

COMP 204

Introduction to image analysis with scikit-image (part three)

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Edge detection

Goal: Identify regions of the image that contain sharp changes in colors/intensities.

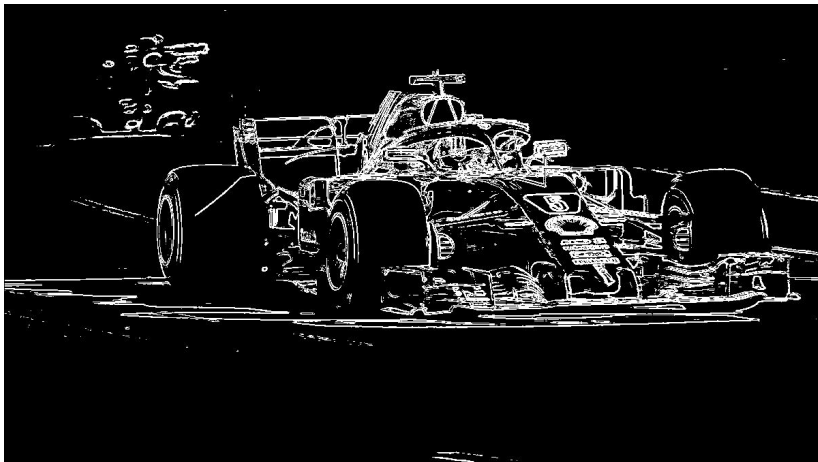
Why? Useful for

- ▶ delineating objects (image segmentation)
- ▶ recognizing them (object recognition)
- ▶ etc.

Edge detection



Edge detection



Edge detection

What's an edge in an image?

Horizontal edge at row i :

- ▶ $image[i - 1, j]$ is very different from $image[i + 1, j]$

Vertical edge at column j :

- ▶ $image[i, j - 1]$ is very different from $image[i, j + 1]$

Idea: To determine if an RGB pixel (i, j) belongs to an edge:

For each color $\in \{R, G, B\}$:

- ▶ $L_x[color] = image[i, j - 1, color] - image[i, j + 1, color]$
- ▶ $L_y[color] = image[i - 1, j, color] - image[i + 1, j, color]$
- ▶ $gradient[color] = \sqrt{L_x[color]^2 + L_y[color]^2}$

$edginess = \sqrt{gradient[R]^2 + gradient[G]^2 + gradient[B]^2}$

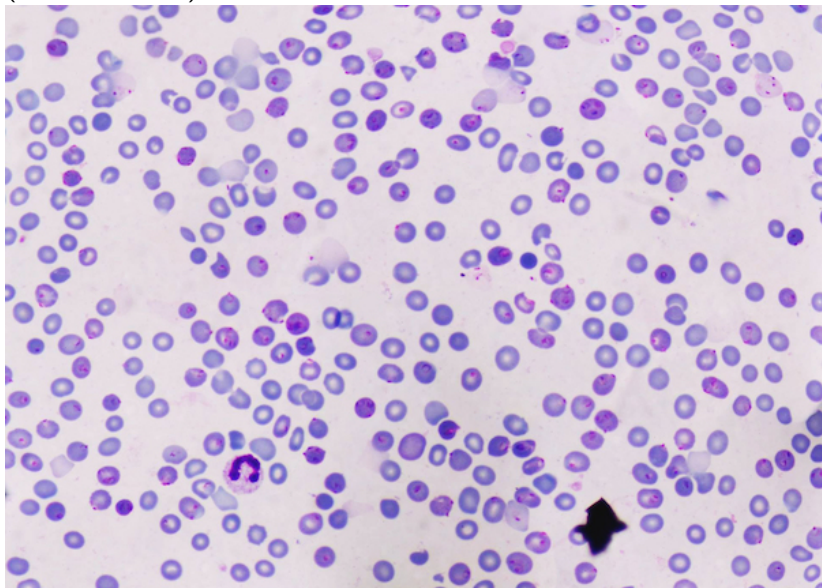
if $edginess > some_threshold$, then pixel (i, j) belongs to an edge

Edge detection

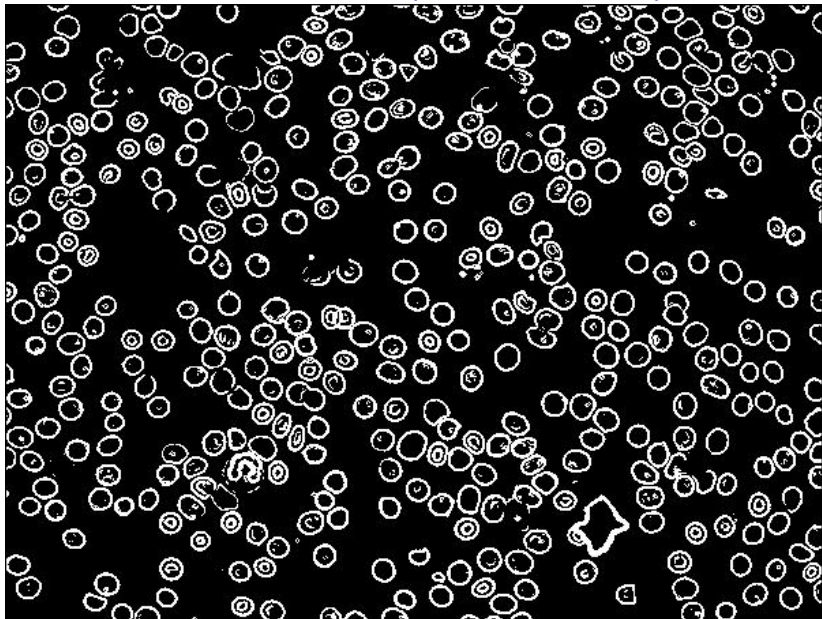
```
1 def detect_edges(im, min_gradient=50):
2     """
3     Args:
4         im: The image on which to detect edges
5         min_gradient: The minimum gradient value
6                     for a pixel to be called an edge
7     Returns: An new image with edge pixels set to white,
8             and everything else set to black
9     """
10    n_row, n_col, colors = image.shape
11
12    # create a empty empty of the same size as the original
13    edge_image = np.zeros( (n_row, n_col, 3), dtype=np.uint8)
14
15    for i in range(1, n_row-1): # avoid the first/last row
16        for j in range(1, n_col-1): # and first/last col
17            grad=[0,0,0]
18            for c in range(3): # for each color
19                Lx = float(im[i-1,j,c])-float(im[i+1,j,c])
20                Ly = float(im[i,j-1,c])-float(im[i,j+1,c])
21                grad[c] = math.sqrt(Lx**2+Ly**2)
22            norm = math.sqrt(grad[0]**2 + grad[1]**2 \
23                            + grad[2]**2)
24            if (norm > min_gradient):
25                edge_image[i,j] = (255,255,255)
26    return edge_image
```

Analysis of microscopy images

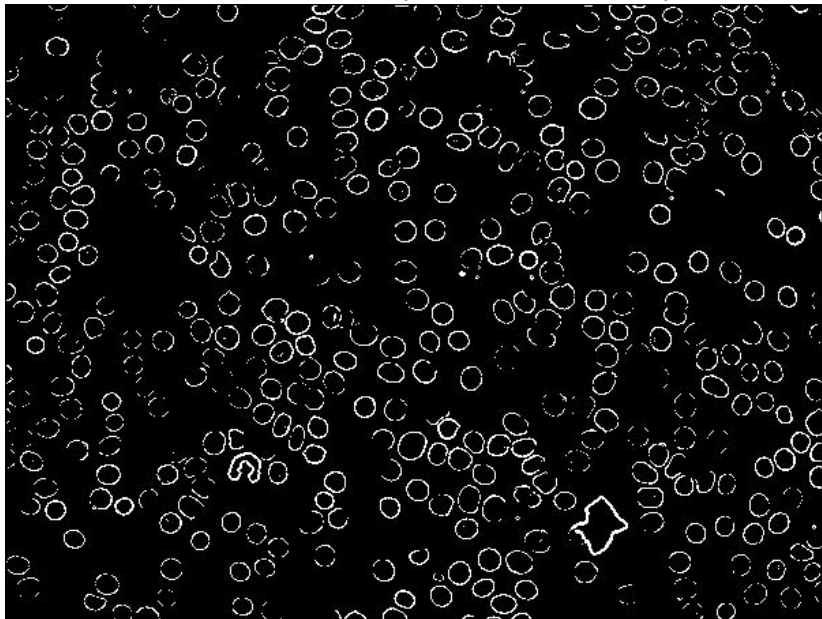
Cells (purple "circles") are infected by *Plasmodium falciparum* (small red dots).



Edge detection (threshold = 60)



Edge detection (threshold = 120)



Edge detection

Skimage has many edge detection algorithms:

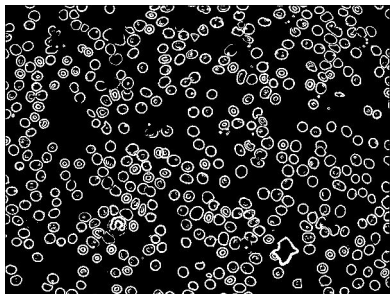
http://scikit-image.org/docs/0.5/auto_examples/plot_canny.html

Counting/annotating cells

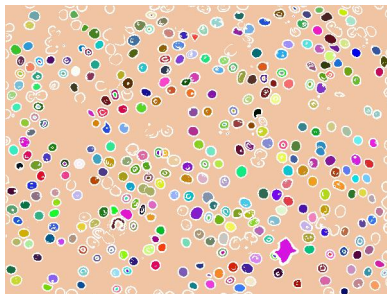
What if we want to automatically identify/count cells in the image?

Idea:

1. Find edges in the image
2. Identify closed (encircled) shapes within the edge image



to



Each closed shape is assigned a different color.

Number of closed shapes (= approximation to cell count) is calculated.

Seed filling algorithm

How to take an edge image and fill-in each closed shape?

Seed filling (aka flood filling) algorithm:

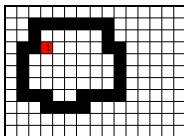
- ▶ Start from a black pixel.
- ▶ Color it and expand to its neighboring pixel, unless neighbor is an edge (white).
- ▶ Keep expanding until no more expansion is possible
- ▶ Repeat from a new starting point, until no black pixels are left

Seed filling algorithm

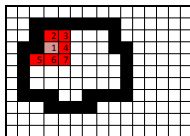
Oops: I've swapped black and white!...

Black = edge, white = background

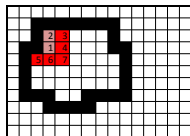
Seed = pixel at position (4,4)



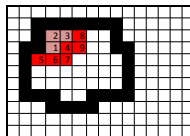
Front: [1]



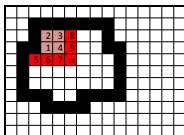
Front: [2, 3, 4, 5, 6, 7]



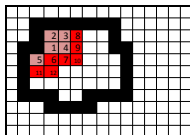
Front: [3, 4, 5, 6, 7]



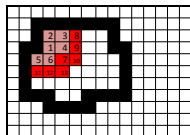
Front: [4, 5, 6, 7, 8, 9]



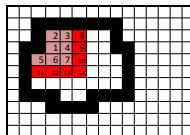
Front: [5, 6, 7, 8, 9, 10]



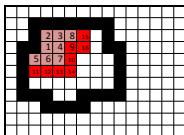
Front: [6, 7, 8, 9, 10, 11, 12]



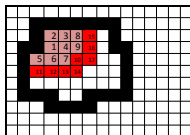
Front: [7, 8, 9, 10, 11, 12, 13]



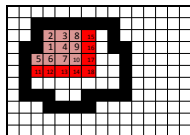
Front: [8, 9, 10, 11, 12, 14]



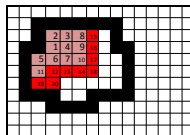
Front: [9, 10, 11, 12, 14, 15, 16]



Front: [10, 11, 12, 14, 15, 16, 17]



Front: [11, 12, 14, 15, 16, 17, 18]



Front: [12, 14, 15, 16, 17, 18, 19, 20]

Seed filling implementation

```
1 def seedfill(im, seed_row, seed_col, fill_color, bckg):
2     """
3     im: The image on which to perform the seedfill algorithm
4     seed_row and seed_col: position of the seed pixel
5     fill_color: Color for the fill
6     bckg: Color of the background, to be filled
7     Returns: Number of pixels filled
8     Behavior: Modifies image by performing seedfill
9     """
10    size=0 # keep track of patch size
11    n_row, n_col, foo = im.shape
12    front=[(seed_row, seed_col)] # initial front
13    while len(front)>0:
14        r, c = front.pop(0) # remove 1st element of front
15        # This is how to test equality of two np.arrays
16        if np.array_equal(im[r, c], bckg):
17            im[r, c]=fill_color # color the pixel
18            size+=1
19            # look at all neighbors
20            for i in range(max(0, r-1), min(n_row, r+2)):
21                for j in range(max(0, c-1), min(n_col, c+2)):
22                    # if background, add to front
23                    if np.array_equal(im[i, j], bckg) and \
24                       (i, j) not in front:
25                        front.append((i, j))
26    return size
```

Seeding from all possible starting pixel...

```
1 filename="malaria2"
2 fig=plt.figure() # ignore this
3 image = io.imread(filename+".jpg")
4
5 edge_image = detect_edges(image, 60)
6 io.imsave(filename+"_edge.jpg",edge_image)
7
8 min_cell_size=100 # based on prior knowledge
9 max_cell_size=300 # based on prior knowledge
10 n_cells=0
11
12 for i in range(edge_image.shape[0]):
13     for j in range(edge_image.shape[1]):
14         # if pixel is black, seedfill from here
15         if np.array_equal(edge_image[i,j,:],(0,0,0)):
16             rand_color = (random.randrange(255),
17                           random.randrange(255),
18                           random.randrange(255))
19             size=seedfill_with_animation(edge_image, i ,j ,
20                                         rand_color,(0,0,0))
21             if size>= min_cell_size and size<max_cell_size:
22                 n_cells+=1
23 print("Number of cells:", n_cells) # Number of cells: 208
```

Seed filling execution

See live execution of program

Issues

Several things would need to be improved to get a more accurate cell count:

- ▶ Some cells are not surrounded by a closed edge because of lack of contrast; those end up not being counted.
- ▶ In some cells, the nucleus is enclosed by an edge. Those cells often end up not being counted, because both the cytoplasmic and nuclear portions are too small to be called a cell.
- ▶ Some cells may not be red blood cells, and should not be counted
- ▶ etc...