Jigsaw Image Mosaics (JIM)

Based on the paper 'Jigsaw Image Mosaics' by Junhwan Kim and Fabio Pellacini, SIGGRAPH 2002



April 1, 2004 Presentation by Kaleigh Smith

Outline



- Description of JIM, artistic inspiration and related work
- Definition of JIM Energy Framework
- Input Preparation and Active Contours
- Mosaic Algorithm
- Algorithm Optimizations
- JIM Results
- Comments on JIM

Junhwan Kim Fabio Pellacini

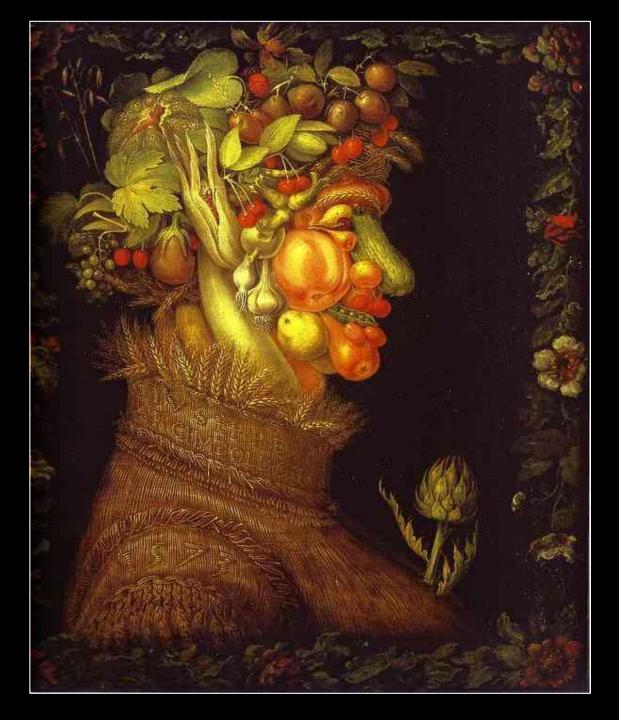
SIGGRAPH 2002





Arcimboldo 1527-1593

Summer, 1573



Photomosaic

Robert Silvers and Michael Hawley

1997



Photomosaic



- Fixed container shape (rectangular)
- Fixed tile shape (rectangular)
- Fixed packing (grid)

Photomosaic

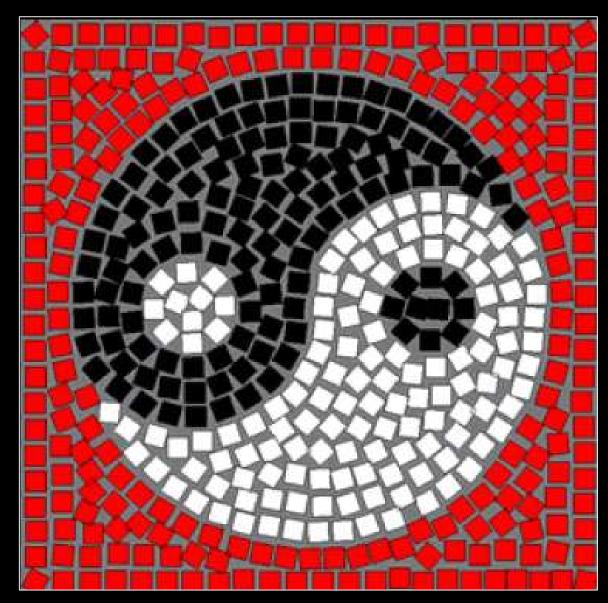


- Fixed container shape (rectangular)
- Fixed tile shape (rectangular)
- Fixed packing (grid)
- Match the intensity of the tile texture to the underlying image intensity. No special packing.

Simulated Decorative Mosaic

Alejo Hausner

SIGGRAPH 2001

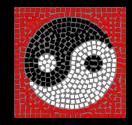


Simulated Decorative Mosaic



- Fixed container shape (rectangular)
- Fixed tile shape (rectangular or elliptical)
- Important image edges represented by userspecified feature curves.

Simulated Decorative Mosaic



- Fixed container shape (rectangular)
- Fixed tile shape (rectangular or elliptical)
- Important image edges represented by userspecified feature curves.
- Determines best packing of tiles in container and orients tiles to feature curves to preserve edges from the source image.
- Allows tile configuration to have gaps and overlapped tiles.

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Properties of a JIM - arbitrarily shaped container, arbitrarily shaped tiles of textures.





- Properties of a JIM arbitrarily shaped container, arbitrarily shaped tiles of textures.
- Tiles packed arbitrarily and allows for gaps and overlaps of tiles.

Resulting JIM





 JIM approaches problem as an energy minimization problem, where the energy of a mosaic is a sum of mosaic-related energy terms.

- JIM approaches problem as an energy minimization problem, where the energy of a mosaic is a sum of mosaic-related energy terms.
- Claim that JIM generalizes mosaics by creating a generalized framework.

 "Energy-based framework for the mosaicing problem which generalizes on known algorithms"

Question: is this claim true or proven true by the paper?

Tile Configuration: subset of input tiles with repetition, along with their associated transformations (orientation, translation, deformation).

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JIM: a tile configuration that minimizes energy E.

 $\mathbf{E} = \mathbf{W}_{\mathbf{C}} \mathbf{E}_{\mathbf{C}} + \mathbf{W}_{\mathbf{G}} \mathbf{E}_{\mathbf{G}} + \mathbf{W}_{\mathbf{O}} \mathbf{E}_{\mathbf{O}} + \mathbf{W}_{\mathbf{D}} \mathbf{E}_{\mathbf{D}}$ colour gap overlap deformation

JIM: Energy Framework

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JIM: a tile configuration that minimizes energy E.

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colour gap overlap deformation

• How to produce photomosaic or decorative mosaic?

JIM: Energy Framework $E = W_C E_C + W_G E_G + W_0 E_0 + W_D E_D$ colour gap overlap deformation

- The energy of a tile configuration is the sum of each weighted energy term.
- Each term is the sum of the energy term measured for each tile in the configuration.

JIM: Energy Framework $E = W_C E_C + W_G E_G + W_0 E_0 + W_D E_D$ colour gap overlap deformation

- Terms can be added or removed (flexible and scalable framework).
- Terms can be measured with different metrics.

JIM: Energy Terms Evaluation $E = W_{C} E_{C} + W_{G} E_{G} + W_{O} E_{O} + W_{D} E_{D}$ colour gap overlap deformation

Colour: random locations on each tile, L2 differences.

JIM: Energy Terms Evaluation $E = W_{C} E_{C} + W_{G} E_{G} + W_{O} E_{O} + W_{D} E_{D}$ colour gap overlap deformation

- Colour: random locations on each tile, L2 differences.
- Gap and Overlap: "spring energy formulation".
 - Use the boundary shapes of the tiles and the container to determine the signed distance between each tile and the nearest tile or container edge.

JIM: Energy Terms Evaluation $E = W_{C} E_{C} + W_{G} E_{G} + W_{O} E_{O} + W_{D} E_{D}$ colour gap overlap deformation

- Colour: random locations on each tile, L2 differences.
- Gap and Overlap: "spring energy formulation".
 - Use the boundary shapes of the tiles and the container to determine the signed distance between each tile and the nearest tile or container edge.
- Deformation: difference between original tile shape and deformed tile shape.

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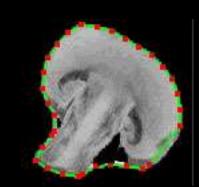
JIM: Preparation of Input

- JIM works on arbitrarily shaped containers and tiles.
 - The container and tile shapes are determined and represented using Active Contours.
- Also, active contours are used to segment a source image into a set of arbitrarily shaped containers.

JIM: Shapes by Active Contours

 Active Contours are a classic shape model described by Kass, Witkin and Terzopoulos, 'Snakes: Active Contour Models' (1987).

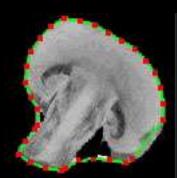
Contour = vertices (control points) connected by edges.



Source: Philip Lau and Katia Hristo

JIM: Shapes by Active Contours

- Contour is controlled by minimizing an energy function of properties: snake continuity, snake curvature and image gradient.
- We use them to find image boundary.
- Also used to deform image boundaries.



Source: Philip Lau and Katia Hristo

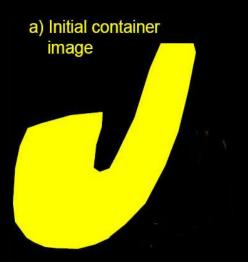
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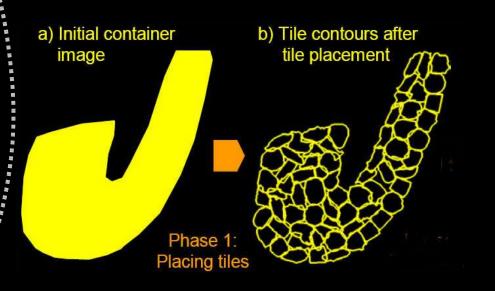


I. Prepare input tiles, segment source image and treat each container separately.





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- 2. Pack the container with tiles from tile set.





Best first search for creating the packing.

 1. Find a suitable position in container – this gives a container region.

- 2. Search for tile to use and register tile to the determined container region.
- Subtract tile shape from the container to get new container shape to pack.



Best first search for creating the packing.

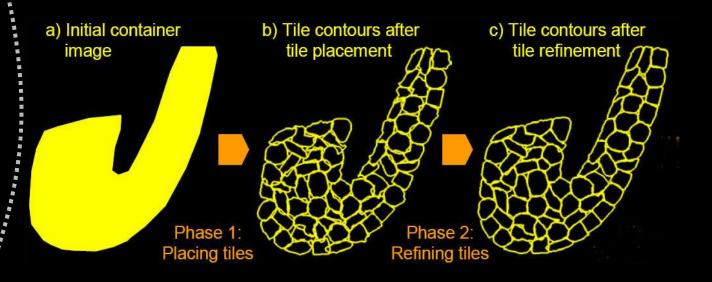
 1. Find a suitable position in container – this gives a container region.

- 2. Search for tile to use and register tile to the determined container region.
- Subtract tile shape from the container to get new container shape to pack.

If can't find a tile to finish filling a container, backtrack to last configuration with minimal energy.



- I. Prepare input tiles, segment source image and treat each container separately.
- 2. Pack the container with tiles from tile set.
- 3. Refine the packing by deforming the tiles.





• **Refine the tile shapes.** Reduce gap or overlap.

 Use a set of active contours and minimize energy according to forces that:

- maintain contour original shape
- * repulse between two overlapping contours
- * attract two contours if they are separated by a gap.



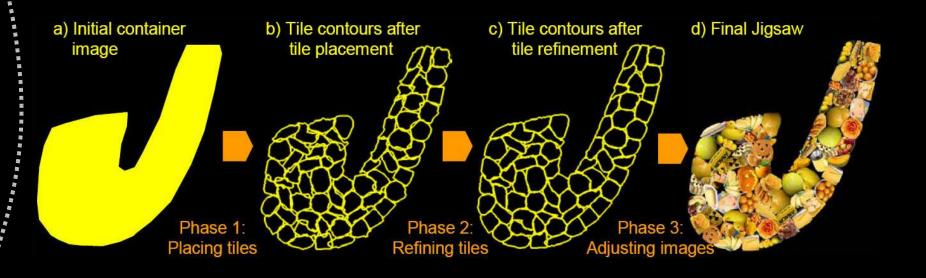
Refine the tile shapes. Reduce gap or overlap.

 Use a set of active contours and minimize energy according to forces that:

- maintain contour original shape
- * repulse between two overlapping contours
- * attract two contours if they are separated by a gap.
- This minimizes over all four energy terms, and must not increase energy of a configuration.



- I. Prepare input tiles, segment source image and treat each container separately.
- 2. Pack the container with tiles from tile set.
- 3. Refine the packing by deforming the tiles.







The algorithm:

O((V_{tile})(N_{tile})(V_{container})(N_{tilesInContainer})(1+b))

- Number of vertices per tile.
- Number of tiles.
- Number of vertices per container.
- Number of tiles in the container.
- Branching overhead for backtracking in search.

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- REDUCE: Branching overhead for backtracking in search.
- Want to place tiles so that it is easy to fill container shape at each iteration of algorithm (no protrusions and container shape is convex).



- REDUCE: Branching overhead for backtracking in search.
- Want to place tiles so that it is easy to fill container shape at each iteration of algorithm (no protrusions and container shape is convex).
 - Fill areas with least number of neighbours first. Use Centroidal Voronoi Diagram (CVD).
 - Add Lookahead energy term to energy formula that penalizes tiles that make container shape difficult to fill at next iteration.

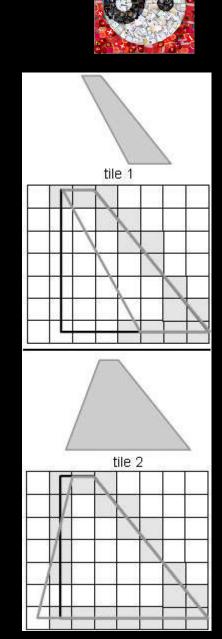


- REDUCE: Number of vertices representing container shape.
- At each iteration of the algorithm, the container shape changes due to the removal of the added tile.
- Results in jagged edges and container fragments.
 - If fragment is smaller than smallest tile, treat as a gap and remove from resulting container shape.

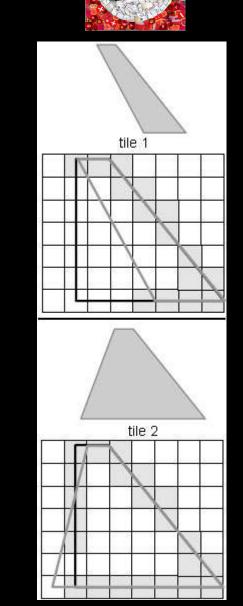


- REDUCE: Number of tiles to be searched.
- At each iteration of the algorithm must search all tiles to find the tile which best fits into the container region to be filled (the predetermined best location to be filled).
- Use Geometric Hashing so that the algorithm does not consider tiles that are bad fits for the container region.

- Geometric Hashing reduces number of tiles to search.
- Create grid of squares in plane.
 Each square corresponds to hash table entry.
- Place each tile and orientation over the grid and keep track of all tiles and their orientations that cross each square of the grid.



- Take boundary of container region to be filled and align ove grid.
- For every grid square crossed by container region, have a list of all tiles and orientations that also crossed that square.
 - Candidates for best fitting tile: the tiles that share the most crossed squares with the container region.

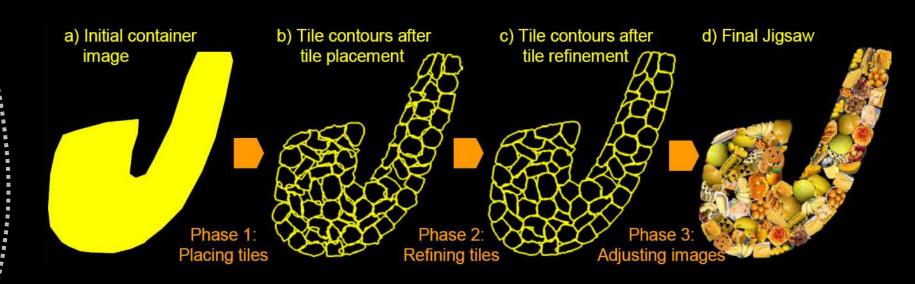


container

JIM: Mosaic Algorithm



So that's how they optimize the straightforward mosaic algorithm.

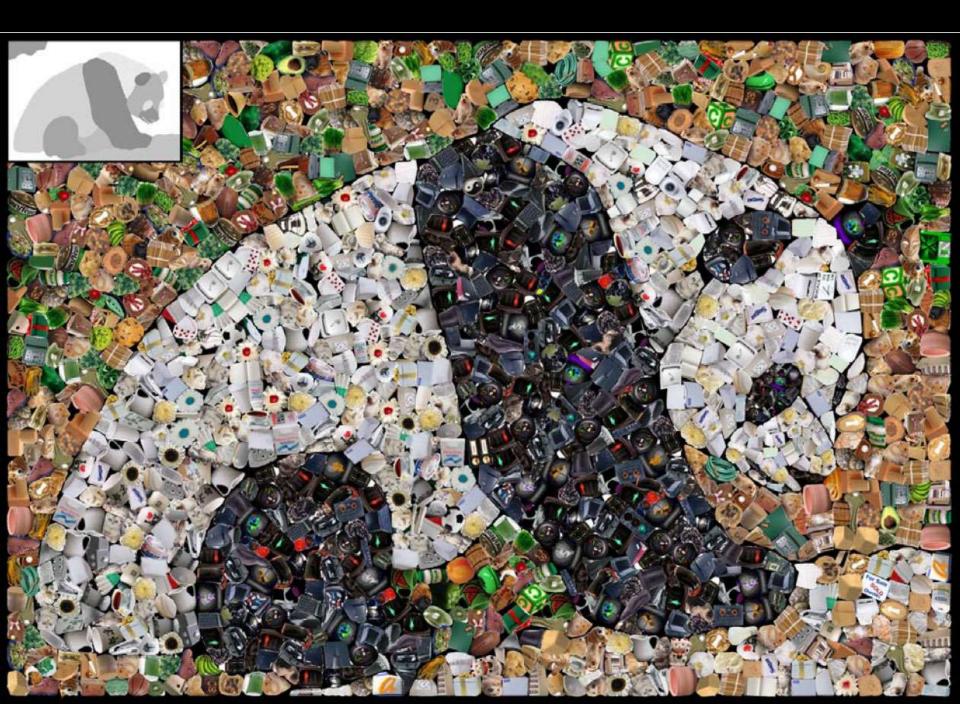


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JIM: Comments



- "Energy-based framework for the mosaicing problem which generalizes on known algorithms"
 - Is this true?
 - There are no examples of a JIM that reproduces a simulated decorative mosaic.
 - Styles seem intuitively different, especially with respect to the tile orientation.
 - The framework has little to do with the actual physical process of creating a mosaic.

JIM: Comments



"deforming them slightly to achieve a more visually-pleasing effect"

★ Again, subjective.

- * Does smooshing together really create a better mosaic?
- Tile deformation increases the computer-created look of JIM but does not make it look more like a mosaic.

References



- "Jigsaw Image Mosaics", Junhwan Kim and Fabio Pellacini, 2002.
- "Simulated Decorative Mosaics", Alejo Hausner, 2001.
- Photomosaics, Robert Silvers and Michael Hawley, 1997.
- "Snake: Active contour model", M. Kass, A. Witkin and D.Terzopoulos, Int. J. Computer Vision, 1987.
- Philip Lau and Katia Hristova, Student Project implementation of JIM http://www.ic.sunysb.edu/Stu/pwlau/

