COMP 204

Introduction to image analysis with scikit-image (part two)

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Grayscaling

Many image processing algorithms assume a 2D matrix

not an image with a third dimension of color

To bring the image into two dimensions

- we need to summarize the three colors into a single value
- this process is more commonly know as grayscaling
- where the resulting image only holds intensities of gray
 - with values between 0 and 1

skimage submodule color has useful functions for this task

► API

http://scikit-image.org/docs/dev/api/skimage.

color.html

Grayscaling

Goal: Create a grayscale version of a color image (see next slide)

```
1 import skimage.io as io
2 import skimage.color as color
3 import matplotlib.pyplot as plt
4 from skimage.color import rgb2gray
5
6 # read image into memory
7 image = io.imread("monkey.jpg")
8 # convert to grayscale
gray_image = rgb2gray(image)
  print(image[0,0]) # prints [255,255,255]
12 print (gray_image [0,0]) # prints 1.0
  plt.imshow(gray_image)
14 plt.show()
15 io.imsave("monkey_grayscale.jpg",gray_image)
```



Binary image

Goal: Produce a black-and-white version of a color image (see next slide).

```
1 import skimage.io as io
2 import skimage.color as color
3 import matplotlib.pyplot as plt
4 from skimage.color import rgb2gray
5 import numpy as np
6
  image = io.imread("monkey.jpg")
8 gray_image = rgb2gray(image)
9
10 # this creates a new array.
11 # with 1's everywhere gray_image > 0.5, and 0 elsewhere
  black_and_white = np.where(gray_image > 0.5, 255, 0)
  plt.imshow(black_and_white)
15 plt.show()
16 io.imsave("monkey_black_and_white.jpg", black_and_white)
```



Blurring an image

Goal: Reduce the resolution of an image by blurring it, e.g. to reduce fine-level "noise" (unwanted details).

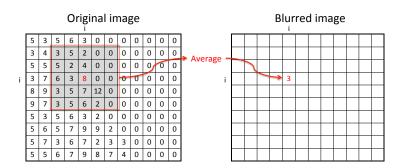




Blurring an image

Blurring is achieved by replacing each pixel by the average value of the pixels in a small window centered on it.

Example, window of size 5:



Blurring an image

```
1 def blur(image, filter_size):
      n_row, n_col, colors = image.shape
      blurred=np.zeros((n_row, n_col, colors),dtype=np.uint8)
3
      half_size=int(filter_size/2)
      for i in range(n_row):
5
           for j in range(n_col):
6
              # define the boundaries of window around (i,j)
               left=max(0,j-half_size)
8
               right=min(j+half_size,n_row)
               top=max(0,i-half_size)
10
               bot=min(n_col,i+half_size)
              # calculate average of RGB values in window
12
               blurred[i,j] = 
13
                   image [bot:top, left:right,:].mean(axis=(0,1))
14
      return blurred_image
15
```

- image[bottom:top, left:right , ,:] corresponds to the sub-image ranging from rows bottom to top-1 and columns left to right-1, and all 3 color dimensions.
- means(axis=(0,1)) states that we want to take an average over dimension 0 (rows) and dimension 1 (columns) but not dimension 2 (RGB). This returns that a 1d ndarray containing the average red, green, and blue values in the subimage.

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Original image



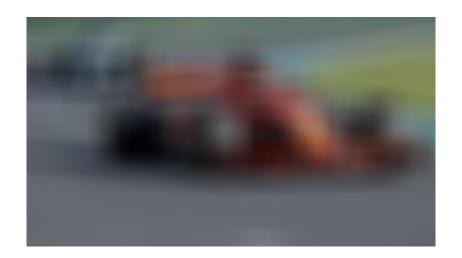
Window size = 5



Window size = 21



Window size = 101



Running time issues

Note: When our window size is large (say 101), blurring the image is slow (> 1 minute). Why?

- ► Our image is 674 × 1200 pixels.
- For each pixel in the image, we need to calculate the average of the 101×101 pixels around it, and for each of the three colors!
- The total number of operations is proportional to $674 \times 1200 \times 101 \times 101 = 25$ Billion operations!

SkImage has many built-in blurring functions (called filters) with faster implementations:

http://scikit-image.org/docs/dev/api/skimage.filters.html

Goal: Identify regions of the image that contain sharp changes in colors/intensities.

Why? Useful for

- delineating objects (image segmentation)
- recognizing them (object recognition)
- etc.





What's an edge in an image?

Horizontal edge at row i: image(i-1,j) is very different from image(i+1,j)

Vertical edge at column j: image(i, j-1) is very different from image(i, j+1)

Idea:

For each position (i,j) and each color (RGB), calculate change_hor = image(i-1,j, color) - image(i+1,j, color) change_vert = image(i,j-1, color) - image(i,j+1, color) edge_image(i,j,color) = sqrt(change_hor^2 + change_vert^2)

```
def detect_edges(image):
      n_row, n_col, colors = image.shape
      edge_image = np.zeros( (n_row, n_col, 3), dtype=np.uint8)
3
      for i in range (1, n_row - 1):
4
           for j in range (1, n\_col -1):
               for c in range(3):
7
                   # conversion to int needed to accommodate
8
                   # for potentially negative values
9
                    d_r=int(image[i-1,j,c])-int(image[i+1,j,c])
                    d_c = int(image[i, i-1, c]) - int(image[i, i+1, c])
                    grad = math.sqrt(d_r**2+d_c**2)
12
13
                   # limit value to 255
14
                    edge_image[i,j,c]=np.uint8(min(255,grad))
15
       return edge_image
16
```

Edge detection on monkey image



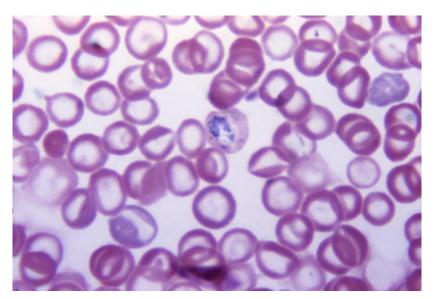
Not so great if our goal is to find the monkey in the image!

Blurring + Edge detection

To smooth out fine details like leaves: Start by blurring the image, then apply edge detection.



Analysis of microscopy images





Skimage has many edge detection algorithms: http://scikit-image.org/docs/0.5/auto_examples/plot_canny.html