Sample-efficient Learning of Mixture Models

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(Slides created by Hassan)

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 - Given an iid sample generated from an unknown density g^* , find density \hat{g} that is "close" to g.

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 - Statistical efficiency
 - Computational efficiency
- Our focus is on statistical efficiency
- We improve the state-of-the-art for learning mixture models in terms of sample complexity.





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- $\bullet \ \mathcal{F}$ is a class of probability density functions.
 - E.g., Multivariate Gaussian pdfs over \mathbb{R}^d
- Δ_k is the *k*-dimensional simplex.
 - $\Delta_k = \{(w_1, ..., w_k) : w_i \ge 0, \sum w_i = 1\}$
- The class of k-mixtures of \mathcal{F} is defined by
 - $\mathcal{F}^k := \{\sum_{i=1}^k w_i f_i : (w_1, \ldots, w_k) \in \Delta_k, f_1, \ldots, f_k \in \mathcal{F}\}$
 - E.g., Gaussian Mixture Models (GMMs) with k components.
- Lots of applications, e.g., in modelling multi-modal distributions

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$$\|g - \hat{g}\|_{TV} \coloneqq \sup_{A \subset \mathbb{R}^d} |g(A) - \hat{g}(A)|$$

• $\|g - \hat{g}\|_{TV} = \frac{1}{2} \|g - \hat{g}\|_1 = \frac{1}{2} \int_z |g - \hat{g}| dz$

PAC-Learning of Distributions (Realizable Setting)

A distribution learning method is called a PAC-learner for \mathcal{F} with sample complexity $m_{\mathcal{F}}(\epsilon, \delta)$ if for all distribution $g \in \mathcal{F}$ and all $\epsilon, \delta > 0$, given ϵ , δ , and a sample of size $m_{\mathcal{F}}(\epsilon, \delta)$, with probability at least $1 - \delta$ outputs an ϵ -approximation of g.

Main Theorem

Assume that \mathcal{F} can be learned in the realizable setting with sample complexity $m_{\mathcal{F}}(\epsilon, \delta)$ Then the class \mathcal{F}^k can be learned with

$$m_{\mathcal{F}^k}(\epsilon,\delta) = O\left(rac{k\log k \cdot m_{\mathcal{F}}(\epsilon,\delta/3k)}{\epsilon^2}
ight)$$

samples.

So by going from one component to a mixture of k components, the sample complexity increases at most by a factor of $(k \log k)/\epsilon^2$.

Learning Axis-aligned Gaussians

The class of *d*-dimensional axis-aligned Gaussians is PAC-learnable in the realizable setting with $m_F(\epsilon, \delta) = O((d + \log(1/\delta))/\epsilon^2)$



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- (Somewhat) Improvement over previous known upper bounds
 - $\widetilde{O}(dk^9/\epsilon^4)$ (Suresh, Orlitsky, Acharya, Jafarpour'14)
 - $\widetilde{O}((d^2k^4 + d^3k^3)/\epsilon^2)$ (Karpinski and Macintyre (1997))

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Lower Bound (Suresh, Orlitsky, Acharya, Jafarpour'14)

The sample complexity of learning mixtures of k axis-aligned Gaussians in \mathbb{R}^d in the realizable setting is $m_{\mathcal{F}^k}(\epsilon, 1/2) = \Omega(dk/\epsilon^2)$.

Learning Gaussians

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Learning Mixture of Gaussians

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 - $\widetilde{O}(d^2k^3/\epsilon^4)$ (Diakonikolas, Kane, Stewart'17)
 - $\widetilde{O}(d^4k^4/\epsilon^2)$ (Karpinski and Macintyre'97)

High level overview of the algorithm

- Create a finite set of "candidate" pdfs based on the sample
- Choose the best one based on a fresh new sample

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Learning Finite Classes (Devroye and Lugosi (2001))

For a finite class \mathcal{F} of distributions, there is an algorithm than learns \mathcal{F} with $O(\log(M)/\epsilon^2)$ new samples.

Learning means choosing the closest candidate from ${\mathcal F}$ to the target.

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Note that we know how to learn a single Gaussian using d^2/ε^2 samples But in the case of mixtures, we don't know which sample point came from which component of mixture,

but we can try "all" possible cases (exhaustive search) to generate the candidates.

Algorithm

Recall, target has form $\{\sum_{i=1}^{k} w_i f_i : w_i \ge 0, \sum w_i = 1, f_1, \dots, f_k \in \mathcal{G}_d\}$ In words: try all possible ways of partitioning data into components, and all possible mixture weights

Input: k, ϵ, δ and an iid sample S of size kd^2/ε^2 0. Let \widehat{W} be an (ϵ/k) -cover for Δ_k in ℓ_{∞} distance. 1. $\mathcal{C} = \emptyset$. (set of candidate distributions) 2. For each $(\widehat{w}_1, \dots, \widehat{w}_k) \in \widehat{W}$ do: 3. For each possible partition of S into A_1, A_2, \dots, A_{k+1} : 4. Provide A_i to the \mathcal{F} -learner, and let \widehat{G}_i be its output. 5. Add the candidate distribution $\sum_{i \in [k]} \widehat{w}_i \widehat{G}_i$ to \mathcal{C} . 6. Apply the algorithm for finite classes to \mathcal{C} and output its result.

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Input: k, ε, δ and an iid sample S of size kd²/ε²
0. Let W be an (ε/k)-cover for Δ_k in ℓ_∞ distance.
1. C = Ø. (set of candidate distributions)
2. For each (ŵ₁,..., ŵ_k) ∈ W do:
3. For each possible partition of S into A₁, A₂, ..., A_{k+1}:
4. Provide A_i to the *F*-learner, and let Ĝ_i be its output.
5. Add the candidate distribution ∑_{i∈[k]} ŵ_i Ĝ_i to C.
6. Apply the algorithm for finite classes to C and output its result.

• $|C| \le k^{kd^2/\varepsilon^2} \times (1/\varepsilon)^k$ so $\log |C| \le (kd^2/\varepsilon^2) \log k + k \log(1/\varepsilon)$.

• Remains to prove that there is an ϵ -close candidate in C.

• For learning mixture of k Gaussians in \mathbb{R}^d ,

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within log factors. Close the gap! Guess: correct answer is $\frac{kd^2}{\epsilon^2}$

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Thank You!