are completely correlated

... or more generally if features are not linearly independent

examples having a binary feature x_1 as well as its negation $x_2 = (1 - x_1)$

Time complexity

$$w^* = (\underbrace{X^\top X}_{D \times D})^{-1} \underbrace{X^\top}_{D \times N} \underbrace{y}_{N \times 1}$$

$\mathcal{O}(ND)$ D elements, each using N ops.

$\mathcal{O}(D^3)$ matrix inversion

$\mathcal{O}(D^2N)$ D x D elements, each requiring N multiplications

total complexity for is $\mathcal{O}(ND^2 + D^3)$ which becomes $\mathcal{O}(ND^2)$ for $N > D$

in practice we don't directly use matrix inversion (unstable)

however, other more stable solutions (e.g., Gaussian elimination) have similar complexity

Multiple targets

instead of $y \in \mathbb{R}^N$ we have $Y \in \mathbb{R}^{N \times D'}$

a different weight vectors for each target

each column of Y is associated with a column of W

$$\underbrace{\hat{Y}}_{N \times D'} = \underbrace{X}_{N \times D} \underbrace{W}_{D \times D'}$$

$$W^* = \underbrace{(X^\top X)}_{D \times D}{}^{-1} \underbrace{X^\top}_{D \times N} \underbrace{Y}_{N \times D'}$$

$$\hat{Y} = \begin{bmatrix} \hat{y}_1^{(1)} & \hat{y}_2^{(1)} \\ \hat{y}_1^{(2)} & \hat{y}_2^{(2)} \\ \vdots & \\ \hat{y}_1^{(N)} & \hat{y}_2^{(N)} \end{bmatrix} = \begin{bmatrix} 1 & x_1^{(1)}, & x_2^{(1)}, & \cdots, & x_D^{(1)} \\ 1 & \vdots & \vdots & \ddots & \vdots \\ 1 & x_1^{(N)}, & x_2^{(N)}, & \cdots, & x_D^{(N)} \end{bmatrix} \begin{bmatrix} w_{0,1} & w_{0,2} \\ w_{1,1} & w_{1,2} \\ w_{2,1} & w_{2,2} \\ \vdots & \\ w_{D,1} & w_{D,2} \end{bmatrix}$$

$$\hat{y}_1^{(1)} = w_{0,1} + x_1^{(1)} w_{1,1} + x_2^{(1)} w_{2,1} + \cdots + x_D^{(1)} w_{D,1}$$

$$\hat{y}_2^{(1)} = w_{0,2} + x_1^{(1)} w_{1,2} + x_2^{(1)} w_{2,2} + \cdots + x_D^{(1)} w_{D,2}$$

Fitting non-linear data

so far we learned a linear function $f_w = \sum_d w_d x_d$

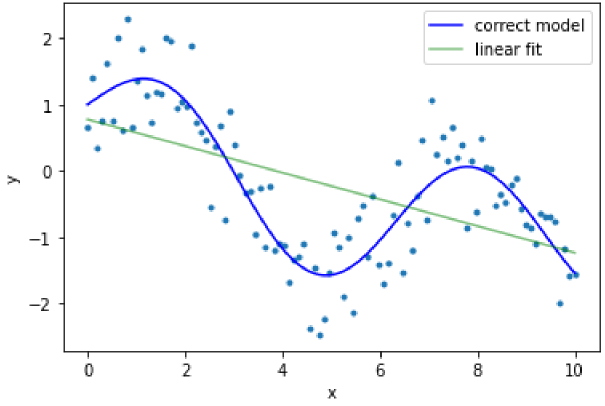
sometimes this may be too simplistic

example

Synthetic data when we generated data from a function $y^* = \sin(x) + cos(\sqrt{x})$

$$\mathcal{D} = \{(x^{(n)}, y^*(x^{(n)}) + \epsilon\}_{n=1}^{N}$$

small noise



we see linear fit is not close to correct model that the data is generated from, can we get a better fit?

idea create new more useful features out of initial set of given features

e.g., $x_1^2, x_1 x_2, \log(x),$ how about $x_1 + 2x_3$?

Nonlinear basis functions

so far we learned a linear function $f_w = \sum_d w_d x_d$

let's denote the set of all features by $\phi_d(x) \forall d$

the problem of linear regression doesn't change $f_w = \sum_d w_d \phi_d(x)$

$\phi_d(x)$ *is the new x*

solution simply becomes $(\Phi^\top \Phi) w^* = \Phi^\top y$

replacing X with Φ

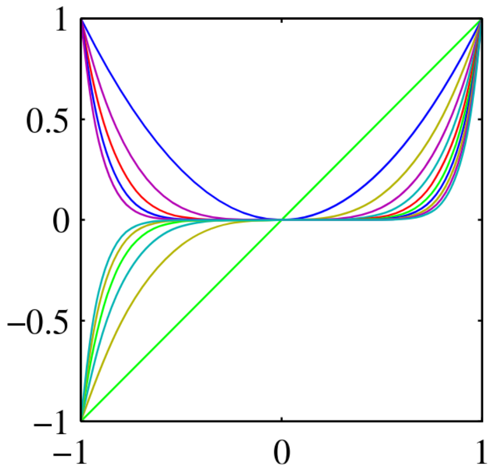
a (nonlinear) feature

$$\Phi = \begin{bmatrix} \phi_1(x^{(1)}), & \phi_2(x^{(1)}), & \cdots, & \phi_D(x^{(1)}) \\ \phi_1(x^{(2)}), & \phi_2(x^{(2)}), & \cdots, & \phi_D(x^{(2)}) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_1(x^{(N)}), & \phi_2(x^{(N)}), & \cdots, & \phi_D(x^{(N)}) \end{bmatrix}$$

one instance

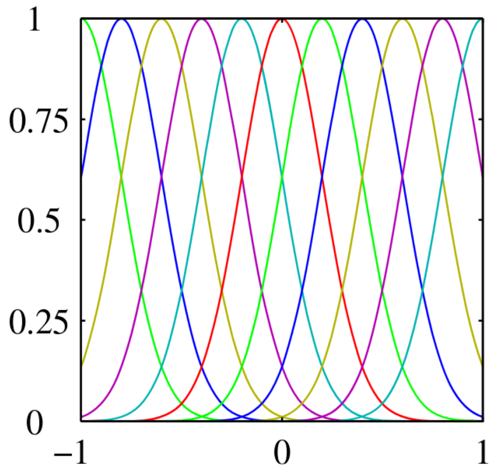
Nonlinear basis functions

example original input is scalar $x \in \mathbb{R}$



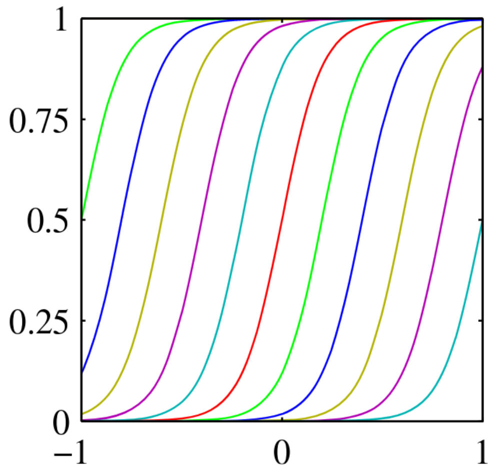
polynomial bases

$$\phi_k(x) = x^k$$



Gaussian bases

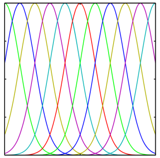
$$\phi_k(x) = e^{-\frac{(x-\mu_k)^2}{s^2}}$$



Sigmoid bases

$$\phi_k(x) = \frac{1}{1+e^{-\frac{x-\mu_k}{s}}}$$

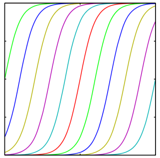
Linear regression with nonlinear bases: example



Gaussian bases

$$\phi_k(x) = e^{-\frac{(x-\mu_k)^2}{s^2}}$$

we are using a fixed standard deviation of s=1

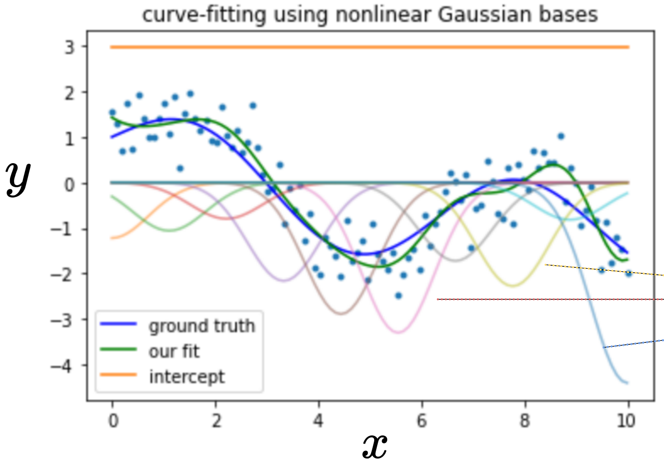


Sigmoid bases

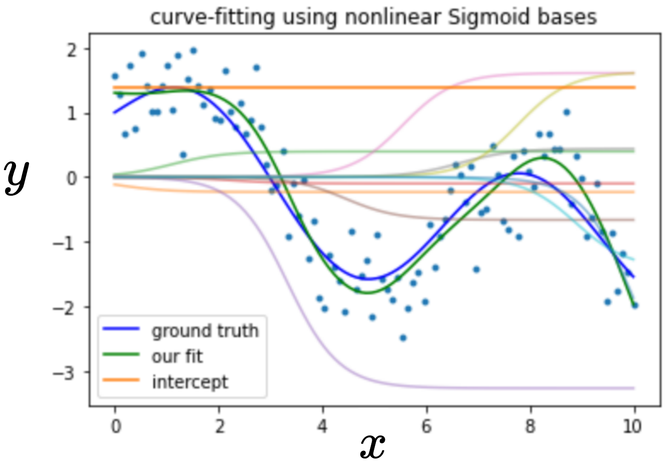
$$\phi_k(x) = \frac{1}{1+e^{-\frac{x-\mu_k}{s}}}$$

we are using a fixed standard deviation of s=1

$$\hat{y}^{(n)} = w_0 + \sum_k w_k \phi_k(x)$$



the green curve (our fit) is the sum of these scaled Gaussian bases plus the intercept. Each basis is scaled by the corresponding weight



Probailistic interpretation

idea given the dataset $\mathcal{D} = \{(x^{(1)}, y^{(1)}), \ldots, (x^{(N)}, y^{(N)})\}$

learn a probabilistic model $p(y|x; w)$

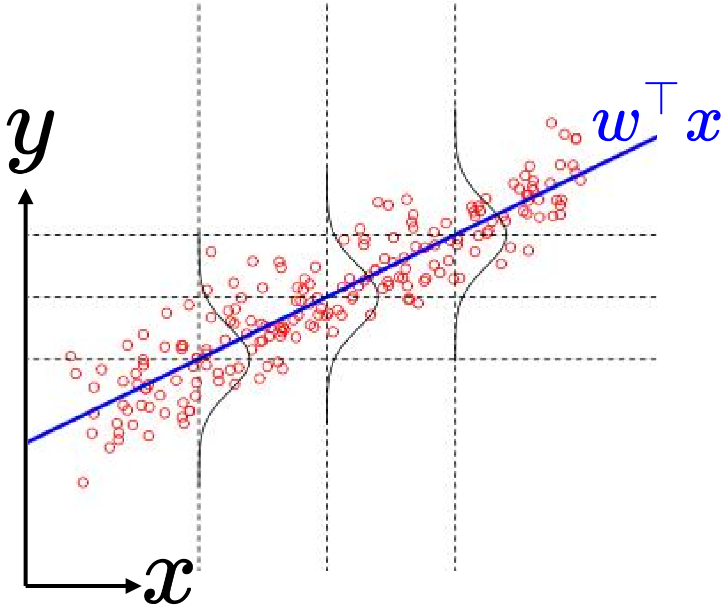


image from here

consider $p(y|x;w)$ with the following form

$$p_w(y \mid x) = \mathcal{N}(y \mid w^\top x, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y-w^\top x)^2}{2\sigma^2}}$$

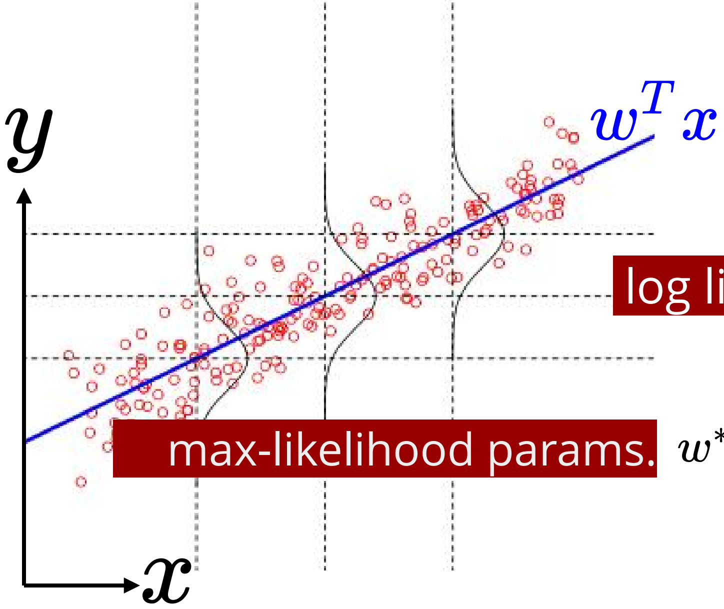
assume a fixed variance, say $\sigma^2 = 1$

Q: how to fit the model?

A: maximize the conditional likelihood!

Maximum likelihood & linear regression

cond. probability $p(y \mid x; w) = \mathcal{N}(y \mid w^\top x, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y - w^\top x)^2}{2\sigma^2}}$



likelihood $L(w) = \prod_{n=1}^{N} p(y^{(n)} \mid x^{(n)}; w)$

log likelihood $\ell(w) = \sum_n -\frac{1}{2\sigma^2}(y^{(n)} - w^\top x^{(n)})^2 + \text{constants}$

max-likelihood params. $w^* = \arg\max_w \ell(w) = \arg\min_w \frac{1}{2} \sum_n (y^{(n)} - w^\top x^{(n)})^2$

linear least squares!

image from here

whenever we use square loss, we are assuming Gaussian noise!

Summary

linear regression:

- models targets as a linear function of features
- fit the model by minimizing the sum of squared errors
- has a direct solution with $\mathcal{O}(ND^2 + D^3)$ complexity
- probabilistic interpretation

we can build more expressive models:

- using any number of non-linear features